



The MIP-Solving-Framework SCIP

Timo Berthold
Zuse Institut Berlin

DFG Research Center MATHEON
Mathematics for key technologies



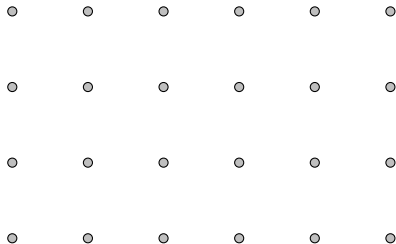
Berlin, 23.05.2007



Definition MIP

The optimization problem

is called a MIP
(mixed integer program).



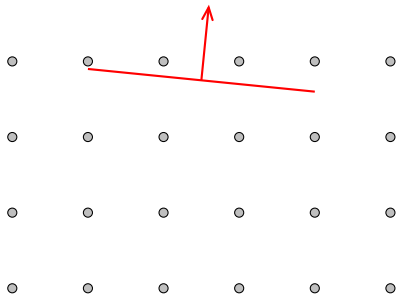


Definition MIP

The optimization problem

$$\min \quad c^T x$$

is called a MIP
(mixed integer program).



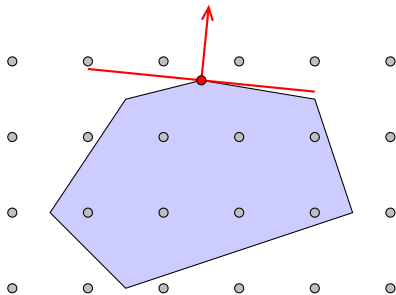


Definition MIP

The optimization problem

$$\begin{array}{ll} \min & c^T x \\ \text{s.t.} & Ax \leq b \end{array}$$

is called a MIP
(mixed integer program).



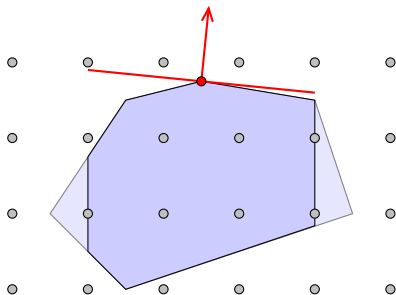


Definition MIP

The optimization problem

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Ax \leq b \\ & l \leq x \leq u \end{aligned}$$

is called a MIP
(mixed integer program).



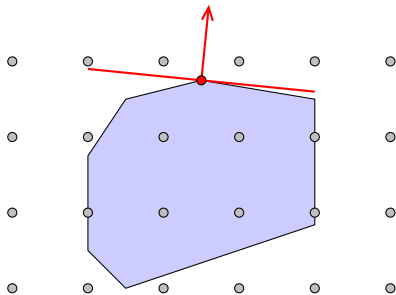


Definition MIP

The optimization problem

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Ax \leq b \\ & l \leq x \leq u \end{aligned}$$

is called a MIP
(mixed integer program).



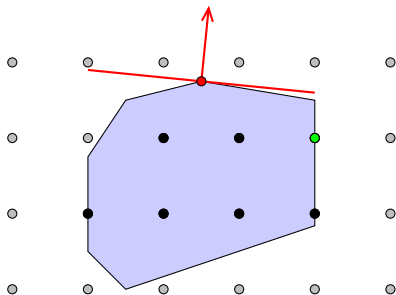


Definition MIP

The optimization problem

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Ax \leq b \\ & l \leq x \leq u \\ & x_j \in \mathbb{Z} \quad \forall j \in I \end{aligned}$$

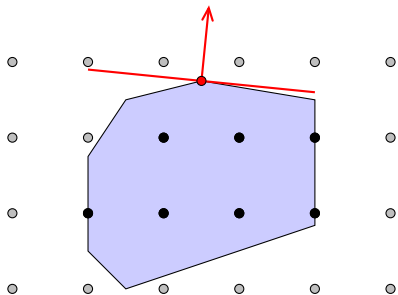
is called a MIP
(mixed integer program).





Exact methods

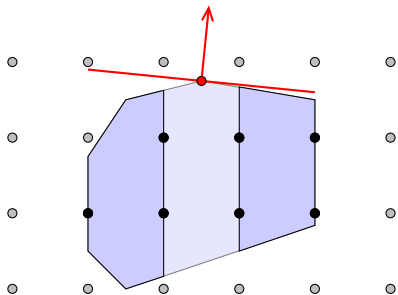
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

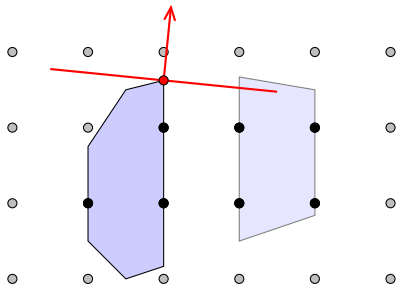
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

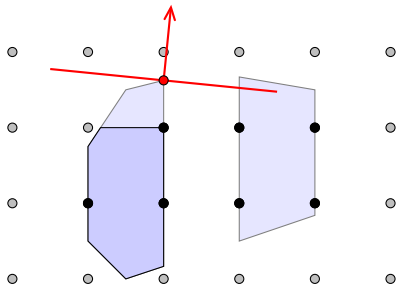
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

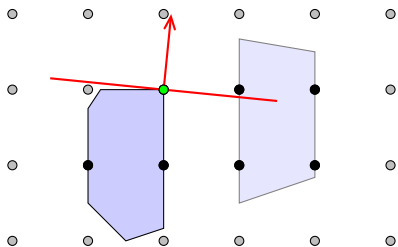
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

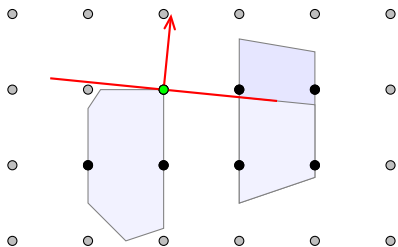
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

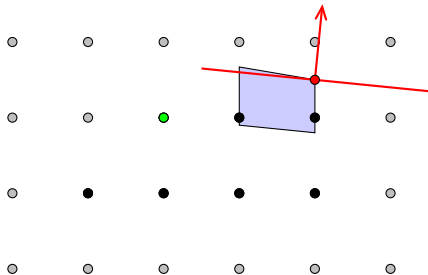
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

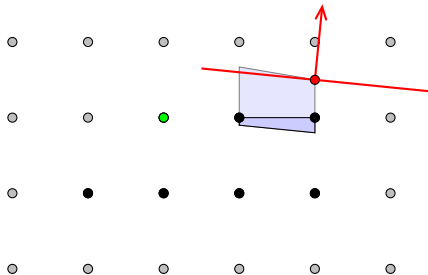
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

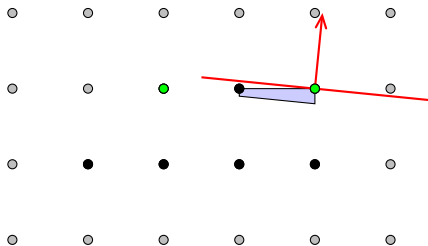
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

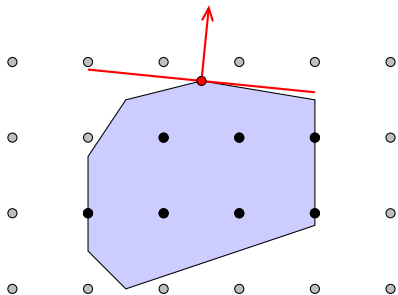
- ▷ **Branch-And-Bound**
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

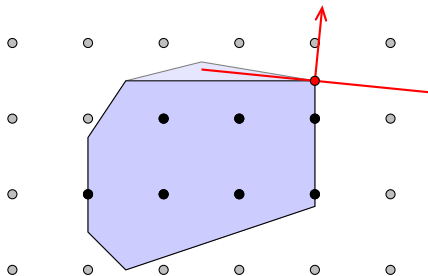
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

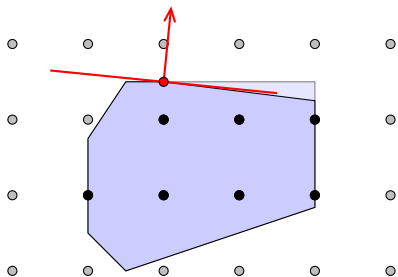
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

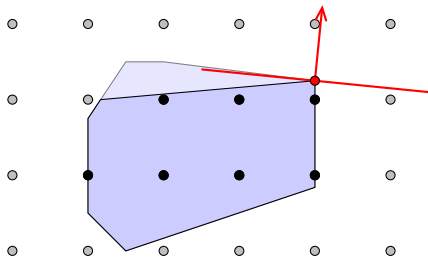
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

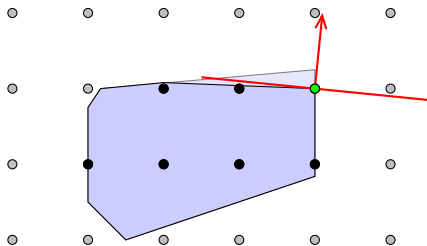
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

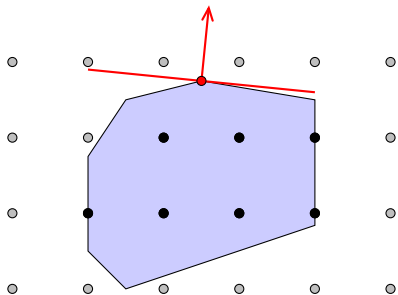
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

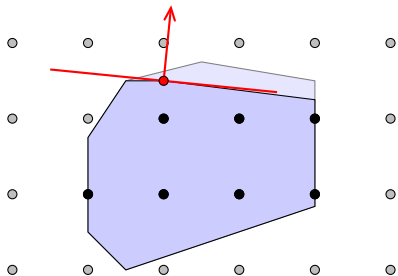
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ Combination: Branch-And-Cut





Exact methods

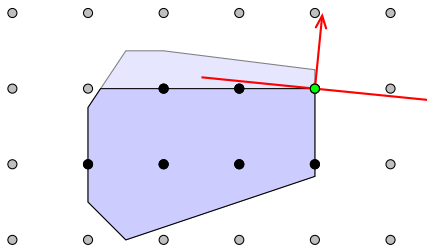
- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ **Combination: Branch-And-Cut**





Exact methods

- ▷ Branch-And-Bound
- ▷ Cutting planes
- ▷ **Combination: Branch-And-Cut**





Constraint Program (CP)

- ▷ General constraints
- ▷ Integer variables \Rightarrow (CIP)

Examples

How do we solve CPs?



Constraint Program (CP)

- ▷ General constraints
- ▷ Integer variables \Rightarrow (CIP)

Examples

- ▷ TSP as CP
- ▷ n-Queens

How do we solve CPs?



Constraint Program (CP)

- ▷ General constraints
- ▷ Integer variables \Rightarrow (CIP)

Examples

- ▷ TSP as CP
- ▷ n-Queens

How do we solve CPs?

- ▷ Branching:
 - ▶ Divide into subproblems, solve recursively
- ▷ Domain Propagation:
 - ▶ Reductions in variables' domains "propagate"
 - ▶ E.g. $x_1 + 2x_2 \geq 5$, $x_1 \leq 2 \Rightarrow x_2 \geq 2$



SCIP ← CP+MIP

- ▷ SCIP combines technologies
- ▷ Standalone-solver for MIP
 - ▶ A bundle of MIP-solving-components as default plugins
 - ▶ MIP-solver as fast as CPLEX 9.0
 - ▶ Underlying LP-solver: treated as blackbox
- ▷ Branch-Cut-And-Price-Framework for MIP and CIP
 - ▶ C++ wrapper classes for user plugins



SCIP ← CP+MIP

- ▷ SCIP combines technologies
- ▷ Standalone-solver for MIP
 - ▶ A bundle of MIP-solving-components as default plugins
 - ▶ MIP-solver as fast as CPLEX 9.0
 - ▶ Underlying LP-solver: treated as blackbox
- ▷ Branch-Cut-And-Price-Framework for MIP and CIP
 - ▶ C++ wrapper classes for user plugins



Key data

- ▷ Since October 2002
- ▷ Achterberg, Wolter, B. et al.
- ▷ Approx. 220.000 lines of C code
- ▷ Free für academic use
- ▷ Available at <http://scip.zib.de>
- ▷ July 2007: version 1.0



Key data

- ▷ Since October 2002
- ▷ Achterberg, Wolter, B. et al.
- ▷ Approx. 220.000 lines of C code
- ▷ Free für academic use
- ▷ Available at <http://scip.zib.de>
- ▷ July 2007: version 1.0 ... | hope so...



Types of plugins



Types of plugins

- ▷ **Presolver:** simplifies the problem in advance, strengthens structure



Types of plugins

- ▷ **Presolver:** simplifies the problem in advance, strengthens structure
- ▷ **Node selection:** which subproblem should be regarded next?



Types of plugins

- ▷ **Presolver:** simplifies the problem in advance, strengthens structure
- ▷ **Node selection:** which subproblem should be regarded next?
- ▷ **Branching rule:** how to divide the problem?



Types of plugins

- ▷ **Presolver:** simplifies the problem in advance, strengthens structure
- ▷ **Node selection:** which subproblem should be regarded next?
- ▷ **Branching rule:** how to divide the problem?
- ▷ **Separator:** adds cuts, improves dual bound



Types of plugins

- ▷ **Presolver**: simplifies the problem in advance, strengthens structure
- ▷ **Node selection**: which subproblem should be regarded next?
- ▷ **Branching rule**: how to divide the problem?
- ▷ **Separator**: adds cuts, improves dual bound
- ▷ **Constraint handler**: assures feasibility, strengthens formulation



Types of plugins

- ▷ **Presolver**: simplifies the problem in advance, strengthens structure
- ▷ **Node selection**: which subproblem should be regarded next?
- ▷ **Branching rule**: how to divide the problem?
- ▷ **Separator**: adds cuts, improves dual bound
- ▷ **Constraint handler**: assures feasibility, strengthens formulation
- ▷ **Conflict handler**: learns from infeasibility, improves dual bound



Types of plugins

- ▷ **Presolver:** simplifies the problem in advance, strengthens structure
- ▷ **Node selection:** which subproblem should be regarded next?
- ▷ **Branching rule:** how to divide the problem?
- ▷ **Separator:** adds cuts, improves dual bound
- ▷ **Constraint handler:** assures feasibility, strengthens formulation
- ▷ **Conflict handler:** learns from infeasibility, improves dual bound
- ▷ **Heuristic:** searches solutions, improves primal bound



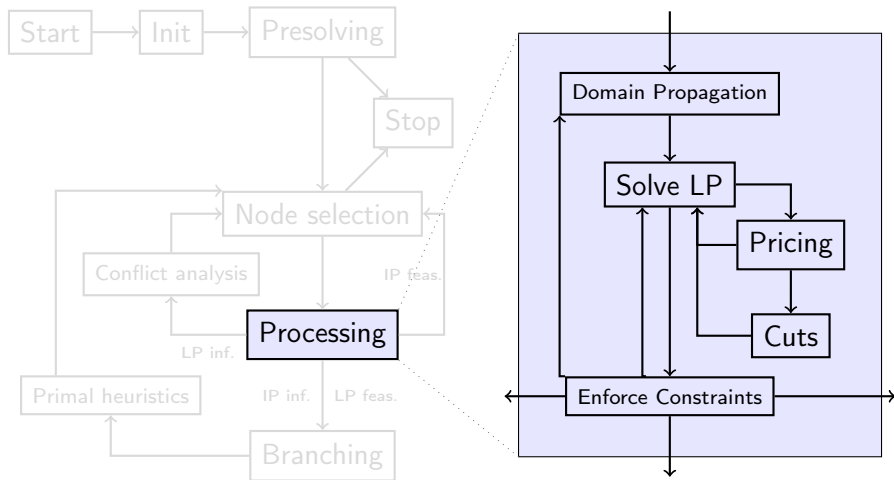
Types of plugins

- ▷ **Presolver**: simplifies the problem in advance, strengthens structure
- ▷ **Node selection**: which subproblem should be regarded next?
- ▷ **Branching rule**: how to divide the problem?
- ▷ **Separator**: adds cuts, improves dual bound
- ▷ **Constraint handler**: assures feasibility, strengthens formulation
- ▷ **Conflict handler**: learns from infeasibility, improves dual bound
- ▷ **Heuristic**: searches solutions, improves primal bound
- ▷ **Propagator**: simplifies problem, improves dual bound locally



Types of plugins

- ▷ **Presolver**: simplifies the problem in advance, strengthens structure
- ▷ **Node selection**: which subproblem should be regarded next?
- ▷ **Branching rule**: how to divide the problem?
- ▷ **Separator**: adds cuts, improves dual bound
- ▷ **Constraint handler**: assures feasibility, strengthens formulation
- ▷ **Conflict handler**: learns from infeasibility, improves dual bound
- ▷ **Heuristic**: searches solutions, improves primal bound
- ▷ **Propagator**: simplifies problem, improves dual bound locally
- ▷ **Pricer**: allows dynamic generation of variables





Default plugins

- ▷ 5 presolvers
- ▷ 5 node selection rules
- ▷ 14 constraint handlers
- ▷ 8 separators
- ▷ 8 branching rules
- ▷ 4 conflict handlers
- ▷ 2 propagators
- ▷ 23 primal heuristics

SCIP as a framework for a TSP-solver



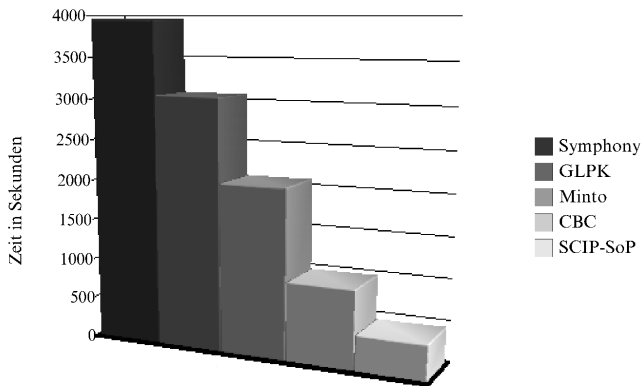
Default plugins

SCIP as a framework for a TSP-solver

main program:	196 lines
TSP file reader:	407 lines
graph structure:	80 lines
subtour constraint:	793 lines
Gomory-Hu algo.:	658 lines
FarInsert heuristic:	354 lines
2-Opt heuristic:	304 lines
<hr/>	
altogether:	2792 lines



Comparison With Other Free MIP-Solvers





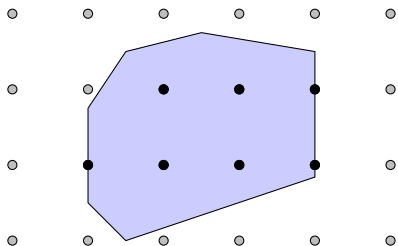
Characteristics

- ▷ Highest priority to feasibility
- ▷ Distinguish:
 - ▶ Start heuristics
 - ▶ Improvement heuristics
- ▷ Keep control of effort!
- ▷ Use available information



Used Information

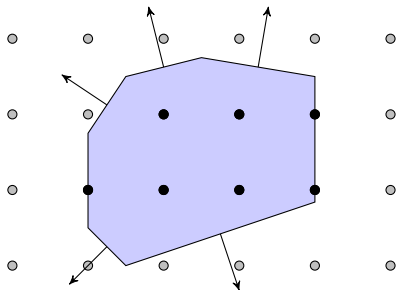
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

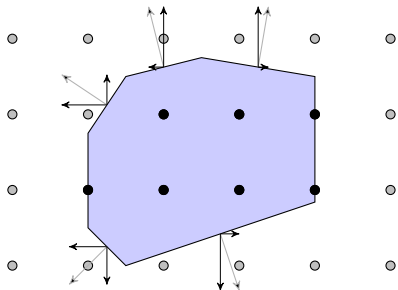
- ▷ **Variables' locking numbers:**
Potentially violated rows
- ▷ **Variables' pseudocosts:**
Average objective change
- ▷ **Special points:**
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

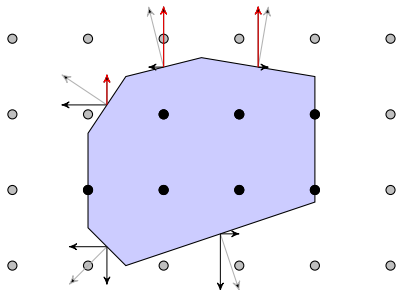
- ▷ **Variables' locking numbers:**
Potentially violated rows
- ▷ **Variables' pseudocosts:**
Average objective change
- ▷ **Special points:**
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





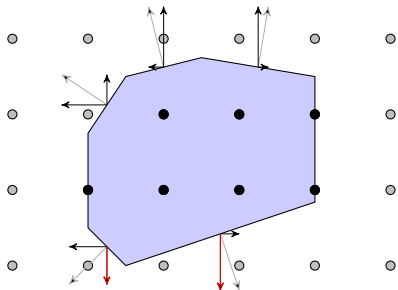
Used Information

- ▷ **Variables' locking numbers:**
Potentially violated rows
- ▷ **Variables' pseudocosts:**
Average objective change
- ▷ **Special points:**
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions



Used Information

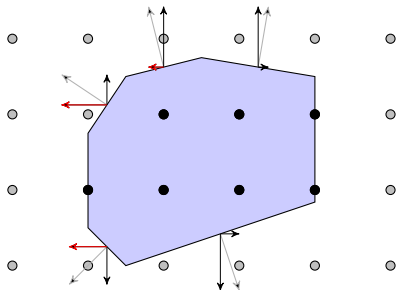
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

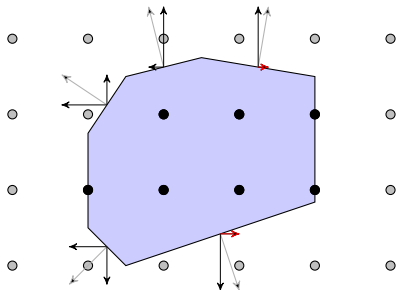
- ▷ **Variables' locking numbers:**
Potentially violated rows
- ▷ **Variables' pseudocosts:**
Average objective change
- ▷ **Special points:**
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

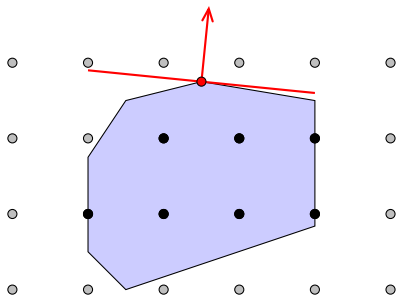
- ▷ **Variables' locking numbers:**
Potentially violated rows
- ▷ **Variables' pseudocosts:**
Average objective change
- ▷ **Special points:**
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

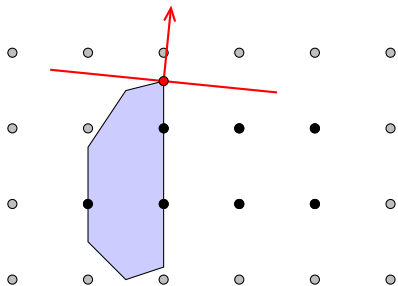
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

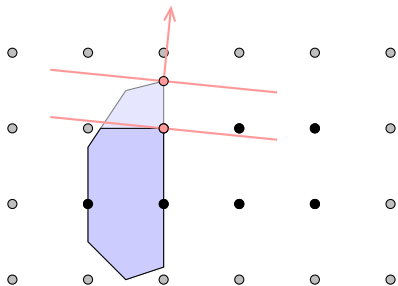
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

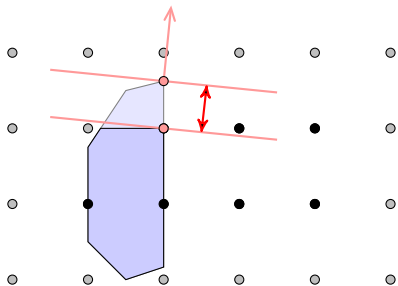
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

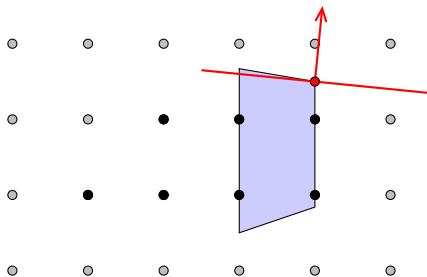
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

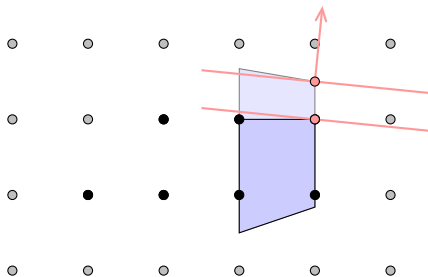
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

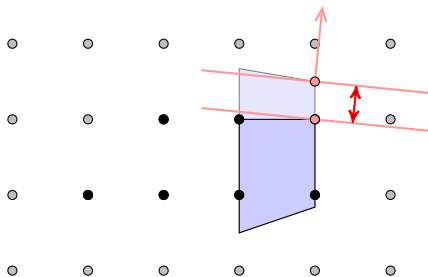
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

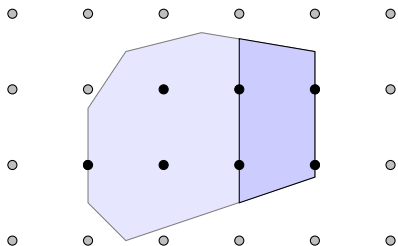
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

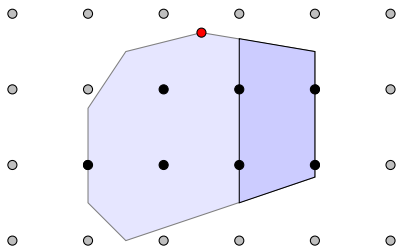
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

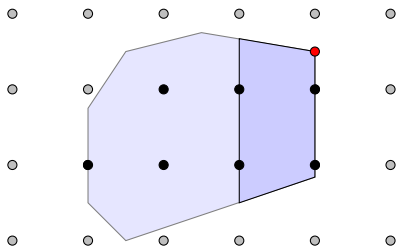
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

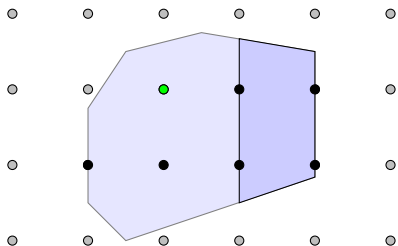
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ **Current LP optimum**
 - ▶ Current best solution
 - ▶ Other known solutions





Used Information

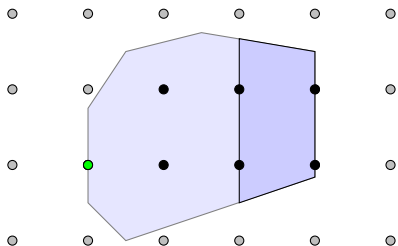
- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ **Current best solution**
 - ▶ Other known solutions





Used Information

- ▷ Variables' locking numbers:
Potentially violated rows
- ▷ Variables' pseudocosts:
Average objective change
- ▷ Special points:
 - ▶ LP optimum at root node
 - ▶ Current LP optimum
 - ▶ Current best solution
 - ▶ Other known solutions





Approaches

- ▷ **Rounding**
- ▷ **Diving**: simulate DFS in the Branch-And-Bound-tree using some special branching rule
- ▷ **Objective diving**: manipulate objective function
- ▷ **LNS**: solve some sub-MIP
- ▷ **Pivoting**: manipulate simplex algorithm



Approaches

- ▷ **Rounding**
- ▷ **Diving**: simulate DFS in the Branch-And-Bound-tree using some special branching rule
- ▷ **Objective diving**: manipulate objective function
- ▷ **LNS**: solve some sub-MIP
- ▷ **Pivoting**: manipulate simplex algorithm



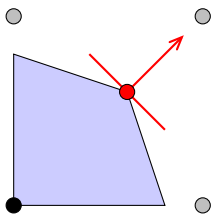
Implemented into SCIP

- ▷ 5 Rounding heuristics
- ▷ 8 Diving heuristics
- ▷ 3 Objective divers
- ▷ 4 LNS improvement heuristics



Ideas

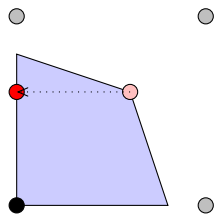
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

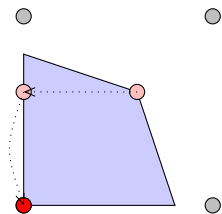
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

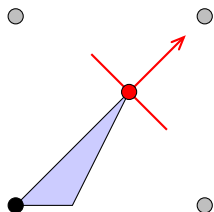
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

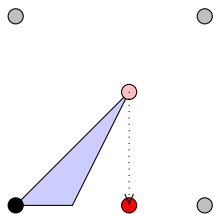
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

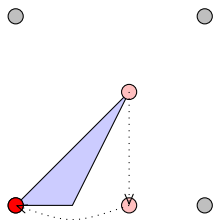
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

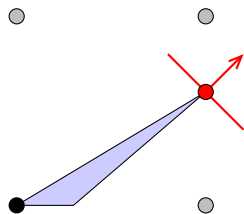
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

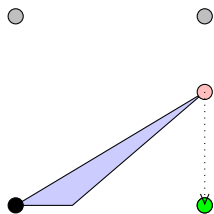
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

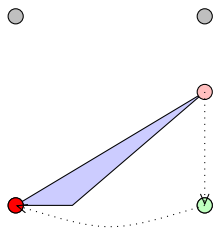
- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Ideas

- ▷ **Simple Rounding** always stays feasible,
- ▷ **Rounding** may violate constraints,
- ▷ **Shifting** may unfix integers.





Idea: iteratively solve the LP and round a variable

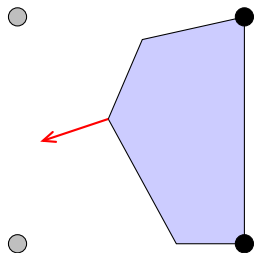
Applied branching rules

- ▷ **Fractional Diving:** lowest fractionality
- ▷ **Coefficient Diving:** lowest locking number
- ▷ **Linesearch Diving:** highest increase since root
- ▷ **Guided Diving:** lowest difference to best known solution
- ▷ **Pseudocost Diving:** highest ratio of pseudocosts
- ▷ **Vectorlength Diving:** lowest ratio of objective change and number of rows containing the variable



Algorithm

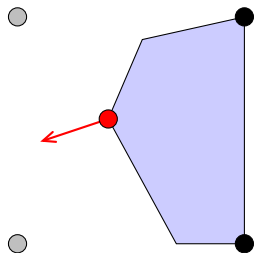
1. Solve LP;
2. Round LP optimum;
3. If feasible:
 4. Stop!
5. Else:
 6. Change Objective;
 7. Go to 1;





Algorithm

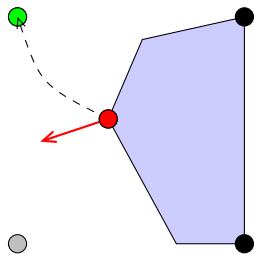
1. **Solve LP;**
2. Round LP optimum;
3. If feasible:
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

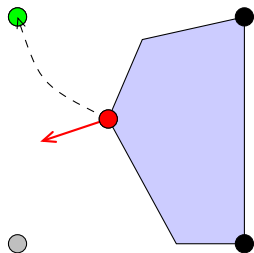
1. Solve LP;
2. Round LP optimum;
3. If feasible:
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

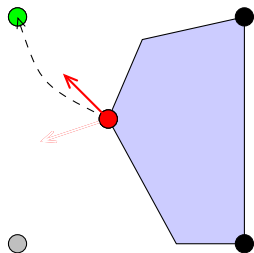
1. Solve LP;
2. Round LP optimum;
3. **If feasible:**
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

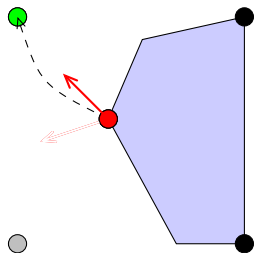
1. Solve LP;
2. Round LP optimum;
3. If feasible:
 4. Stop!
5. Else:
 6. **Change Objective;**
 7. Go to 1;





Algorithm

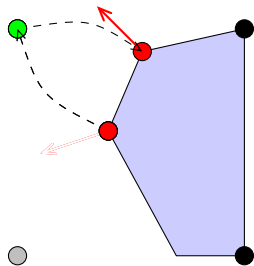
1. Solve LP;
2. Round LP optimum;
3. If feasible:
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

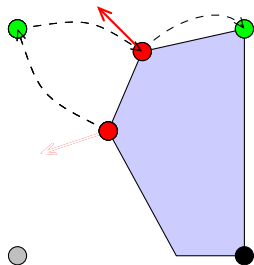
1. **Solve LP;**
2. Round LP optimum;
3. If feasible:
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

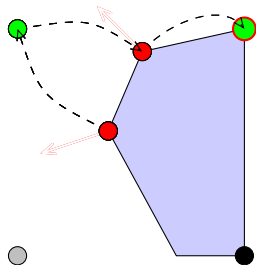
1. Solve LP;
2. **Round LP optimum;**
3. If feasible:
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

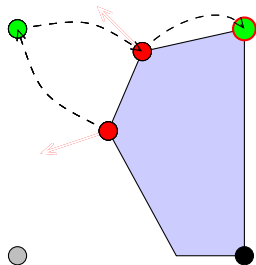
1. Solve LP;
2. Round LP optimum;
3. **If feasible:**
4. Stop!
5. Else:
6. Change Objective;
7. Go to 1;





Algorithm

1. Solve LP;
2. Round LP optimum;
3. If feasible:
4. **Stop!**
5. Else:
6. Change Objective;
7. Go to 1;





Improvements

- ▷ Objective $c^T x$ regarded at each step
- ▷ Algorithm able to resolve from cycling
- ▷ Quality of solutions much better



Improvements

- ▷ Objective $c^T x$ regarded at each step
- ▷ Algorithm able to resolve from cycling
- ▷ Quality of solutions much better

Results

- ▷ Finds a solution for 74% of the test instances
- ▷ On average 5.5 seconds running time
- ▷ Optimality gap decreased from 107% to 38%



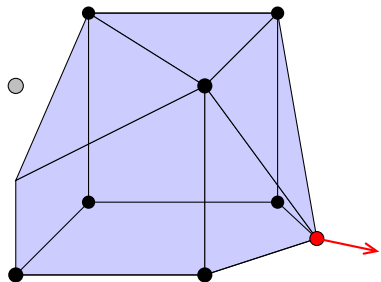
Algorithm

1. $\bar{x} \leftarrow$ LP optimum;
2. Fix all integral variables:
 $x_i := \bar{x}_i \quad \forall i : \bar{x}_i \in \mathbb{Z};$
3. Reduce domain of fractional variables:
 $x_i \in \{\lfloor \bar{x}_i \rfloor; \lceil \bar{x}_i \rceil\};$
4. Solve the resulting sub-MIP



Algorithm

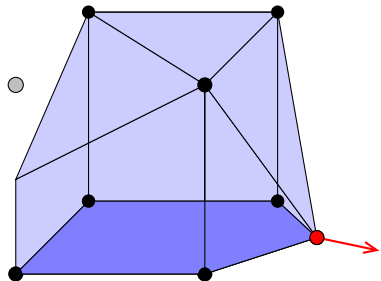
1. $\bar{x} \leftarrow$ LP optimum;
2. Fix all integral variables:
 $x_i := \bar{x}_i \quad \forall i : \bar{x}_i \in \mathbb{Z};$
3. Reduce domain of fractional variables:
 $x_i \in \{\lfloor \bar{x}_i \rfloor; \lceil \bar{x}_i \rceil\};$
4. Solve the resulting sub-MIP





Algorithm

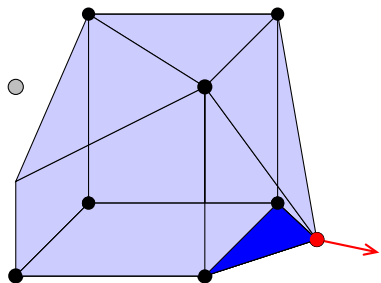
1. $\bar{x} \leftarrow$ LP optimum;
2. **Fix all integral variables:**
 $x_i := \bar{x}_i \quad \forall i : \bar{x}_i \in \mathbb{Z};$
3. Reduce domain of fractional variables:
 $x_i \in \{\lfloor \bar{x}_i \rfloor; \lceil \bar{x}_i \rceil\};$
4. Solve the resulting sub-MIP





Algorithm

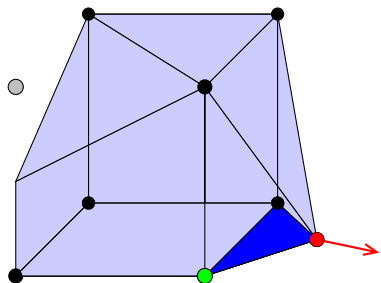
1. $\bar{x} \leftarrow$ LP optimum;
2. Fix all integral variables:
 $x_i := \bar{x}_i \quad \forall i : \bar{x}_i \in \mathbb{Z};$
3. Reduce domain of fractional variables:
 $x_i \in \{ \lfloor \bar{x}_i \rfloor; \lceil \bar{x}_i \rceil \};$
4. Solve the resulting sub-MIP





Algorithm

1. $\bar{x} \leftarrow$ LP optimum;
2. Fix all integral variables:
 $x_i := \bar{x}_i \quad \forall i : \bar{x}_i \in \mathbb{Z};$
3. Reduce domain of fractional variables:
 $x_i \in \{\lfloor \bar{x}_i \rfloor; \lceil \bar{x}_i \rceil\};$
4. **Solve the resulting sub-MIP**





Observations

- ▷ Solutions found by Rens are roundings of \bar{x}
- ▷ Yields best possible rounding
- ▷ Yields certificate, if no rounding exists

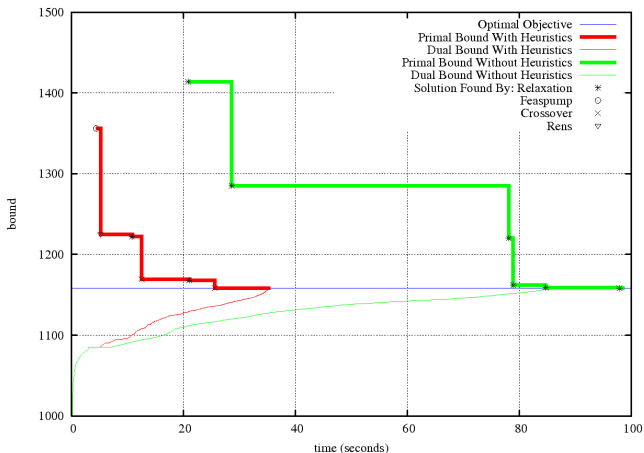


Observations

- ▷ Solutions found by Rens are roundings of \bar{x}
- ▷ Yields best possible rounding
- ▷ Yields certificate, if no rounding exists

Results

- ▷ Approx. $\frac{2}{3}$ of the test instances are roundable
- ▷ Rens finds optimum for 20%!
- ▷ Dominates all other rounding heuristics



Instanz aflow30a: performance of SCIP with and without heuristics



Results

- ▷ Coordination important
- ▷ Positive side effects
- ▷ Improvement of overall performance
- ▷ SCIP with heuristics twice as fast



The MIP-Solving-Framework SCIP

Timo Berthold

Zuse Institut Berlin

DFG Research Center MATHEON
Mathematics for key technologies



Berlin, 23.05.2007