

Series 8:

Task 1:

For the special case $\varepsilon = 3$ we see that via elementary unimodular transformations we have

$$\begin{aligned}
 & \begin{bmatrix} 1 & -1 & & \\ & \lambda & -1 & \\ & & \lambda & -1 \\ c_0 & c_1 & c_2 & c_3 \end{bmatrix} \xrightarrow{\cdot \lambda} \begin{bmatrix} 1 & -1 & & \\ & \lambda & -1 & \\ & & \lambda & -1 \\ c_0 & c_1 & c_2 + \lambda c_3 & c_3 \end{bmatrix} \\
 & \sim \begin{bmatrix} 1 & -1 & & \\ & 0 & -1 & \\ & & 0 & -1 \\ c_0 & c_1 + \lambda c_2 + \lambda^2 c_3 & c_2 + \lambda c_3 & c_3 \end{bmatrix} \sim \begin{bmatrix} 0 & -1 & & \\ & 0 & -1 & \\ & & 0 & -1 \\ p(\lambda) & c_1 + \lambda c_2 + \lambda^2 c_3 & c_2 + \lambda c_3 & c_3 \end{bmatrix} \\
 & \sim \begin{bmatrix} 0 & -1 & & \\ & 0 & -1 & \\ & & 0 & -1 \\ p(\lambda) & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} \overline{I_3} & \\ & p(\lambda) \end{bmatrix} .
 \end{aligned}$$

In the same way we obtain for the general case that there exist unimodular S, T such that

$$S(\lambda) \begin{bmatrix} \mathcal{L}_\varepsilon(\lambda) \\ C \end{bmatrix} T(\lambda) = \begin{bmatrix} I_\varepsilon \\ p(\lambda) \end{bmatrix}$$

$$\Rightarrow \mathcal{Z}\left(\begin{bmatrix} \mathcal{L}_\varepsilon(\lambda) \\ C \end{bmatrix}\right) = \mathcal{Z}\left(\begin{bmatrix} I_\varepsilon \\ p(\lambda) \end{bmatrix}\right) = \mathcal{Z}(p) \quad \text{and also}$$

$$\begin{aligned} \text{rank}_{\mathbb{C}(\lambda)} \begin{bmatrix} \mathcal{L}_\varepsilon(\lambda) \\ C \end{bmatrix} &= \text{rank}_{\mathbb{C}(\lambda)} \begin{bmatrix} I_\varepsilon \\ p(\lambda) \end{bmatrix} \\ &= \varepsilon + \text{rank}_{\mathbb{C}(\lambda)} p(\lambda) = \text{rank}_{\mathbb{C}(\lambda)} \mathcal{L}_\varepsilon(\lambda) + \text{rank}_{\mathbb{C}(\lambda)} p(\lambda) \end{aligned}$$

Task 2:

(a) We have

$$\begin{aligned} &\underbrace{\begin{bmatrix} I & | & BC_2^{-1} \\ 0 & | & I \end{bmatrix}}_{=: S_1} \underbrace{\begin{bmatrix} \lambda I - A & -B \\ C_1 & C_2 \end{bmatrix}}_{=: P(\lambda)} \underbrace{\begin{bmatrix} I & | \\ -C_2^{-1}C_1 & | & I \end{bmatrix}}_{=: T_1} \\ &= \begin{bmatrix} I & BC_2^{-1} \\ I & \end{bmatrix} \begin{bmatrix} \lambda I - A + BC_2^{-1}C_1 & -B \\ 0 & C_2 \end{bmatrix} \\ &= \begin{bmatrix} \lambda I - A + BC_2^{-1}C_1 & 0 \\ 0 & C_2 \end{bmatrix} =: \tilde{P}(\lambda) \end{aligned}$$

Since by Series 3, Task 9 matrix polynomials of the form $(\lambda I - \dots)$ are invertible and also C_2 is invertible we conclude that $\tilde{P}(\lambda)$ and thus also

$$P(\lambda) = S_1^{-1} \tilde{P}(\lambda) T_1^{-1} \quad \text{is invertible.}$$

(b) We have

$$m \underset{\substack{\uparrow \\ \text{rank smaller than number of rows}}}{\geq} \text{rank} [C_1, C_2] \geq \text{rank } C_2 = m$$

$$\Rightarrow m = \text{rank } C_2$$

$$\Rightarrow \text{rank}_{\mathbb{C}(x)} \underbrace{\begin{bmatrix} \lambda I - A & -B \\ C_1 & C_2 \end{bmatrix}}_{\substack{(2) \\ = n+m}} = \underbrace{\text{rank}_{\mathbb{C}(x)} [\lambda I - A, -B]}_{\substack{\text{S.3.7.9} \\ = n}}$$

$$= n+m - n = \text{rank } C_2.$$

(c) Choose $A = [1]$, $B = [1]$, $C_1 = [1]$, $C_2 = [0]$

$$\Rightarrow \text{rank}_{\mathbb{C}(x)} P(x) = \text{rank}_{\mathbb{C}(x)} \begin{bmatrix} \lambda - 1 & -1 \\ 1 & 0 \end{bmatrix} = 2$$

$$\text{rank}_{\mathbb{C}(x)} [\lambda - 1, -1] = 1$$

$$\text{rank} [1, 0] = 1$$

$\Rightarrow [1, 0]$ is regular controller for $\mathcal{L}([\lambda - 1, -1])$.

Task 3:

$$\mathcal{L} \left(\begin{bmatrix} P & 0 \\ -R & I \end{bmatrix} \right) = \left\{ (z_1, z_2) \in \mathcal{L}_\infty^{q+r} \mid \begin{array}{l} P \left(\frac{d}{dt} \right) z_1 = 0 \\ -R \left(\frac{d}{dt} \right) z_1 + z_2 = 0 \end{array} \right\}$$

$$= \left\{ (z_1, z_2) \mid z_1 \in \mathcal{L}(P), z_2 = R \left(\frac{d}{dt} \right) z_1 \right\}$$

$$= \left\{ (z_1, R \left(\frac{d}{dt} \right) z_1) \mid z_1 \in \mathcal{L}(P) \right\} = \begin{bmatrix} I \\ R \left(\frac{d}{dt} \right) \end{bmatrix} \mathcal{L}(P).$$

Task 4: Use the notation $R := \begin{bmatrix} R_{11} & R_{12} \\ 0 & R_{22} \end{bmatrix}$.

(a) If R_{11} has full row rank over $\mathbb{C}(\lambda)$ there exists an $X \in \mathbb{C}(\lambda)^{q_1 \times p_1}$ such that $R_{11}(\lambda) X(\lambda) = \underline{I}$. (cf. Series 2, Task 1)

$$\begin{aligned} \Rightarrow \text{rank}_{\mathbb{C}(\lambda)} R &= \text{rank}_{\mathbb{C}(\lambda)} \begin{bmatrix} R_{11} & R_{12} \\ 0 & R_{22} \end{bmatrix} \begin{bmatrix} \underline{I} & -XR_{12} \\ 0 & \underline{I} \end{bmatrix} \\ &= \text{rank}_{\mathbb{C}(\lambda)} \begin{bmatrix} R_{11} & 0 \\ 0 & R_{22} \end{bmatrix} = \text{rank}_{\mathbb{C}(\lambda)} R_{11} + \text{rank}_{\mathbb{C}(\lambda)} R_{22} \\ &= p_1 + q_2 \end{aligned}$$

To show (1):

" \leq ": Let $\lambda_0 \in \mathcal{Z}(R)$, with Lemma 1.9

$$\text{rank } R(\lambda_0) < \text{rank}_{\mathbb{C}(\lambda)} R = p_1 + q_2$$

Then $\lambda_0 \in \mathcal{Z}(R_{11})$ or, if this not the case, we have $\text{rank } R_{11}(\lambda_0) = p_1$

and thus there exists a $\tilde{X} \in \mathbb{C}^{q_1 \times p_1}$ such that $R_{11}(\lambda_0) \tilde{X} = \underline{I}$.

$$\begin{aligned} \Rightarrow \text{rank } R(\lambda_0) &= \text{rank} \begin{bmatrix} R_{11}(\lambda_0) & R_{12}(\lambda_0) \\ 0 & R_{22}(\lambda_0) \end{bmatrix} \begin{bmatrix} \underline{I} & -\tilde{X}R_{12}(\lambda_0) \\ 0 & \underline{I} \end{bmatrix} \\ &= \text{rank} \begin{bmatrix} R_{11}(\lambda_0) & 0 \\ 0 & R_{22}(\lambda_0) \end{bmatrix} = p_1 + \text{rank } R_{22}(\lambda_0) \end{aligned}$$

$$\Rightarrow p_1 + q_2 > \text{rank } R(\lambda_0) = p_1 + \text{rank } R_{22}(\lambda_0)$$

$$\Rightarrow q_2 > \text{rank } R_{22}(\lambda_0) \Rightarrow \lambda_0 \in \mathcal{Z}(R_{22}).$$

" \supseteq ": If $\lambda_0 \in \mathcal{Z}(R_{11}) / \mathcal{Z}(R_{22})$ then
 $\text{rank } R_{22}(\lambda_0) = q_2$ and as before we get

$$\begin{aligned} \text{rank } R(\lambda_0) &= \text{rank } R_{11}(\lambda_0) + q_2 < p_1 + q_2 \\ &= \text{rank}_{\text{crs}} R \stackrel{\text{Lem. 1.9.}}{\Rightarrow} \lambda_0 \in \mathcal{Z}(R) \end{aligned}$$

If $\lambda_0 \in \mathcal{Z}(R_{22}) / \mathcal{Z}(R_{11})$ an analogous argument implies.

It remains the case when $\lambda_0 \in \mathcal{Z}(R_{11}) \cap \mathcal{Z}(R_{22})$,
 i.e., when $\text{rank } R_{11}(\lambda_0) < p_1$, $\text{rank } R_{22}(\lambda_0) < q_2$.

$$\Rightarrow \text{rank } R(\lambda_0) \leq \text{rank} \begin{bmatrix} R_{11}(\lambda_0) & R_{12}(\lambda_0) \\ & R_{22}(\lambda_0) \end{bmatrix} + \text{rank } R_{22}(\lambda_0)$$

rank is smaller than number of rows $\leq p_1 + \text{rank } R_{22}(\lambda_0) < p_1 + q_2$

$$= \text{rank}_{\text{crs}} R.$$

$$\Rightarrow \lambda_0 \in \mathcal{Z}(R).$$

(b) Choose $R_{11}(\lambda) = \begin{bmatrix} \lambda & \\ & 0 \end{bmatrix}$, $R_{12}(\lambda) = \begin{bmatrix} 0 & 0 \\ \lambda-1 & 0 \end{bmatrix}$,

$$R_{22}(\lambda) = [0, \lambda] \Rightarrow R(\lambda) = \begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda-1 & 0 \\ 0 & 0 & \lambda \end{bmatrix}.$$

Task 5 ϵ Choose $C = [1, 0, \dots, 0]$.

Then (in the special case $\epsilon = 3$; the general case is analogous) we see that by applying elementary unimodular transformations from the left that

$$\mathcal{L} \left(\begin{bmatrix} \lambda^{-1} & & & \\ & \lambda^{-1} & & \\ & & \lambda^{-1} & \\ 1 & 0 & 0 & 0 \end{bmatrix} \right) = \mathcal{L} \left(\begin{bmatrix} 0 & -1 & & \\ & \lambda^{-1} & & \\ & & \lambda^{-1} & \\ 1 & & & \end{bmatrix} \right) = \mathcal{L} \left(\begin{bmatrix} -1 & & & \\ & 0 & -1 & \\ & & \lambda^{-1} & \\ 1 & & & \end{bmatrix} \right)$$

$$= \mathcal{L} \left(\begin{bmatrix} -1 & & \\ & -1 & \\ & & \lambda^{-1} \\ 1 & & & \end{bmatrix} \right) = \{0\}$$

S.S.T.S
 $\Rightarrow \begin{bmatrix} \lambda^{-1} & & \\ & \lambda^{-1} & \\ & & \lambda^{-1} \\ 1 & & & \end{bmatrix}$ is right prime $\Rightarrow \mathcal{Z} \left(\begin{bmatrix} \lambda^{-1} & & \\ & \lambda^{-1} & \\ & & \lambda^{-1} \\ 1 & & & \end{bmatrix} \right) = \emptyset$.

Task 6 ϵ

$$P(\lambda) = \left[\begin{array}{c|cc|cc} 0 & \lambda I - A & C & C & -B \\ \hline I & -C & 0 & 0 & \\ \hline L & 0 & -L & \lambda I - A & -B \\ \hline 0 & 0 & I & -C & 0 \end{array} \right]$$

Task 7^e

1.) If $\mathcal{L}(\lambda I - A, -B)$ is stabilizable then $\mathcal{Z}(\lambda I - A, -B) \subseteq \mathbb{C}_-$ and the Kronecker canonical form of

$$\lambda F + G = \lambda [I, 0] + [-A, -B]$$

only contains blocks of type \mathcal{L} and \mathcal{J} , where all zeros of the \mathcal{J} blocks are in the left half plane.

In the notation of Theorem 2, handout "Constant controllers..." this means that

$$n = p = \varepsilon + \rho \quad \text{and} \quad n + m = q = \varepsilon + \rho + s$$

$$\Rightarrow m = s$$

and thus there exists a regular, stabilizing controller

$$C = [C_1, C_2] \in \mathbb{C}^{s, n+m}$$

with

$$\text{rank} \begin{bmatrix} F \\ C \end{bmatrix} = \text{rank} \begin{bmatrix} I & 0 \\ C_1 & C_2 \end{bmatrix} = n + m$$

$\Rightarrow C_2$ is invertible

Setting $G := -C_2^{-1} C_1$ (as in Corollary 3.6)

this implies that

$$\mathcal{L} \left(\begin{bmatrix} \lambda I - A & -B \\ C_1 & C_2 \end{bmatrix} \right) = \mathcal{L} \left(\begin{bmatrix} \lambda I - A & -B \\ -G & I \end{bmatrix} \right)$$

is stable.

as in
Corollary 3.6
=>

$$\sigma(A + BG) \subseteq \mathbb{C}_-$$

2.) The assumption implies that

$$\mathbb{C}_- \supseteq \mathcal{Z}\left(\begin{bmatrix} \lambda I - A \\ -C \end{bmatrix}\right) = \mathcal{Z}\left(\begin{bmatrix} \lambda I - A^T & -C^T \end{bmatrix}\right)$$

=> $\mathcal{L}\left(\begin{bmatrix} \lambda I - A^T & -C^T \end{bmatrix}\right)$ is stabilizable

$$\stackrel{1.)}{\Rightarrow} \exists \tilde{G} \text{ s.t. } \sigma(A^T + C^T \tilde{G}) \subseteq \mathbb{C}_-$$

$$\Rightarrow \mathbb{C}_- \supseteq \sigma(A^T + C^T \tilde{G}) = \sigma\left(A + \underbrace{\tilde{G}^T C}_{=: L}\right).$$

3.) Combine 1.) & 2.) and use
Corollary 3.8.

Task 8: As in the proof of Theorem 2
from the handout we first see that for
the block of type $\mathcal{L}(2)$ we have

$$\mathcal{Z}\left(\begin{bmatrix} \lambda I - A \\ C_1 \end{bmatrix}\right) = \mathcal{Z}\left(\begin{bmatrix} \lambda & -1 \\ d & -1 \end{bmatrix}\right) = \mathcal{Z}\left(\begin{bmatrix} 0 & -1 \\ d-d & -1 \end{bmatrix}\right)$$

$$\text{choose } C_1 := [d \ -1]$$

$$= \mathcal{Z}\left(\begin{bmatrix} 0 & -1 \\ 1-d & -1 \end{bmatrix}\right)$$

$$= \{d\}$$

and thus we choose the controller

$$C := [C_1, 0]^{-T}$$

$$= [d, -1, 0, 0] \begin{bmatrix} 0 & L & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & R & R & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

$$= [0, L \cdot d, 0, -1].$$

Task 9e

1.) Let $\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \neq 0, \lambda \in \mathbb{C}$ be an eigenvector of $\begin{bmatrix} 0 & I \\ -K & 0 \end{bmatrix}$. $\Rightarrow \lambda \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} v_2 \\ -K v_1 \end{bmatrix}$

$$\Rightarrow \lambda v_1 = v_2 \quad \Rightarrow -K v_1 = \lambda v_2 = \lambda^2 v_1$$

$$\Rightarrow \lambda^2 \in \sigma(-K).$$

Since $-K$ is ~~pos~~ negative semi-definite this implies that

$$\lambda^2 \in \mathbb{R}_{\leq 0}$$

$\Rightarrow \lambda \in i\mathbb{R}$ is purely imaginary.

2.) In this case A has the form of 1.) with

$$K := \begin{bmatrix} k_1 + k_2 & -k_2 \\ -k_2 & k_2 \end{bmatrix}, \text{ and we}$$

only have to show that this K is positive semi-definite. This is the case if and only if

$$S^T \begin{bmatrix} k_1 + k_2 & -k_2 \\ k_2 & k_2 \end{bmatrix} \underbrace{\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}}_{=S}$$

$$= \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} k_1 & -k_2 \\ k_2 & k_2 \end{bmatrix} = \begin{bmatrix} k_1 & \\ & k_2 \end{bmatrix} \text{ is positive semi-definite.}$$

The latter, however is the case, since $k_1, k_2 \geq 0$.

3.) $L_1^e = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ works;

$L_2^e = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ does not work.