## TECHNISCHE UNIVERSITÄT BERLIN Institut für Mathematik



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http://www3.math.tu-berlin.de/geometrie/Lehre/WS19/MP1/

WS 19/20

## Exercise Sheet 4 (12.11.19)

Due date: 19.11.19

- To get the Übungsschein (necessary condition for the oral exam) you need to collect 60% of the total sum of points in each half of the semester. Each exercise sheet has 20 points. The total number of sheets is 12-14.
- Please work in fixed groups of 2 or 3 students.
- Please justify each step of your computations. Results without any explanation are not accepted. Please write in a readable
  way. Unreadable handwriting will not be corrected. Feel free to write your answers either in English or in German.
- Please turn in your homework directly to me at the beginning of the Tutorial or leave it in my letter box (MA 701, Frau Jean Downes). No homework will be accepted after the deadline has passed.

Exercise 1 (5 pts)

Consider the discrete dynamical system defined in terms of iterations of the map  $\Phi: \mathbb{R} \setminus \{1/2\} \to \mathbb{R}$  defined by

$$\Phi: x \mapsto \frac{3x-2}{2x-1}.$$

- 1. Construct the n-th iteration of  $\Phi$ .
- 2. Show that  $\lim_{n\to\infty} \Phi^n(x) = 1$ , i.e., x = 1 is an attracting fixed point.
- 3. Is the point x = 1 asymptotically stable?

Exercise 2 (4 pts)

Consider the following ODE in  $\mathbb{R}^2$ :

$$\begin{cases} \dot{x}_1 = -x_1^3 - 2x_1x_2^2, \\ \dot{x}_2 = x_1^2x_2 - x_2^3. \end{cases}$$

Consider the fixed point (0,0).

1. Is the function

$$F(x_1, x_2) := x_1^2 + x_1^2 x_2^2$$

a Lyapunov function? What does it tell you about the stability of (0,0)?

2. Is the function

$$G(x_1, x_2) := x_1^2 + x_1^2 x_2^2 + x_2^4$$

a Lyapunov function? What does it tell you about the stability of (0,0)?

Turn over

Exercise 3 (3 pts)

Consider the following IVP in  $\mathbb{R}^2$ :

$$\begin{cases} \dot{x}_1 = x_1 - \alpha \sin x_2, \\ \dot{x}_2 = \alpha + x_1^4, \\ (x_1(0), x_2(0)) \in \mathbb{R}^2, \end{cases}$$

with  $\alpha > 0$ . Prove that the system cannot possess a periodic orbit.

Consider a Hamiltonian system of ODEs

$$\dot{x}_k = \frac{\partial H}{\partial p_k}, \qquad \dot{p}_k = -\frac{\partial H}{\partial x_k}, \qquad k = 1, \dots, n$$
 (1)

with some smooth function  $H(x, p) : \mathbb{R}^{2n} \to \mathbb{R}$ .

- 1. Show that the phase space volume is preserved.
- 2. With the help of the Poincaré recurrence theorem, prove that (1) does not have asymptotically stable fixed points.

Consider the following gradient system in  $\mathbb{R}^2$ :

$$\begin{cases} \dot{x} = \operatorname{grad}_{x} G(x), \\ x(0) \in \mathbb{R}^{2}, \end{cases}$$

where

$$G(x_1, x_2) = x_1^4 + 2x_1^2x_2^2 + x_2^4 - 4x_2^2 - 2.$$

- 1. Find the fixed points and study their stability.
- 2. Sketch the phase portrait.