

## Series 5:

Task 1: With  $P(\lambda) = \sum_{i=0}^k \lambda^i P_i$   
we have

$$\begin{aligned} P\left(\frac{d}{dt}\right) y(t) &= \sum_{i=0}^k \left(\frac{d}{dt}\right)^i (P_i e^{\lambda_0 t} \alpha_0) \\ &= \sum_{i=0}^k P_i (\lambda_0)^i e^{\lambda_0 t} \alpha_0 \\ &= P(\lambda_0) e^{\lambda_0 t} \alpha_0 = P(\lambda_0) y(t). \end{aligned}$$

## Task 2:

1.) Let  $\mathcal{L}(P)$  be controllable from  $t_0$  to  $t_1$ . To show that  $\mathcal{L}(P)$  is controllable from 0 to  $t_1 - t_0$  let  $z_0, z_1 \in \mathcal{L}(P)$ . Since then also  $z_0(\cdot - t_0), z_1(\cdot - t_0) \in \mathcal{L}(P)$  (the system is time-invariant) there exists a  $\tilde{z} \in \mathcal{L}(P)$  with

$$\tilde{z}(t) = \begin{cases} z_0(t - t_0) & , t \leq t_0 \\ z_1(t - t_0) & , t \geq t_1 \end{cases}$$

Then also  $z(\cdot) := \tilde{z}(\cdot + t_0) \in \mathcal{L}(P)$  and  $z$  fulfills

$$z(t) = \tilde{z}(t + t_0) = \begin{cases} z_0(t + t_0 - t_0) & , t + t_0 \leq t_0 \\ z_1(t + t_0 - t_0) & , t + t_0 \geq t_1 \end{cases} = \begin{cases} z_0(t) & , t \leq 0 \\ z_1(t) & , t \geq t_1 - t_0 \end{cases}$$

This shows controllability from 0 to  $t_1$  to  $t_0$ .  
 The other direction work analogously.

2.) Let  $\mathcal{L}(P)$  be controllable from  $t_0$  to  $t_1$ .  
 Let  $y_0, y_1 \in \mathcal{L}(SPT)$ , i.e., for  $i=1,2$

$$0 \stackrel{\text{SPT}}{\overset{d}{dt}} y_i$$

$$\Rightarrow 0 = P \left( \frac{d}{dt} \right) \underbrace{\left[ T \left( \frac{d}{dt} \right) y_i \right]}_{=: z_i}.$$

$$\Rightarrow z_0, z_1 \in \mathcal{L}(P)$$

$$\Rightarrow \exists z \in \mathcal{L}(P) \text{ such that}$$

$$z(t) = \begin{cases} z_0(t), & t \leq t_0 \\ z_1(t), & t \geq t_1 \end{cases}.$$

Set  $y := T^{-1} \left( \frac{d}{dt} \right) z$  so that

$$y(t) = T^{-1} \left( \frac{d}{dt} \right) z(t) = \begin{cases} T^{-1} \left( \frac{d}{dt} \right) z_0(t), & t \leq t_0 \\ T^{-1} \left( \frac{d}{dt} \right) z_1(t), & t \geq t_1 \end{cases}$$

$$= \begin{cases} y_0(t), & t \leq t_0 \\ y_1(t), & t \geq t_1 \end{cases},$$

which shows controllability of  $\mathcal{L}(SPT)$   
 from  $t_0$  to  $t_1$ .

### Task 3:

- Using Lemma 1.9 one finds that  $\mathcal{L}$ ,  $\mathcal{M}$ ,  $\mathcal{N}$  have no zeros but the blocks of type

$$\mathcal{J}_{p_j}(\lambda_j) = \begin{bmatrix} \lambda_j & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \\ & & & & \lambda_j \end{bmatrix} \in \mathbb{C}[\lambda]^{p_j \times p_j}$$

we have  $\mathcal{Z}(\mathcal{J}_{p_j}) = \{\lambda_j\}$ .

- Since the zeros of  $\lambda F + G$  and the zeros of its Kronecker canonical form are the same we have that

$$\begin{aligned} \mathcal{Z}(\lambda F + G) &= \bigcup_{j=1}^u \mathcal{Z}(\mathcal{J}_{p_j}) \\ &= \{\lambda_1, \dots, \lambda_u\} \end{aligned}$$

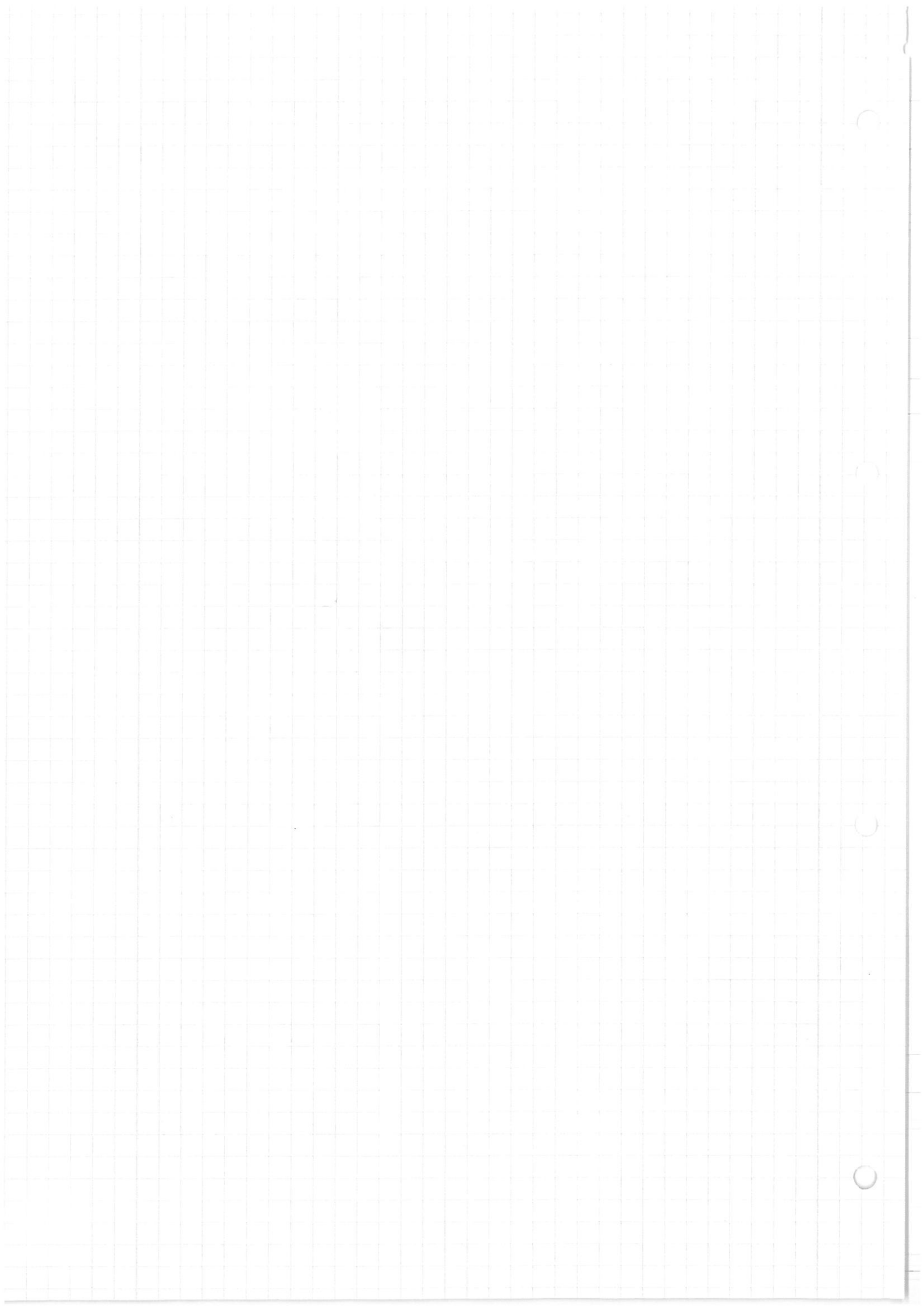
- is the union of all zeros of the blocks  $\mathcal{J}_{p_1}, \dots, \mathcal{J}_{p_u}$ .

### Task 4:

~~The~~ The blocks of type  $\mathcal{L}$  and  $\mathcal{M}$  are left prime.

- The blocks of type  $\mathcal{N}$  and  $\mathcal{H}$  are right prime.

The blocks of type  $\mathcal{J}$  are neither.



## Task 5:

" $\Leftarrow$ " Let  $S$  be a polynomial right inverse and  $z \in \mathcal{L}(P)$

$$\Rightarrow P\left(\frac{d}{dt}\right)z = 0 \quad \Rightarrow \quad \underbrace{S\left(\frac{d}{dt}\right)P\left(\frac{d}{dt}\right)}_{=I} z = S\left(\frac{d}{dt}\right) \cdot 0 = 0$$

$$\Rightarrow z = 0 \quad \Rightarrow \quad \mathcal{L}(P) \subseteq \{0\}$$

$$\Rightarrow \mathcal{L}(P) = \{0\}$$

" $\Rightarrow$ " ~~Assume~~ Assume to the contrary that there was a  $\lambda_0 \in \mathbb{C}$  with  $\text{rank}(P(\lambda_0)) < q$ . Then there exists a  $\alpha_0 \neq 0$  such that

$$P(\lambda_0)\alpha_0 = 0.$$

Set  $z(t) := e^{\lambda_0 t} \alpha_0$ . Using Task 1 we find that

$$P\left(\frac{d}{dt}\right)z(t) = P(\lambda_0)e^{\lambda_0 t}\alpha_0 = \underbrace{P(\lambda_0)\alpha_0}_{=0} e^{\lambda_0 t} = 0$$

$$\Rightarrow z \in \mathcal{L}(P) \text{ although } z \neq 0. \quad \square$$

## Task 6:

In this case the Smith form is

$$P = S \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix} T. \quad \text{Set } R := [I_r, 0]T.$$

Task 7: If  $\text{rank } P(\lambda_0) = q \quad \forall \lambda_0 \in \mathbb{C}$   
 then also for all  $\mu_0 \in \mathbb{C}$  we have

$$\text{rank } P^{\sim}(\mu_0) = \text{rank } P^{\#}(-\bar{\mu}_0)$$

$$= \text{rank } P(\underbrace{-\bar{\mu}_0}_{=\lambda_0}) = q,$$

i.e., that  $P^{\sim}$  is left prime.

Task 8:

If there was a block of type  $\mathcal{L}$   
 or  $\mathcal{J}$  then  $\overline{F}$  could not have  
 full row rank.

Task 9: (With the notation from the handout)

The number of inputs is

$$q - \text{rank}_{\mathbb{C}(z)}(\lambda F + G)$$

$$= q_1 + p_2 + q_3 - \underbrace{\text{rank}_{\mathbb{C}(z)} \lambda F_1 + G_1}_{= p_1} - \underbrace{\text{rank}_{\mathbb{C}(z)} \lambda F_2 + G_2}_{= p_2}$$

$$\quad \quad \quad - \underbrace{\text{rank}_{\mathbb{C}(z)} \lambda F_3 + G_3}_{= q_3}$$

$$= q_1 - p_1.$$

For the Kalman decomposition case, i.e.,



if one computes the Kalman decomposition and the canonical form in the handout for  $\lambda[I, 0] - [A, B] =: \lambda F + G$

then we have (with the corresponding notations)

$$p_3 = q_3 = 0, \quad p_2 = n - r$$

$$p_1 = r, \quad q_1 = r + m.$$

Task 10:

Block of type  $\mathcal{L}_3$  (omitting minus signs)

Since the leading matrix has full row rank, the "right prime reduction" is already done. Then proceed as

$$\left( \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right] \right) \rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right] \right)$$

$$\rightarrow \left( \left[ \begin{array}{c|c} 1 & 1 \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right] \right) \rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right] \right)$$

$$\rightarrow \left( \left[ \begin{array}{c|c} 1 & 1 \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right] \right) \rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline 1 & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & 1 \\ \hline 1 & 1 \end{array} \right] \right)$$

Block of type  $\mathcal{L}_3$

Is already in canonical form

$$\mathcal{L}_3(\lambda) = \lambda \begin{bmatrix} 1 & \\ \hline 1 & 1 \end{bmatrix} - \begin{bmatrix} \lambda_j & 1 \\ \lambda_j & 1 \\ \lambda_j & \lambda_j \end{bmatrix} =: \lambda F_j + G_j$$

Since  $\overline{F}_g$  is invertible

Block of type  $\mathcal{M}_3$ :

$$\begin{aligned} \left( \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right] \right) &\rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right] \right) \rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right] \right) \\ &\rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right] \right) \rightarrow \left( \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right], \left[ \begin{array}{c|c} 1 & \\ \hline & 1 \end{array} \right] \right) \end{aligned}$$

$\Rightarrow$  after three steps in the "right prime reduction" we find that the blocks of type  $\mathcal{M}_3$  are already in the wanted form.

Blocks of type  $\mathcal{M}$  give the same result



## Task 11:

1. For all  $z \in \mathbb{C}$  we have

$$\text{rank } U(z) = \text{rank} \begin{bmatrix} U_1(z) & \tilde{U}(z) \\ 0 & U_2(z) \end{bmatrix}$$

$$\geq \text{rank}(U_1(z)) + \text{rank}(U_2(z))$$

$$= p_1 + p_2$$

2. Let  $[U_1, U_1'] =: V_1$  and  $[U_2, U_2'] =: V_2$  be unimodular. Set

$$U' := \begin{bmatrix} U_1' & 0 \\ 0 & U_2' \end{bmatrix}. \quad \text{Then}$$

$$[U, U'] = \begin{bmatrix} U_1 & \tilde{U} & U_1' & 0 \\ 0 & U_2 & 0 & U_2' \end{bmatrix}$$

$$= \begin{bmatrix} U_1 & U_1' & \tilde{U} & 0 \\ 0 & 0 & U_2 & U_2' \end{bmatrix} \underbrace{\begin{bmatrix} I & & & \\ & 0 & I & \\ & I & 0 & \\ & & & I \end{bmatrix}}_{=: P}$$

$$= \begin{bmatrix} V_1 & \tilde{V} \\ 0 & V_2 \end{bmatrix} P,$$

by setting  $\tilde{V} := [\tilde{U}, 0]$ . Furthermore,

$[U, U']$  is unimodular if and only if  $\begin{bmatrix} V_1 & \tilde{V} \\ 0 & V_2 \end{bmatrix}$  is, i.e., if ~~and only~~ for example

There exists a polynomial matrix  $X$  with

$$\begin{aligned} I &= \begin{bmatrix} V_1^{-1} & X \\ 0 & V_2^{-1} \end{bmatrix} \begin{bmatrix} V_1 & \tilde{V} \\ 0 & V_2 \end{bmatrix} \\ &= \begin{bmatrix} I & V_1^{-1} \tilde{V} + X V_2 \\ 0 & I \end{bmatrix}. \end{aligned}$$

However, choosing  $X := -V_1^{-1} \tilde{V} V_2^{-1}$  one can see that this is true.

3. If  $S_1, S_2$  are the left inverses one can ~~see~~ find similar to  $Z$  that

$$S := \begin{bmatrix} S_1 & X \\ 0 & S_2 \end{bmatrix},$$

with  $X := -S_1 \tilde{U} S_2$ , is a left inverse of  $U$ .

## Task 12:

Since for all  $\lambda$  we have

$$\begin{aligned} \text{rank}(\lambda_0 F + G) &= \text{rank} \begin{bmatrix} 1 & 1 & 1 & 0 \\ -R & 0 & 0 & 1 \\ 0 & \lambda_0 L & 0 & -1 \end{bmatrix} \cdot R \\ &= \text{rank} \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & R & R & 1 \\ 0 & \lambda_0 L & 0 & -1 \end{bmatrix} = \text{rank} \begin{bmatrix} 1 & 1 & 0 & 1 \\ & R & 1 & R \\ & & -1 & \lambda_0 L \end{bmatrix} = 3 \end{aligned}$$

Lemma 1.9 implies that  $\mathcal{Z}(P) = \emptyset$ . Thus  $\mathcal{L}_0(P)$  is controllable by Definition 2.14.

## Task 13:

1.) The system

$$\left\{ \begin{bmatrix} \ddot{q} \\ \dot{q} \\ q \end{bmatrix} \in \mathcal{L}_\infty^2 \mid m \ddot{q} + d \dot{q} + k q = f \right\}$$

$$= \left\{ \begin{bmatrix} \ddot{q} \\ \dot{q} \\ q \end{bmatrix} \in \mathcal{L}_\infty^2 \mid \begin{bmatrix} (\frac{d}{dt})^2 m + (\frac{d}{dt}) d + k & -1 \end{bmatrix} \begin{bmatrix} \ddot{q} \\ \dot{q} \\ q \end{bmatrix} = 0 \right\}$$

with the Definition  $P(\lambda) := \begin{bmatrix} \lambda^2 m + \lambda d + k & -1 \end{bmatrix}$  can be written as  $\mathcal{L}(P)$ .

Since for all  $\lambda_0 \in \mathbb{C}$  we have

$$\text{rank} [P(\lambda_0)] = \text{rank} [\lambda_0^2 m + \lambda_0 d + k, -1] = 1$$

Lemma 1.9 again implies controllability of the system.

2.) Here the system is  $\mathcal{L}(P)$  with

$$P(\lambda) := \left[ \begin{array}{c|c} \lambda^2 m_1 + \lambda d_1 + k_1 & -1 \\ \hline \lambda^2 m_2 + \lambda d_2 + k_2 & -1 \end{array} \right].$$

Since the set of zeros does not change under unimodular transformations we have

$$\mathcal{Z}(P) = \mathcal{Z} \left( \left[ \begin{array}{c|c} \lambda^2 m_1 + \lambda d_1 + k_1 & -(\lambda^2 m_2 + \lambda d_2 + k_2) \\ \hline 0 & 0 \end{array} \right] \begin{array}{c} -1 \\ -1 \end{array} \right)$$

$$= \mathcal{Z} \left( \left[ \begin{array}{c|c} \lambda^2 m_1 + \lambda d_1 + k_1 & -(\lambda^2 m_2 + \lambda d_2 + k_2) \\ \hline & -1 \end{array} \right] \right)$$

$$= \mathcal{Z} \left( \left[ \underbrace{\lambda^2 m_1 + \lambda d_1 + k_1}_{=: p_1}, \underbrace{-\left(\lambda^2 m_2 + \lambda d_2 + k_2\right)}_{=: p_2} \right] \right).$$

$$= \mathcal{Z} \left( \left[ \lambda^2 + \lambda \frac{d_1}{m_1} + \frac{k_1}{m_1}, \lambda^2 + \lambda \frac{d_2}{m_2} + \frac{k_2}{m_2} \right] \right)$$

Notation  
on exercise  
sheet

$$= \mathcal{Z} \left( \left[ (\lambda - \lambda_1^{(1)})(\lambda - \lambda_2^{(1)}), (\lambda - \lambda_1^{(2)})(\lambda - \lambda_2^{(2)}) \right] \right).$$

This set is empty if and only if

$$\{\lambda_1^{(1)}, \lambda_2^{(1)}\} \cap \{\lambda_1^{(2)}, \lambda_2^{(2)}\} = \emptyset, \text{ i.e.,}$$

if the two polynomials  $p_1, p_2$  have no common zeros. Since we assume that  $\lambda_{1,2}^{(i)}$  is a complex conjugate pair, this is the case if and only if

$$\operatorname{Re}(\lambda_1^{(1)}) \neq \operatorname{Re}(\lambda_1^{(2)}) \quad \vee \quad \operatorname{Im}(\lambda_1^{(1)}) \neq \operatorname{Im}(\lambda_1^{(2)})$$

$$\Leftrightarrow \frac{d_1}{2m_1} \neq \frac{d_2}{2m_2} \quad \vee \quad \left( \frac{d_1}{2m_1} \right)^2 - \frac{k_1}{m_1} \neq \left( \frac{d_2}{2m_2} \right)^2 - \frac{k_2}{m_2}.$$