

# Quantitative MRI using Modelbased CS

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CSA 2015: Compressed Sensing and its Applications



## **Outline of Talk**

#### PART I

- A General model-based CS Framework
- Practical model-based recovery algorithm

#### PART II

- Overview of Quantitative MRI & Magnetic Resonance Fingerprinting (MRF)
- A Compressed Sensing version of MRF



## Model based CS



# **Basics of Compressed sensing**

#### Signal Model:

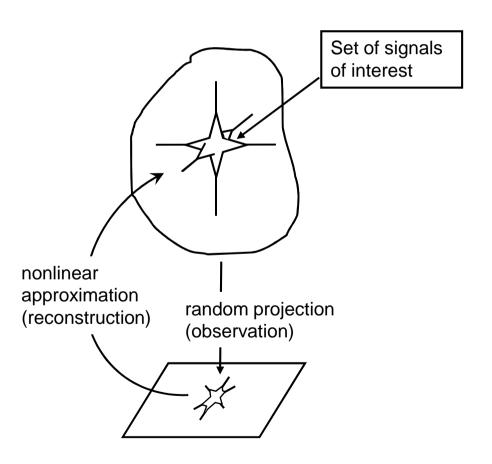
Compressed Sensing typically assumes a signal that is approximately k-sparse.

#### Encoder:

Use an encoder usually in the form of a random projection with e.g. RIP

#### Decoder:

Signal reconstruction is achieved by a nonlinear reconstruction to invert the linear projection operator on the signal set, e.g. L1, OMP, IHT, CoSaMP, AMP, etc...



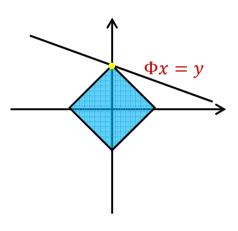


#### **Reconstruction Algorithms**

RIP enables us to replace  $l_0$  minimization with practical algorithms, e.g.:

**Relaxation**: replace  $l_0$  with  $l_1$ :

$$\hat{x} = \underset{x}{\operatorname{argmin}} \|x\|_1 \text{ subject to } \Phi x = y$$



Theorem [Candes 2008]:

RIP  $\delta_{2k} \leq \sqrt{2} - 1$   $\Longrightarrow$  guaranteed sparse recovery

Iterative Hard Thresholding (IHT): greedy gradient projection

$$x^{\{t+1\}} = P_{\Sigma_{k}} (x^{\{t\}} + \mu \Phi^{T} (y - \Phi x^{\{t\}}))$$

Theorem [Blumensath, D. 2010]:

RIP  $\delta_{2k} \leq 1/5 \implies$  guaranteed sparse recovery



# Compressed sensing for general signal models

#### Signal Model:

Replace k-sparse signal model with a general signal model, e.g low rank models, union of subspace, low dimensional manifolds, ...

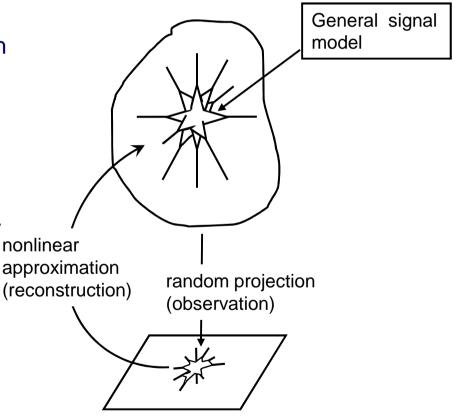
#### **Encoder:**

Information preserving, e.g. Modelbased RIP

#### Decoder:

Atomic norm minimization?

Model-based greedy methods?





## Model based CS set up

- Measurement matrix:  $\Phi \in \mathbb{R}^{m \times n}$
- a general (low dimensional) signal model:  $\Sigma \in \mathbb{R}^n$
- Assume a model based  $(\Sigma \Sigma)$  RIP

$$\|x\|_{2}^{2} \le \|\Phi z\|_{2}^{2} \le \beta \|z\|_{2}^{2}, \quad \forall z \in \Sigma - \Sigma$$

(can be satisfied with number of measurements:  $m \sim \dim(\Sigma)$ )

We now want a practical decoder...



# A Practical model-based CS Algorithm

IHT generalizes to a good (Instance Optimal) decoder for an arbitrary signal model  $\Sigma$  given an appropriate RIP [Blumensath 2011] :

$$x^{\{n+1\}} = P_{\Sigma}(x^{\{n\}} + \mu \Phi^{T}(y - \Phi x^{\{n\}}))$$

where  $P_{\Sigma}(x)$  is the orthogonal projection onto  $\Sigma$ 

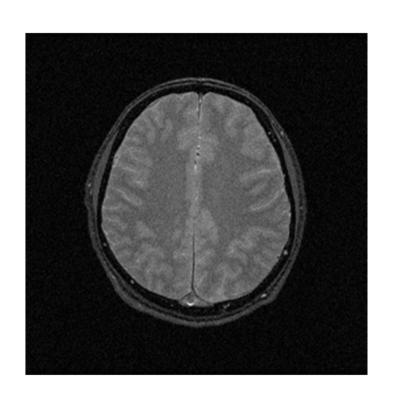
Practical only if  $P_{\Sigma}(x)$  can be implemented efficiently



# Compressive Quantitative MRI



#### **Structural MRI is Qualitative**



Standard MR images are not quantitative...

Like your digital camera [Tofts] they produce pretty pictures..

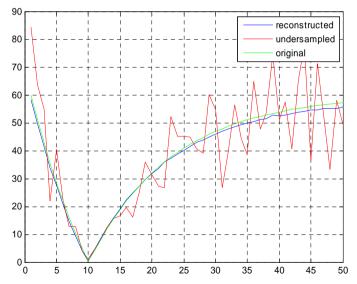
...But the process is quantitative and described by the Bloch equations (physical model):

$$\frac{\partial \mathbf{m}(t)}{\partial t} = \mathbf{m}(t) \times \gamma \mathbf{B}(t) - \begin{pmatrix} \mathbf{m}^{x}(t)/T2 \\ m^{y}(t)/T2 \\ (m^{z}(t) - \mathbf{m}_{eq})/T1 \end{pmatrix}$$



## **Quantitative MRI**

- Quantitative MRI, e.g. estimation proton density, T1, T2, etc.,
- Offers better physiological information and material discrimination etc.
- Traditional approach: acquire multiple scans and estimate the exponential relaxation from multiple data points...



T1 relaxation curve fitted for each voxel

Alternative new approach for full quantitative MRI:

"Magnetic Resonance Fingerprinting" [Ma et al, Nature, 2013]

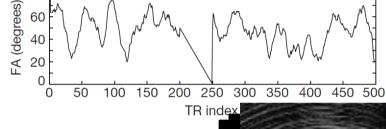


# Magnetic Resonance Fingerprinting

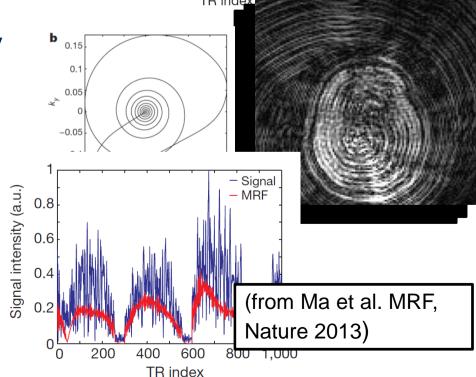
MRF aim: simultaneous acquisition of all MR parameters at

once!

 Excite magnetic spin in tissue with a sequence of random RF pulses



- Acquire image sequence from very undersampled in k-space (spiral trajectory) and back project.
- 3. Use dictionary, *D*, of predicted responses for different parameter values (fingerprints) is matched each voxel sequence





# Is MRF Compressed Sensing?

#### ... not quite:

- Fingerprints average aliasing ≠ Alias cancellation (c.f. filtered Back Projection vs Iterative recon)
- Spiral k-space sampling does not provide suitable data embedding



## Voxel-wise Bloch response model

We can think of the MRF dictionary D (Fingerprints) as a discretization of the Bloch magnetization response to **B**(t) with respect to the parameters T1, T2...

$$\frac{\partial \mathbf{m}(t)}{\partial t} = \mathbf{m}(t) \times \gamma \mathbf{B}(t) - \begin{pmatrix} \mathbf{m}^{x}(t)/T2 \\ m^{y}(t)/T2 \\ (m^{z}(t) - \mathbf{m}_{eq})/T1 \end{pmatrix}$$

- This essentially samples a manifold  $\mathcal{B} \in \mathbb{C}^L$  for L excitation pulses
- The proton density simply scales the response defining a cone R<sub>+</sub>B
- Full image sequence model is the N-product of this cone (N voxels):

$$X \in (\mathbb{R}_+ \mathcal{B})^N \subset \mathbb{C}^{N \times L}$$



## **Model Projection**

MRF reconstruction is "matched filter" with voxel sequence X<sub>{i,:}</sub>:

$$\hat{k}_i = \underset{k}{\operatorname{argmax}} \frac{\left| \left\langle D_k, X_{\{i,:\}} \right\rangle \right|}{\|D_k\|_2}$$

- T1<sub>i</sub> and T2<sub>i</sub> can be found using look up table.
- Proton density estimated as the magnitude of the correlation:

$$\hat{\rho}_i = \frac{\langle D_k, X_{\{i,:\}} \rangle}{\|D_k\|_2}$$

Our interpretation: this is an approximate projection onto  $\mathbb{R}_+\mathcal{B}$ 



### **Excitation Scheme**

- Random excitation sequences map parameter space into higher dimensional response space
- not directly part of "compressed sensing"... but still involves data embedding.
- However in order to get a RIP we require some form of persistence of excitation to continuously acquire new information.



#### Persistence of Excitation

We measure persistence of excitation through the following definition:

Definition: flatness. Let U be a collection of vectors  $\{u\} \in \mathbb{C}^L$ . We denote the flatness of U,  $\lambda(U)$  as:

$$\lambda(U) \coloneqq \max_{u \in U} \frac{\|u\|_{\infty}}{\|u\|_{2}}$$

from standard norm inequalities  $L^{-1/2} \le \lambda(U) \le 1$ 

We <u>assume</u> that random pulses give us chords of  $\mathbb{R}_+\mathcal{B}$ ,  $u \in \mathbb{R}_+\mathcal{B} - \mathbb{R}_+\mathcal{B}$  are sufficiently flat (empirically true)

(similar ideas in other areas of CS)

Theorem [D., Puy, Vandergh



# Subsampling & model-based RIP

Signal model has no spatial structure. Hence need to fully cover k-space

### Proposed k-space sampling:

Randomized Echo Planar Imaging (EPI): uniformly subsample multiple lines in k-space with random shift

We would prefer to have  $L \sim n$ 

to have  $L \sim p$ 

dom EPI

If excitation is "sufficiently persistent" then random EPI with factor p undersampling achieves RIP on voxer-wise model,  $(\mathbb{R}_+\mathcal{B})^N$  with a sequence length:  $L \sim \mathcal{O}(\delta^{-2}p^2\dim(\mathbb{R}_+\mathcal{B})\log(\frac{N}{s})$ 



# Bloch response recovery via Iterated Projection (BLIP)

- Incorporate Bloch dictionary into projected gradient algorithm:
  - (1) **Gradient**: calculate for each acquisition time, t:

$$X_{:,l}^{\{n+1/2\}} = X_{:,l}^{\{n\}} + \mu F^H P(l)^T \left( P(l) F X_{:,l}^{\{n\}} - Y_{:,l} \right)$$

– (2) **Projection**: for each voxel i find the atom in D most correlated to voxel sequence  $X_{i,:}^{\{n+1/2\}}$  then scale and replace.

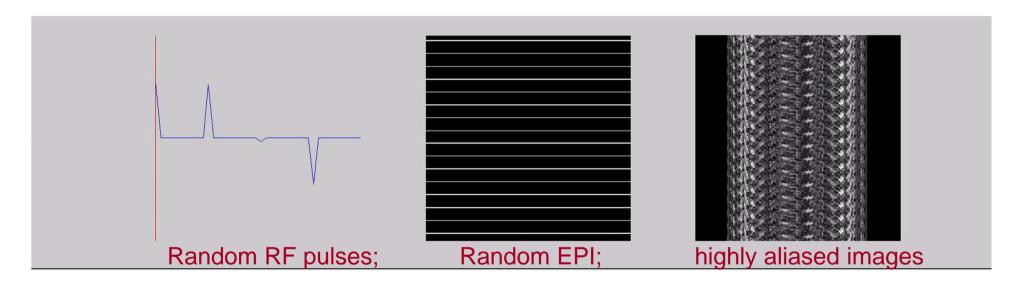
 $(\sim \mathcal{O}(L \log |\{D_k\}|))$  using a fast nearest neighbour search)

Finally use look up table to estimate ρ, T<sub>1</sub>, T<sub>2</sub>



# Back Projected Image Sequence

Proposed acquisition system:  $Y_{:,l} = P(l)FX_{:,l}$ 



Each image in the sequence is heavily aliased,... but encodes different spatial parameter information...

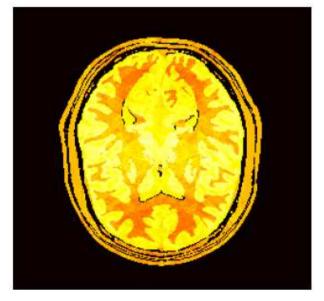
Together the image sequence can be restored with BLIP...

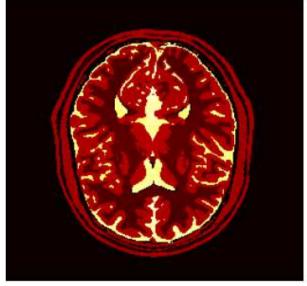


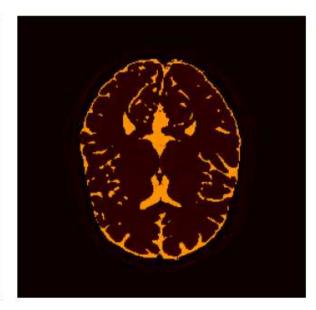
# Proton density, T1 and T2

Simulation Set up: Sequence length 200; random EPI sampling at 6.25% Nyq. uniform TR and i.i.d. random flip angles applied to MNI anatomical brain phantom

BLIP Density estimate BLIP T1 estimate BLIP T2 estimate





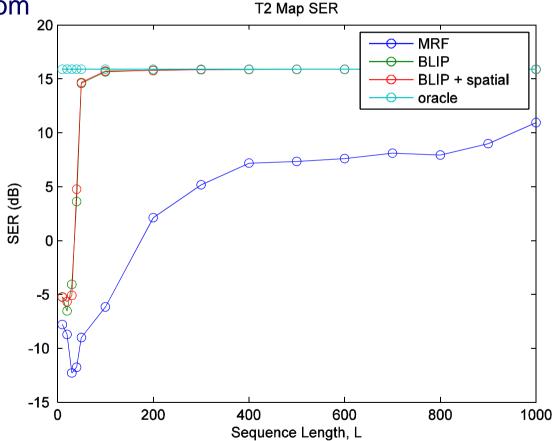




# Performance vs Sequence Length

Random EPI sampling at 6.25% Nyq. applied to the MNI anatomical





BLIP gives near perfect recovery from very short pulse sequences

significant improvement over the MRF matched filter reconstruction



### Conclusions

- Model based CS gives us a new tool for CS
- Initial go at applying it to fully quantitative MR Imaging
- Developed a practical algorithm based on gradient projection onto the Bloch equations model and Random EPI sampling (BLIP)

#### Next...

- We need to put it on the scanner. (in progress..)
- Deduce better excitation sequences & sampling patterns
- Evaluate model inaccuracies
- Determine how best to incorporate spatial regularization



## Questions