

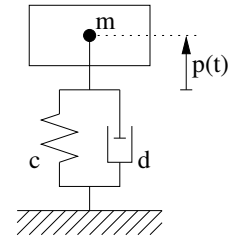
Example 1.2.6 (Linear spring-damper system)

Consider a linear spring-damper system with its model equation

$$\dot{y} = \begin{bmatrix} 0 & 1 \\ -c/m & -d/m \end{bmatrix} y$$

on $t \in [t_0, t_f] = [0, 10]$. We choose the mass $m = 1$, the damping $d = 1$ and the stiffness c varying in $[0, 100]$. The initial condition is

$$y(t_0) = y_0 = \begin{bmatrix} p_0 \\ v_0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$



The numerical results by use of the explicit Euler method and the implicit Euler method with an equidistant stepsize $h = 1/20$ as well as the stability region of the explicit Euler method and the h-scaled eigenvalues are illustrated in the following figures for different c .

