

Theorem 4.4

Let $P \in \mathbb{C}[\lambda]^{p,q}$, $H = H^* \in \mathbb{C}^{k_q, k_q}$, $z_0 \in \mathcal{L}_+(P)$, and set $\tilde{H}(\lambda) := \Delta_K^q(\lambda) H \Delta_K^q(\lambda)$.

Let $\hat{z} \in \mathcal{L}_+(P)$ solve (LQ).

Then H is non-negative w.r.t. P and there exists a

$\hat{u} \in \mathcal{C}_+^p$ such that

$$(\Delta) \quad \begin{bmatrix} 0 & p(\frac{d}{dt}) \\ p^{\sim}(\frac{d}{dt}) & H^{\sim}(\frac{d}{dt}) \end{bmatrix} \begin{bmatrix} \hat{u}(t) \\ \hat{z}(t) \end{bmatrix} = 0 \quad t \geq 0.$$

○ Remarks: Since by (LQ) $\hat{z}(t) = z_0(t)$ for $t \leq 0$ and z_0 does not have to be optimal (Δ) does in general not hold for $t \leq 0$.

Proof: To show non-negativity, let $y \in \mathcal{L}_+(P)$ with $y(t) = 0$ for $t \leq 0$ be arbitrary. } (□)

For $s \in \mathbb{R}$ define $z_s(t) := \hat{z}(t) + sy(t) \in \mathcal{L}_+(P)$

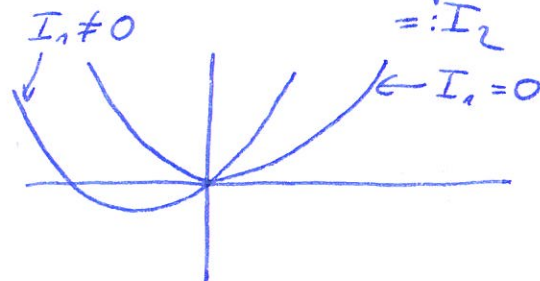
so that for $t \leq 0$ we have $z_s(t) = \underbrace{\hat{z}(t)}_{= z_0(LQ)} + \underbrace{sy(t)}_{= 0(\square)} = z_0(t)$.

○ Since $\hat{z}(t)$ is the optimal trajectory (in the sense of (LQ)) z_s cannot be better:

$$\begin{aligned} \int_0^{\infty} (\Delta \hat{z})^* H (\Delta \hat{z}) dt &\leq \int_0^{\infty} (\Delta z_s)^* H (\Delta z_s) dt \\ &= \int_0^{\infty} (\Delta \hat{z})^* H (\Delta \hat{z}) dt + \underbrace{s \cdot 2 \operatorname{Re} \left\{ \int_0^{\infty} (\Delta y)^* H (\Delta \hat{z}) dt \right\}}_{=: I_1} + \underbrace{s^2 \int_0^{\infty} (\Delta y)^* H (\Delta y) dt}_{=: I_2} \end{aligned}$$

$\Rightarrow 0 \leq s I_1 + s^2 I_2$ for all $s \in \mathbb{R}$.

$\Rightarrow I_1 = 0$ and $I_2 \geq 0$.



Thus we have non-negativity $0 \leq I_2 = \int_0^\infty (\Delta y)^* H(\Delta y) dt$
 since y was arbitrary.

Since with y also $i \cdot y \in \mathcal{L}_+(P)$ is a trajectory with
 imaginary unit

$i \cdot y(t) = 0$ for $t \leq 0$ we obtain that $0 = I_1$ also implies

$$0 = \operatorname{Re} \left\{ \int_0^\infty \underbrace{(\Delta i y)^*}_{(i \Delta y)^*} H(\Delta \hat{z}) dt \right\} = -\operatorname{Re} \left\{ i \int_0^\infty (\Delta y)^* H(\Delta \hat{z}) dt \right\}$$

$$= (i \Delta y)^* = -i (\Delta y)^*$$

$$= \operatorname{Im} \left\{ \int_0^\infty (\Delta y)^* H(\Delta \hat{z}) dt \right\}.$$

This means that the real part and the imaginary part are zero and thus $0 = \int_0^\infty (\Delta y)^* H(\Delta \hat{z}) dt$

$$= \int_0^\infty (\Delta_K^q \left(\frac{d}{dt} y \right)^*)^* (H \Delta_K^q \left(\frac{d}{dt} \hat{z} \right)) dt$$

Lemma 4.2 \Downarrow

$$\int_0^\infty y^* \left(\Delta_K^q \left(\frac{d}{dt} \right) H \Delta_K^q \left(\frac{d}{dt} \right) \hat{z} \right) dt - \sum_{c=1}^\infty (-1)^c \underbrace{\left(\Delta_K^q \left(\frac{d}{dt} \right) y(t) \right)^*}_{=0 \text{ with } (*)} \dots$$

$$\dots \left(H \Delta_K^q \left(\frac{d}{dt} \right) \hat{z}(t) \right) \Big|_0^\infty \quad (*)$$

$$= \int_0^\infty y^* \left(\tilde{H} \left(\frac{d}{dt} \right) \hat{z} \right) dt \text{ for all } y \in \mathcal{L}_+(P) \text{ with } y(t) = 0, t \leq 0.$$

Let $r := \operatorname{rank}_{\mathbb{C}(\lambda)} P$ and let $U \in \mathbb{C}[\lambda]^{q, q-r}$ and $V \in \mathbb{C}[\lambda]^{q, r}$ be

the kernel and co-kernel spanning matrices, as given by

Lemma 1.10, i.e., let a) $[U, V]$ unimodular

b) $P U = 0$

c) $P V$ has full column rank.

Then for all $\alpha \in \mathcal{L}_+^{q-r}$ with $\alpha(t) = 0, t \leq 0$ we have that

$$U\left(\frac{d}{dt}\right) \alpha(t) \in \mathcal{L}_+(P) \left[\text{since } \underbrace{P\left(\frac{d}{dt}\right)U\left(\frac{d}{dt}\right)\alpha(t)}_{(PU)\left(\frac{d}{dt}\right)\alpha(t)} = 0 \right]$$

and $U\left(\frac{d}{dt}\right)\alpha(t) = 0, t \leq 0$.

Thus (*) implies $0 = \int_0^{\infty} \left(U\left(\frac{d}{dt}\right)\alpha \right)^* \left(\tilde{H}\left(\frac{d}{dt}\right)\hat{z} \right) dt$

$$\stackrel{\text{Lemma 4.2}}{=} \int_0^{\infty} \alpha^* \left(U\left(\frac{d}{dt}\right)^* \tilde{H}\left(\frac{d}{dt}\right)\hat{z} \right) dt + \sum_{e=1}^{\infty} (-1)^e \dots \underbrace{\alpha(t)}_{=0} \dots \Big|_0^{\infty}$$

for all $\alpha \in \mathcal{C}_+^{q-r}$ with $\alpha(t) = 0, t \leq 0$

$$\Rightarrow U^* \left(\frac{d}{dt}\right) \tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t) = 0 \quad \forall t \geq 0 \quad (**)$$

Furthermore, by Series 9, Task 4 and using c) there exists a $\hat{u} \in \mathcal{C}_+^p$ such that $(PV)\left(\frac{d}{dt}\right)\hat{u}(t) = -V^* \left(\frac{d}{dt}\right) \tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t)$.

This implies that for $t \geq 0$ we have

$$P^* \left(\frac{d}{dt}\right)\hat{u}(t) \stackrel{a)}{=} [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* P^* \left(\frac{d}{dt}\right)\hat{u}(t)$$

$$= [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* \begin{bmatrix} U^* \left(\frac{d}{dt}\right) P^* \left(\frac{d}{dt}\right)\hat{u}(t) \\ V^* \left(\frac{d}{dt}\right) P^* \left(\frac{d}{dt}\right)\hat{u}(t) \end{bmatrix}$$

$$= [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* \begin{bmatrix} (PU)^* \left(\frac{d}{dt}\right)\hat{u}(t) \stackrel{b)}{=} 0 \\ (PV)^* \left(\frac{d}{dt}\right)\hat{u}(t) \end{bmatrix}$$

$$= [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* \begin{bmatrix} -U^* \left(\frac{d}{dt}\right) \tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t) \\ -V^* \left(\frac{d}{dt}\right) \tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t) \end{bmatrix}$$

$$= \underbrace{[U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]^* [U\left(\frac{d}{dt}\right), V\left(\frac{d}{dt}\right)]}_{=I} \left(-\tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t) \right) = -\tilde{H}\left(\frac{d}{dt}\right)\hat{z}(t),$$

which in matrix notation is

$$\begin{bmatrix} P^* \left(\frac{d}{dt}\right) \\ \tilde{H}\left(\frac{d}{dt}\right) \end{bmatrix} \begin{bmatrix} \hat{u}(t) \\ \hat{z}(t) \end{bmatrix} = 0 \quad \text{for } t \geq 0 \quad \blacksquare$$

Remark: Results similar to Theorem 4.3 and 4.4 can be obtained for finite-time optimal control problems of the form

$$\inf_{z \in \mathcal{L}_+(P)} \left(\int_0^T (\Delta_K z(t))^* H(\Delta_K z(t)) dt + (\Delta_K z(T))^* H(\Delta_K z(T)) \right) \text{ where } z(t) = z_0(t), t \leq 0 \quad T > 0 \text{ is some fixed finite end-time.}$$

- The following theorem states that for (L, Q) the past $t < 0$ of $z_0(t)$ does not play a role but only the values of $z_0(0), \dot{z}_0(t), \dots$

Theorem 4.5 Let $P \in \mathcal{O}[\lambda]_K^{p, q}$ and $H = H^* \in \mathbb{C}^{k_q, k_q}$. Define

$$\Theta: \mathbb{C}^{k_q} \rightarrow \mathbb{R} \cup \{\infty, -\infty\} \text{ through}$$

$$\Theta(y) := \inf_{\substack{z \in \mathcal{L}_+(P) \\ \Delta_K z(0) = y}} \int_0^\infty (\Delta_K z(t))^* H(\Delta_K z(t)) dt.$$

same as in (L, Q)

$$\text{Then we have } \Theta(\Delta_K z_0(0)) = \underbrace{\inf_{\substack{z \in \mathcal{L}_+(P) \\ z(t) = z_0(t), t \leq 0}} \int_0^\infty (\Delta z(t))^* H(\Delta z(t)) dt}$$

for all $z_0 \in \mathcal{L}_+(P)$.

Furthermore, if $K=1$ (this implies that $\Delta_K^q(\lambda) = I$ and thus $\Delta_K z = z$) and $P(\lambda) = \lambda F + G$ we also have

$$\Theta(z_0(0)) = \inf_{\substack{z \in \mathcal{L}_+(P) \\ Fz_0(0) = Fz(0)}} \int_0^\infty z^*(t) H z(t) dt$$

Proof: see Appendix.

Para-Hermitian Schur-Form

In this section we use the following notation: we set

$$J = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} \in \mathbb{C}^{2p, 2p} \quad \text{and with } M_{11} = M_{11}, M_{12} = M_{12}, M_{22} = M_{22}^* \in \mathbb{C}^{p, p}$$

We define the para-Hermitian polynomial

$$N(\lambda) = \lambda J + \underbrace{\begin{bmatrix} M_{11} & M_{12} \\ M_{12}^* & M_{22} \end{bmatrix}}_{=: M = M^*}.$$

If N has no purely imaginary zeros, i.e., $\mathcal{Z}(N) \cap i\mathbb{R} = \emptyset$

then by Lemma 4.1 the number of zeros in the left and right half plane is the same

$$|\mathcal{Z}(N) \cap \mathbb{C}_-| = |\mathcal{Z}(N) \cap \mathbb{C}_+|.$$

In this section we will show that in this case there exists a unitary $V \in \mathbb{C}^{2p, 2p}$ such that

$$V^* N(\lambda) V = \lambda J + \begin{bmatrix} K & | & T \\ \hline - & & - \\ T^* & | & 0 \end{bmatrix} = \begin{bmatrix} K & | & \lambda I + T \\ \hline - & & - \\ -\lambda I + T^* & | & 0 \end{bmatrix},$$

where the (1,2)-block contains all the zeros in the left half plane.

$\mathcal{Z}(\lambda I + T) = \mathcal{Z}(N) \cap \mathbb{C}_-$ and the (2,1)-block contains all zeros in the right half-plane

$$\mathcal{Z}(-\lambda I + T^*) \stackrel{\text{Lemma 4.1}}{=} -\overline{\mathcal{Z}(\lambda I + T)} = \mathcal{Z}(N) \cap \mathbb{C}_+.$$

Lemma 4.6: Let $\lambda_0 \in \mathcal{Z}(N)$ be with $\operatorname{Re}(\lambda_0) \neq 0$.

Let $x_0 = \begin{bmatrix} v_0 \\ w_0 \end{bmatrix} \in \mathbb{C}^{2p} \setminus \{0\}$ be with $N(\lambda_0)x_0 = 0$.

(Existence of x_0 : Lemma 1.9).

Then there exists a unitary $V \in \mathbb{C}^{2p, 2p}$ such that

$$V^* N(\lambda) V = \lambda J + \begin{bmatrix} * & \vdots & * \\ * & \vdots & * \\ \vdots & \ddots & \vdots \\ * & \vdots & * \end{bmatrix}_p \quad \left(\begin{array}{l} \text{this means that } V^* J V = J \\ \text{by equating coefficients} \end{array} \right)$$

and $V^* x_0 = \beta \cdot e_{2p}$, where $\beta \in \mathbb{C} \setminus \{0\}$.

Proof: [as seen in a lecture of C. Mehl]

From $0 = N(\lambda_0)x_0 = \lambda_0 J x_0 + M x_0$

it follows that $\lambda_0 \underbrace{x_0^* J x_0}_{\in (i\mathbb{R})} = -x_0^* M x_0 \stackrel{M \text{ is Hermitian}}{\in \mathbb{R}}$.

J is skew-Hermitian
(Homework, S. 10, T. 4)

Assume to the contrary that $x_0^* J x_0 \neq 0$. Then

$$\lambda_0 = \frac{1}{\underbrace{x_0^* J x_0}_{\in (i\mathbb{R})}} x_0^* M x_0 \in (i\mathbb{R})$$

which contradicts the assumption $\operatorname{Re}(\lambda) \neq 0$. Thus

$$0 = x_0^* J x_0 = x_0^* \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} \begin{bmatrix} v_0 \\ w_0 \end{bmatrix} = [v_0^* \ w_0^*] \begin{bmatrix} w_0 \\ -v_0 \end{bmatrix} = v_0^* w_0 - w_0^* v_0$$

$$\Rightarrow v_0^* w_0 = w_0^* v_0 = (v_0^* w_0)^* = \overline{v_0^* w_0} \in \mathbb{R}.$$

Let $P_1 \in \mathbb{C}^{p, p}$ be a unitary Householder-transformation such that

$$P_1 v_0 = \alpha \cdot e_p, \quad \alpha \in \mathbb{C} \quad (\text{Existence of } P_1: \text{Homework S. 10, T. 8})$$

and set

$$P_1 w_0 := \tilde{w} := \begin{bmatrix} \tilde{w}_1 \\ \vdots \\ \tilde{w}_p \end{bmatrix} \quad \text{to obtain}$$

$$\underbrace{\begin{bmatrix} P_1 \\ \vdots \\ P_1 \end{bmatrix}}_{=: V_1^*} \begin{bmatrix} V_0 \\ W_0 \end{bmatrix} = \underbrace{\begin{bmatrix} 0 \\ \vdots \\ \alpha \\ \tilde{w}_1 \\ \vdots \\ \tilde{w}_p \end{bmatrix}}_P \quad \text{which is not yet a multiple of } e_{2p} \text{ but at least the transformation}$$

$$V_1^* J V_1 = V_1^* \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} \begin{bmatrix} P_1^* & 0 \\ 0 & P_1^* \end{bmatrix} = \begin{bmatrix} P_1 & \\ & P_1 \end{bmatrix} \begin{bmatrix} 0 & P_1^* \\ -P_1^* & 0 \end{bmatrix} = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} = J$$

leaves J unchanged. Note that

$$R \ni v_0^* w_0 = v_0^* P_1^* P_1 w_0 = (P_1 v_0)^* (P_1 w_0) = [0, \dots, 0, \bar{\alpha}] \begin{bmatrix} \tilde{w}_1 \\ \vdots \\ \tilde{w}_p \end{bmatrix} = \bar{\alpha} \tilde{w}_p$$

If $\alpha \neq 0$ we have that

$$R \ni \frac{\bar{\alpha} \cdot \tilde{w}_p}{|\alpha|^2} = \frac{\bar{\alpha} \cdot \tilde{w}_p}{\bar{\alpha} \cdot \alpha} = \frac{\tilde{w}_p}{\alpha} \quad \text{and thus}$$

$$s := \frac{1}{\sqrt{1 + \left(\frac{\tilde{w}_p}{\alpha}\right)^2}} \in \mathbb{R} \quad \text{and} \quad c = \frac{\tilde{w}_p}{\alpha} \cdot s \in \mathbb{R}$$

$$\text{fulfill } c^2 + s^2 = \left(\frac{\tilde{w}_p}{\alpha}\right)^2 s^2 + s^2 = \left(1 + \left(\frac{\tilde{w}_p}{\alpha}\right)^2\right) s^2 = 1, \text{ and}$$

$$\underbrace{\begin{bmatrix} c & -s \\ s & c \end{bmatrix}}_{=: \hat{G}} \begin{bmatrix} \alpha \\ \tilde{w}_p \end{bmatrix} \stackrel{\substack{\text{only } \tilde{w}_p \text{ is} \\ \text{defined.}}}{=} \begin{bmatrix} c\alpha - s\tilde{w}_p \\ \hat{w}_p \end{bmatrix} = \begin{bmatrix} s \frac{\tilde{w}_p}{\alpha} \cdot \alpha - s \cdot \tilde{w}_p \\ \hat{w}_p \end{bmatrix} \begin{bmatrix} 0 \\ \hat{w}_p \end{bmatrix}$$

where \hat{G} is an orthogonal (and thus also a unitary) given rotation.

If $\alpha = 0$ we can set $c=1, s=0$ and still we have

$$c^2 + s^2 = 1, \text{ and } \underbrace{\begin{bmatrix} c & -s \\ s & c \end{bmatrix}}_{=: \hat{G}} \begin{bmatrix} \alpha \\ \tilde{w}_p \end{bmatrix} := \begin{bmatrix} 0 \\ \hat{w}_p \end{bmatrix}$$

by setting $\hat{w}_p := \tilde{w}_p$, where \hat{G} is again unitary.

In both cases this implies that the Givens rotation

$$g^* := \begin{bmatrix} I_{p-1} & 0 & 0 & 0 \\ 0 & c & 0 & -s \\ 0 & 0 & I_{p-1} & 0 \\ 0 & s & 0 & c \end{bmatrix} \in \mathbb{R}^{2p, 2p} \text{ is unitary} \\ \text{(even orthogonal)}$$

$$\text{and } g^* V_1^* x_0 = g \left[\begin{array}{c} \vdots \\ \alpha \\ \sigma_1 \\ \vdots \\ \omega_p \end{array} \right] = \left[\begin{array}{c} \vdots \\ \omega_1 \\ \vdots \\ \omega_{p-1} \\ \omega_p \end{array} \right] =: \left[\begin{array}{c} 0 \\ \omega \end{array} \right] \text{ while still}$$

$$g^* J g = g^* \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} \begin{bmatrix} I & 0 & 0 & 0 \\ & c & & -s \\ & 0 & I & \\ & s & & c \end{bmatrix} = \begin{bmatrix} I & 0 & 0 & s \\ & c & & c \\ & 0 & I & \\ -s & & & c \end{bmatrix} \begin{bmatrix} 0 & I & \\ & s & & c \\ -I & & 0 & \\ & -c & & s \end{bmatrix} \\ = \begin{bmatrix} 0 & I & & \\ & cs - sc & & c^2 + s^2 \\ -I & & 0 & \\ & -s^2 - c^2 & & -sc + cs \end{bmatrix} = \begin{bmatrix} 0 & I \\ -I & 0 \end{bmatrix} = J.$$

Finally let P_2 again be a unitary Householder - transformation, this time with $P_2 \omega = \beta e_p$ so that

$$\underbrace{\begin{bmatrix} P_2 & \\ & P_2 \end{bmatrix}}_{:= V_2^*} g^* V_1^* x_0 = \begin{bmatrix} 0 \\ \beta e_p \end{bmatrix} = \beta e_{2p} \text{ where as before} \\ V_2^* J V_2 = J.$$

Thus, setting $V^* := V_2^* g^* V_1^* = (V_1 g^* V_2)^*$ the claim is shown \square

Theorem 4.7

If the para-Hermitian polynomial matrix

$$N(\lambda) = \lambda \underbrace{\begin{bmatrix} 0 & I_p \\ -I_p & 0 \end{bmatrix}}_{=: J_p} + M \in \mathbb{C}[\lambda]^{2p, 2p} \text{ has no purely}$$

imaginary zeros, then there exists a unitary $V \in \mathbb{C}^{2p, 2p}$

$$\text{such that } V^* N(\lambda) V = \lambda J_p + \left[\begin{array}{c|c} K & L \\ \hline L^* & 0 \end{array} \right] = \left[\begin{array}{c|c} K & \lambda I + L \\ \hline -\lambda I + L^* & 0 \end{array} \right]$$

where $K = K^* \in \mathbb{C}^{p, p}$, $L = \begin{bmatrix} \blacksquare & \\ & \blacksquare \\ & & \blacksquare \end{bmatrix} \in \mathbb{C}^{p, p}$ is lower triangular

and $\mathcal{Z}(\lambda I + L) \subseteq \mathbb{C}_-$.

Proof: By induction.

Base case: ($p=1$) Homework; works in principle exactly as the inductive step. Or for $p=0$ it is trivial.

Inductive step: Let $\lambda_0 \in \mathcal{Z}(N)$, $\operatorname{Re}(\lambda_0) \neq 0$. Since

$N = N^{\sim}$ by Lemma 4.1 also $-\bar{\lambda}_0 \in \mathcal{Z}(N)$ and

$\operatorname{Re}(-\bar{\lambda}_0) = -\operatorname{Re}(\lambda_0)$. Thus we can w.l.o.g. assume that

$\operatorname{Re}(\lambda_0) < 0$. Let $x_0 \in \mathbb{C}^{2p} \setminus \{0\}$ be with $N(\lambda_0)x_0 = 0$

(Lemma 1.9). By Lemma 4.6 we obtain the existence

of a unitary V with $V^* J_p V = J_p$ and

$$V^* x_0 = \beta e_{2p}, \beta \neq 0$$

Then we have

$$0 = V^* N(\lambda_0) x_0 = \underbrace{V^* N(\lambda_0) V}_{=: \tilde{N}(\lambda_0)} V^* x_0 = \tilde{N}(\lambda_0) \beta e_{2p}, \text{ i.e.,}$$

that the last column of $\tilde{N}(\lambda_0)$ vanishes. Since (due to the structure of $J_p = \begin{bmatrix} 0 & I_p \\ -I_p & 0 \end{bmatrix}$) the last column of $\tilde{N}(\lambda) := V^* N(\lambda) V$ has the form

$$\tilde{N}(\lambda) e_{2p} = \begin{bmatrix} \tilde{m}_1 \\ \vdots \\ \tilde{m}_{p-1} \\ \lambda + \tilde{m}_p \\ \tilde{m}_{p+1} \\ \vdots \\ \tilde{m}_{2p} \end{bmatrix} \text{ this implies that } \tilde{m}_p = -\lambda_0 \text{ and } \tilde{m}_i = 0 \text{ for } i \neq p.$$

Since M (and thus also $V^* M V = \tilde{M}$) is Hermitian the last row of $\tilde{N}(\lambda)$ has the same / a similar form

$$e_{2p}^* \tilde{N}(\lambda) = \left[\overbrace{0, \dots, 0}^{p-1}, \lambda - \lambda_0, \overbrace{0, \dots, 0}^p \right]$$

which means that \tilde{N} has the form

$$\tilde{N}(\lambda) = \lambda \begin{bmatrix} 0 & & I_{p-1} & \\ & 0 & & 1 \\ -I_{p-1} & & 0 & \\ & -1 & & 0 \end{bmatrix} + \begin{bmatrix} \tilde{M}_{11} & X & \tilde{M}_{12} & 0 \\ X & X & X & -\lambda_0 \\ \tilde{M}_{12}^* & X & \tilde{M}_{22} & 0 \\ 0 & -\lambda_0 & 0 & 0 \end{bmatrix} \begin{matrix} \}^{p-1} \\ \}^1 \\ \}^{p-1} \\ \}^1 \end{matrix}$$

where x denotes scalars or vector of matching dimension and $\tilde{M}_{11} = \tilde{M}_{11}^*$, $\tilde{M}_{12}, \tilde{M}_{22} = \tilde{M}_{22}^* \in \mathbb{C}^{(p-1), (p-1)}$ are constant matrices. Since the submatrix of $\tilde{N}(\lambda)$ given by

$$\tilde{N}_1(\lambda) := \lambda J_{p-1} + \begin{bmatrix} \tilde{M}_{11} & \tilde{M}_{12} \\ \tilde{M}_{12}^* & \tilde{M}_{22} \end{bmatrix} \in \mathbb{C}[\lambda]_{1}^{2(p-1), 2(p-1)}$$

also has purely imaginary eigenvalues

$$\mathcal{Z}(N) = \mathcal{Z}(\tilde{N}) = \mathcal{Z}(\tilde{N}_1) \cup \{\lambda_0, -\bar{\lambda}_0\}$$

(Homework, S. 10, T. 10)

the induction hypothesis implies that there exists

$$\text{a unitary } \tilde{V}_1 := \begin{bmatrix} Q_{11} & Q_{12} \\ Q_{21} & Q_{22} \end{bmatrix} \in \mathbb{C}^{2(p-1), 2(p-1)}$$

$\underbrace{\hspace{10em}}_{p-1} \quad \underbrace{\hspace{10em}}_{p-1}$

such that $\tilde{V}_1^* \tilde{N}_1(\lambda) \tilde{V}_1 = \lambda J_{p-1} + \begin{bmatrix} \tilde{K} & \tilde{L} \\ \tilde{L}^* & 0 \end{bmatrix}$ with

\tilde{L} lower triangular. Finally defining

$$\tilde{V} := \begin{bmatrix} Q_{11} & Q_{12} & & \\ & 1 & & 0 \\ Q_{21} & Q_{22} & & \\ & 0 & & 1 \end{bmatrix} \in \mathbb{C}^{2p, 2p} \quad \text{we have}$$

$$\tilde{V}^* \tilde{N}(\lambda) \tilde{V} = \lambda J_p + \begin{bmatrix} \tilde{K} & X & \tilde{L} & 0 \\ X & X & X & -\lambda_0 \\ \tilde{L}^* & X & 0 & 0 \\ 0 & -\bar{\lambda}_0 & 0 & 0 \end{bmatrix} =: \lambda J_p + \begin{bmatrix} K & L \\ L^* & 0 \end{bmatrix}$$

and thus the claim. \square

