

# On Passive Discrete-Time Systems with a Normal Main Operator

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joint work with Yu. Arlinskiĭ and H. de Snoo

Linear discrete time-invariant systems  $\tau$  are determined by the system of equations

$$\begin{cases} h_{k+1} = Ah_k + B\xi_k, \\ \sigma_k = Ch_k + D\xi_k, \end{cases} \quad k = 0, 1, 2, \dots$$

where  $A$ ,  $B$ ,  $C$ , and  $D$  are bounded operators between the underlying separable Hilbert spaces  $\mathfrak{H}$ ,  $\mathfrak{M}$ , and  $\mathfrak{N}$ . The system  $\tau$  can be described by means of the block operator

$$T = \begin{pmatrix} D & C \\ B & A \end{pmatrix} : \begin{pmatrix} \mathfrak{M} \\ \mathfrak{H} \end{pmatrix} \rightarrow \begin{pmatrix} \mathfrak{N} \\ \mathfrak{H} \end{pmatrix}.$$

The system  $\tau$  is said to be passive if  $T$  is contractive. In the talk the emphasis will be on systems whose main operator  $A$  is in addition normal. In particular, a general unitary similarity result for such systems is derived by means of a famous approximation result known for complex functions. The talk is a part of some joint work with Yury Arlinskiĭ and Henk de Snoo on so-called passive quasi-selfadjoint systems.