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# Mathematical Tools for Engineering and Management

## Lecture 10

04 Jan 2012



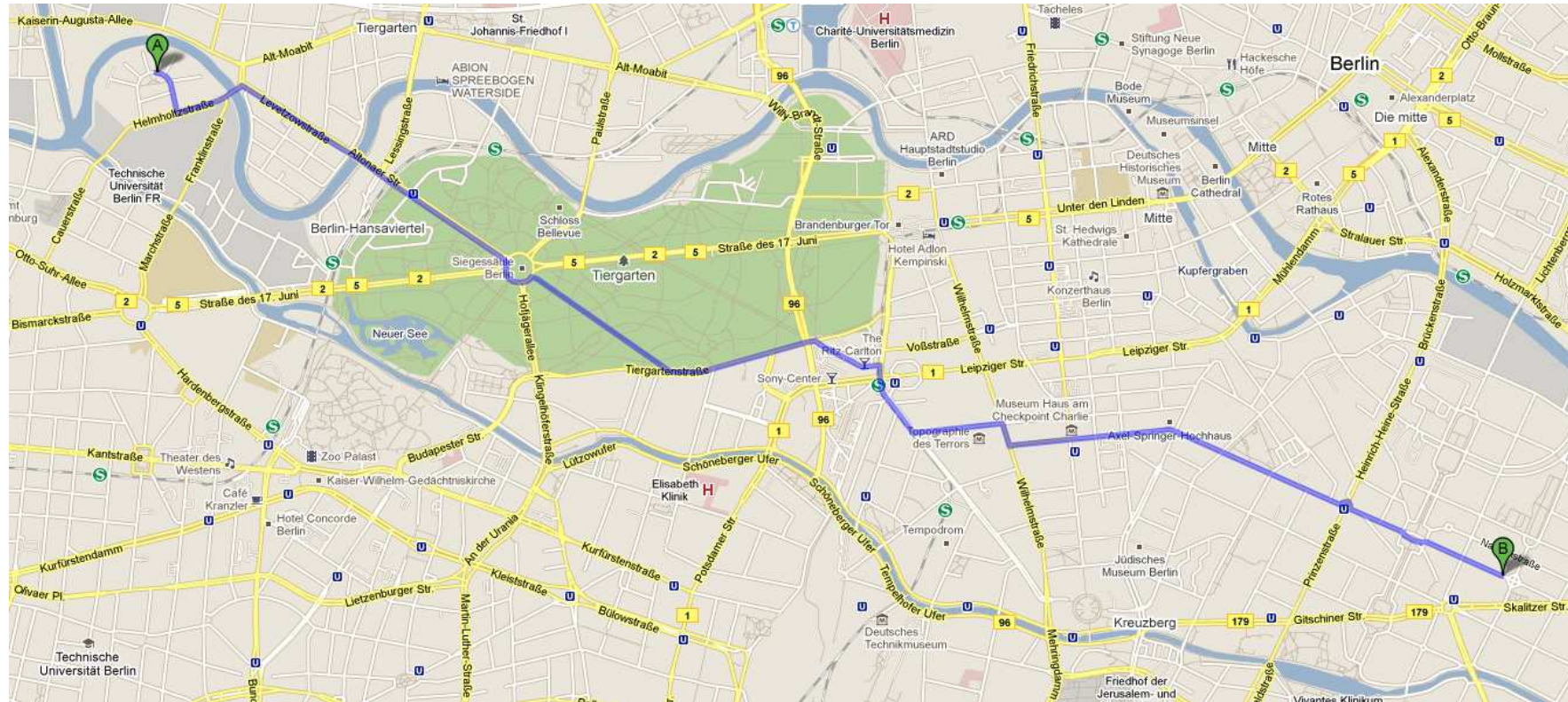
- ▷ Models, Data and Algorithms
- ▷ Linear Optimization
- ▷ Mathematical Background: Polyhedra, Simplex-Algorithm
- ▷ Sensitivity Analysis; (Mixed) Integer Programming
- ▷ MIP Modelling
- ▷ MIP Modelling: More Examples; Branch & Bound
- ▷ Cutting Planes; Combinatorial Optimization: Examples, Graphs, Algorithms
- ▷ TSP-Heuristics
- ▷ Network Flows
- ▷ Shortest Path Problem
- ▷ Complexity Theory
- ▷ Nonlinear Optimization, Scheduling
- ▷ Lot Sizing, Multicriteria Optimization
- ▷ Oral exam

- ▶ Problem: find a shortest path from PTZ to Kreuzburger



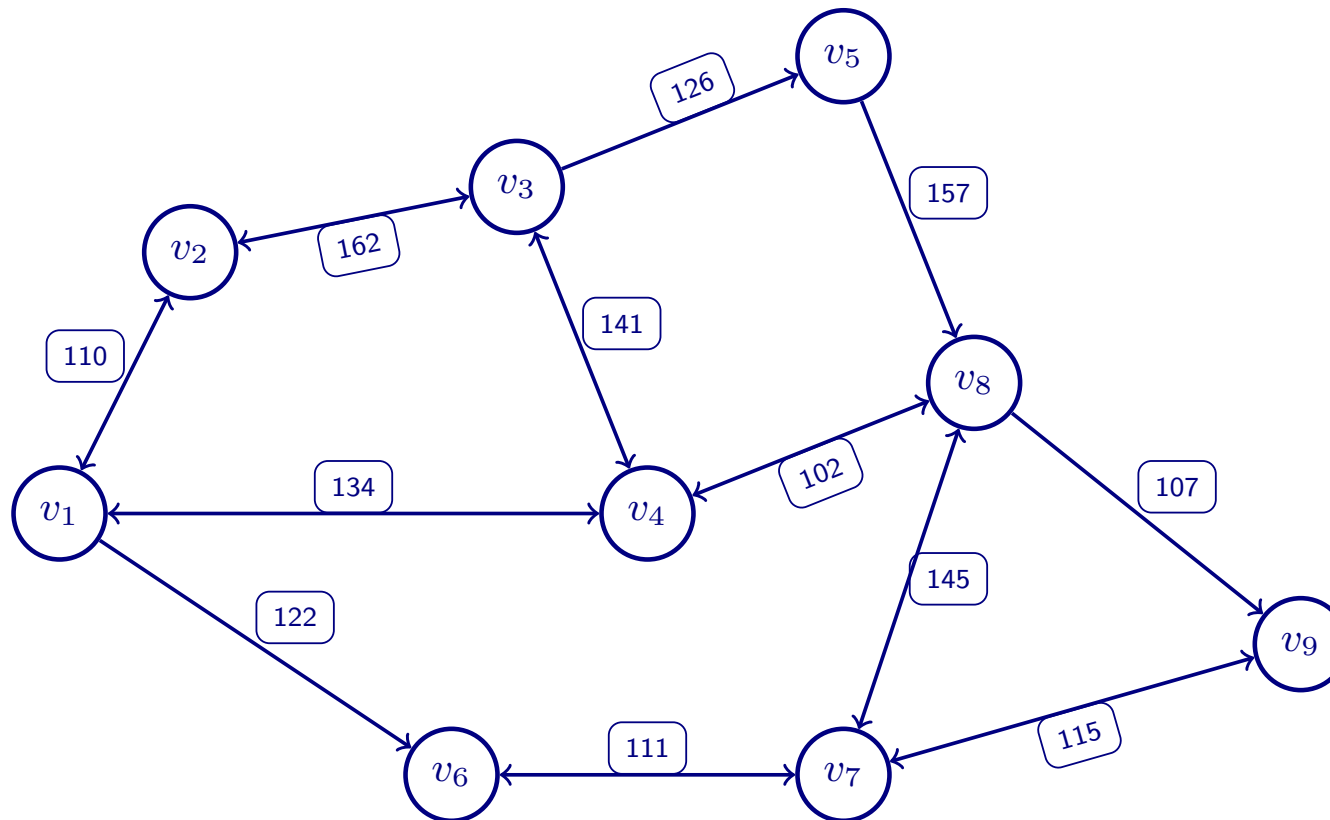
# Example: Shortest Path

▷ Problem: find a shortest path from PTZ to Kreuzburger

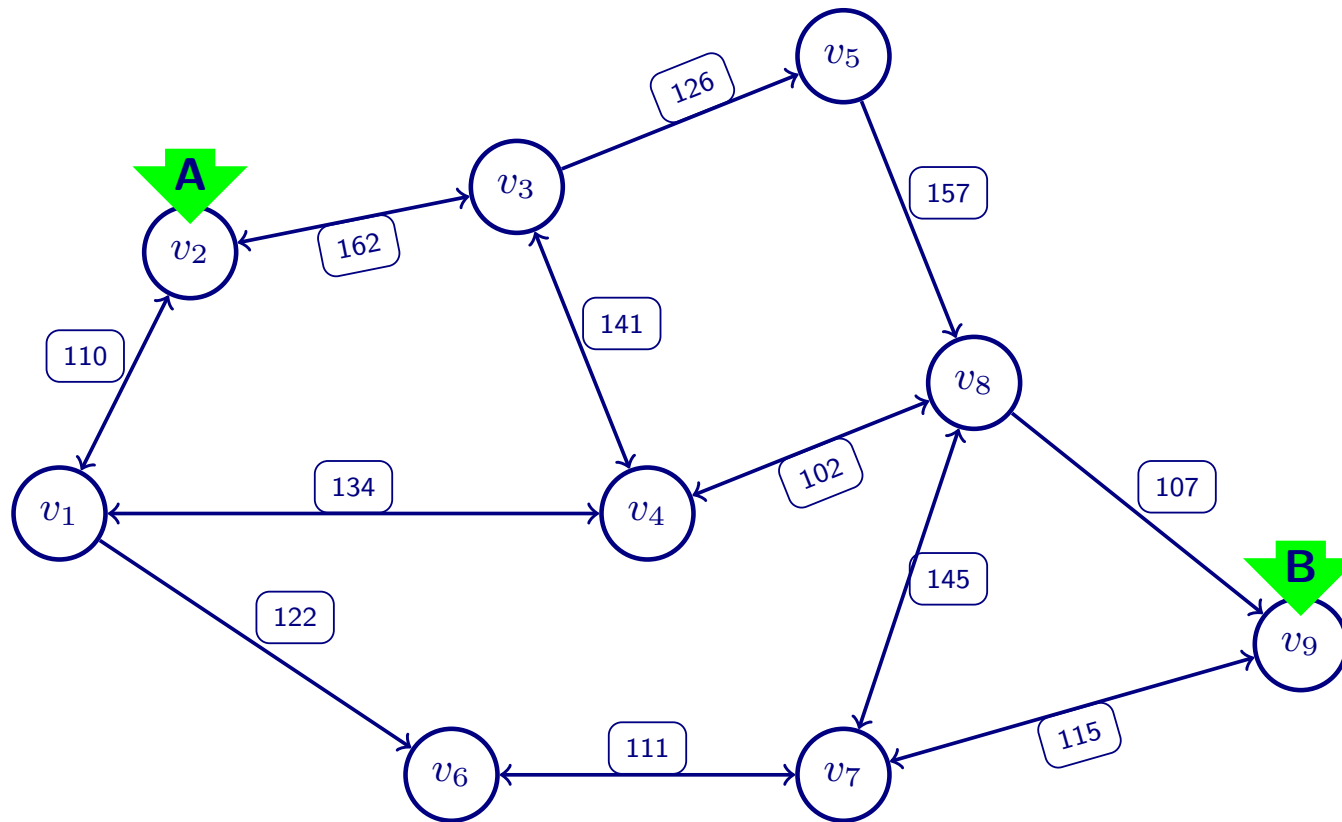


- ▶ Given a network – i.e. a directed graph – with a length for each arc, a start node A and a destination B...

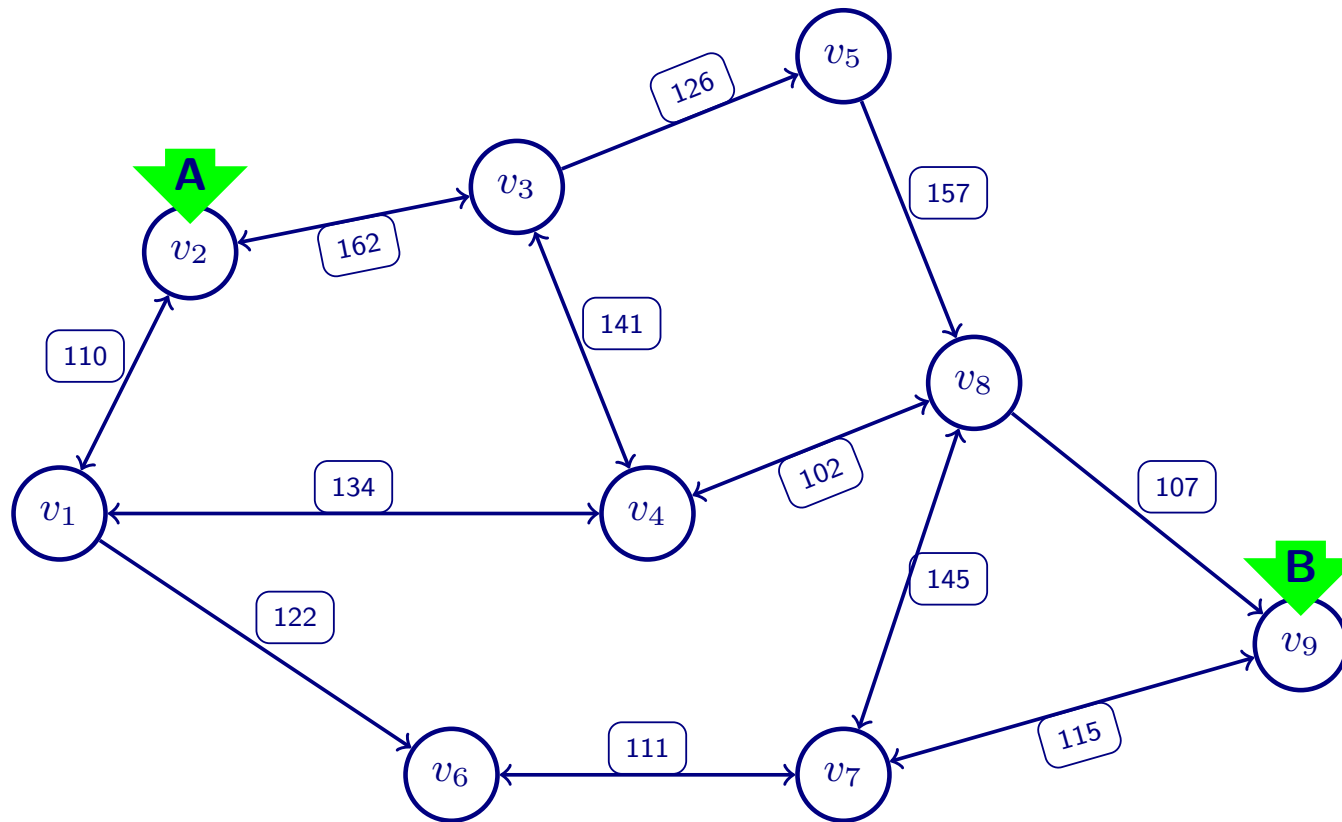
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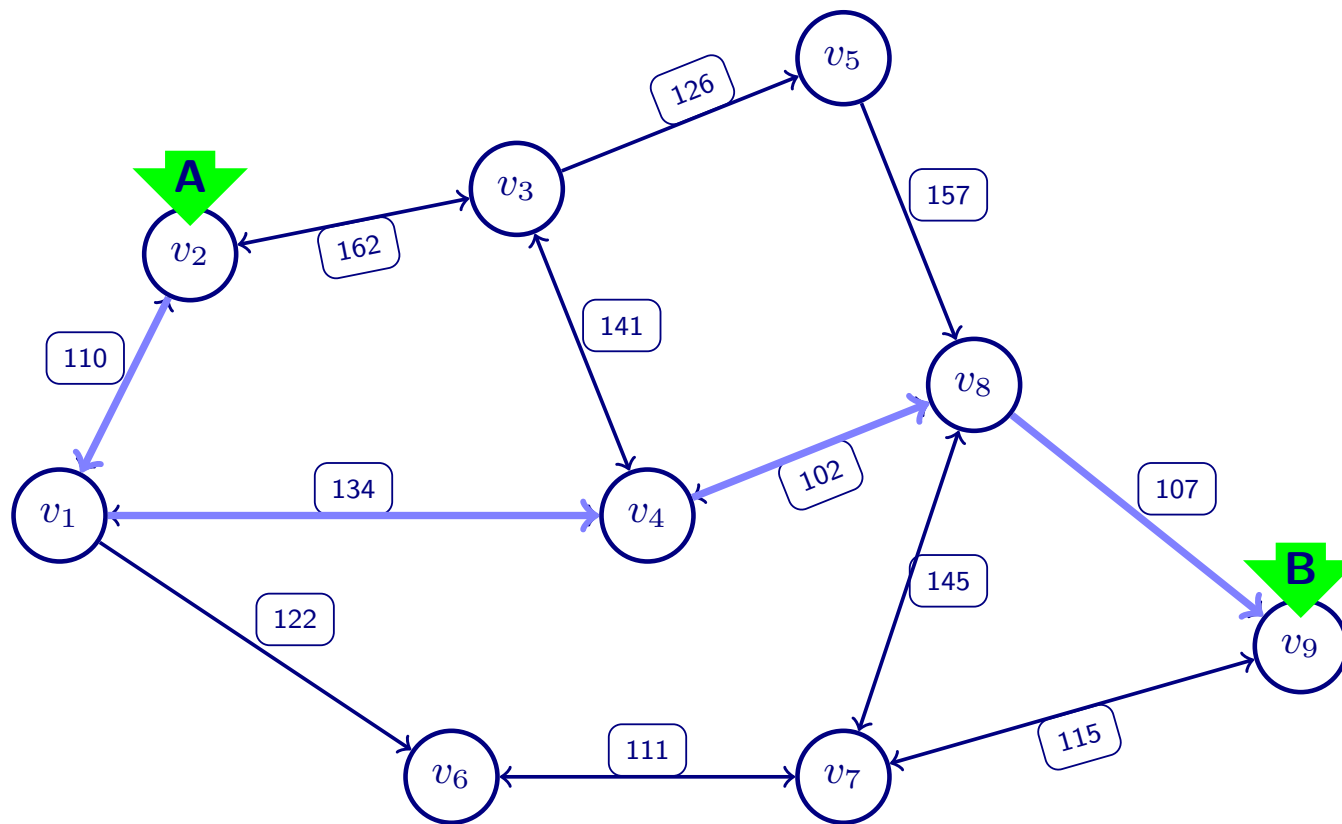


- ▶ Given a network – i.e. a directed graph – with a length for each arc, a start node A and a destination B...
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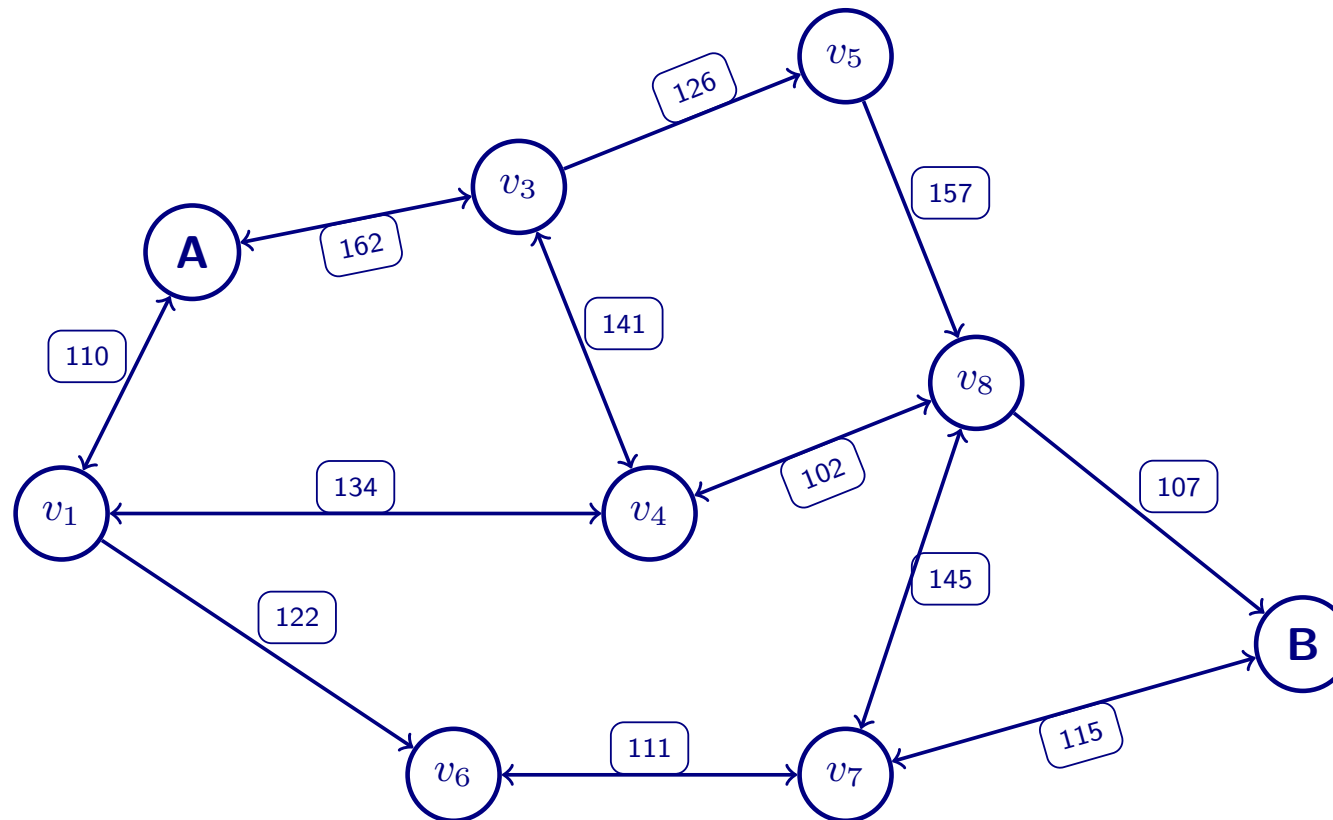


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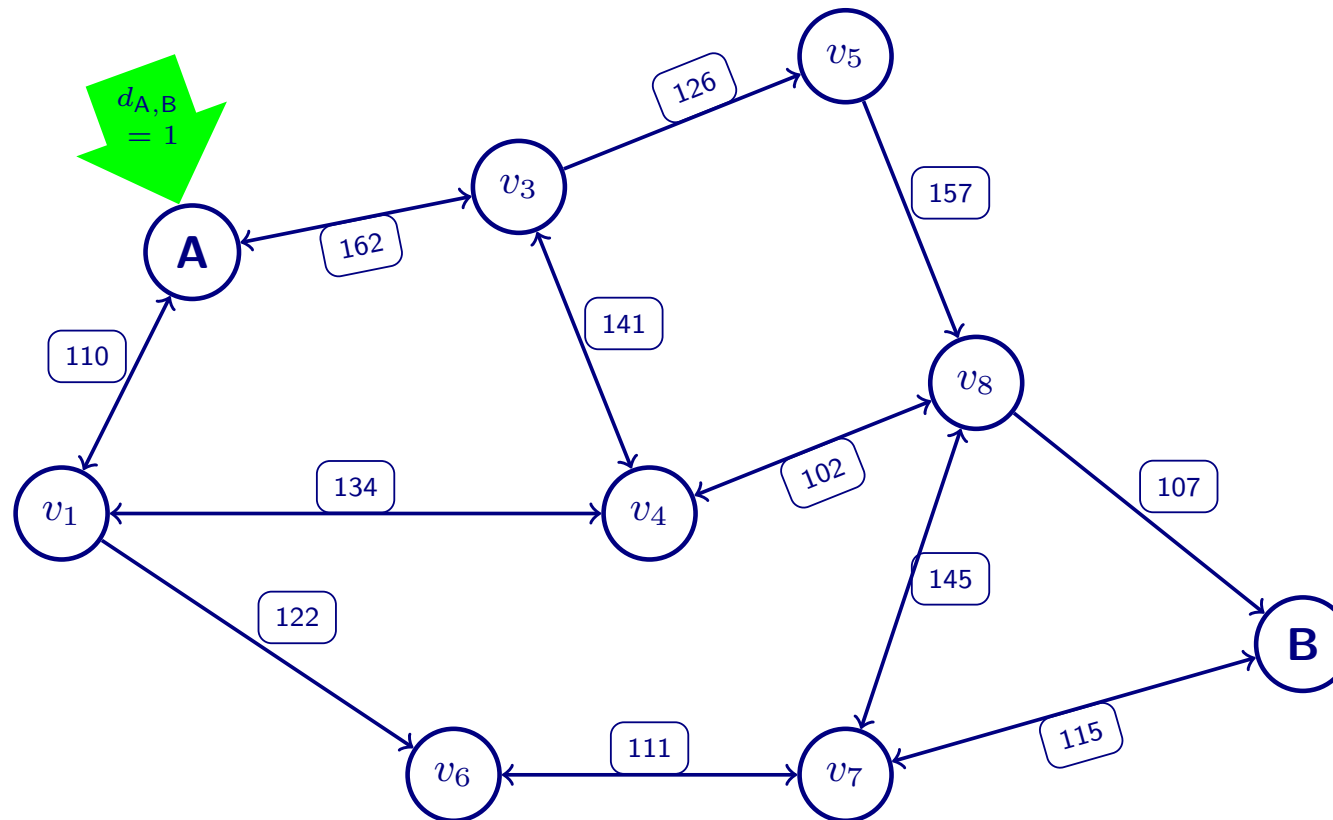


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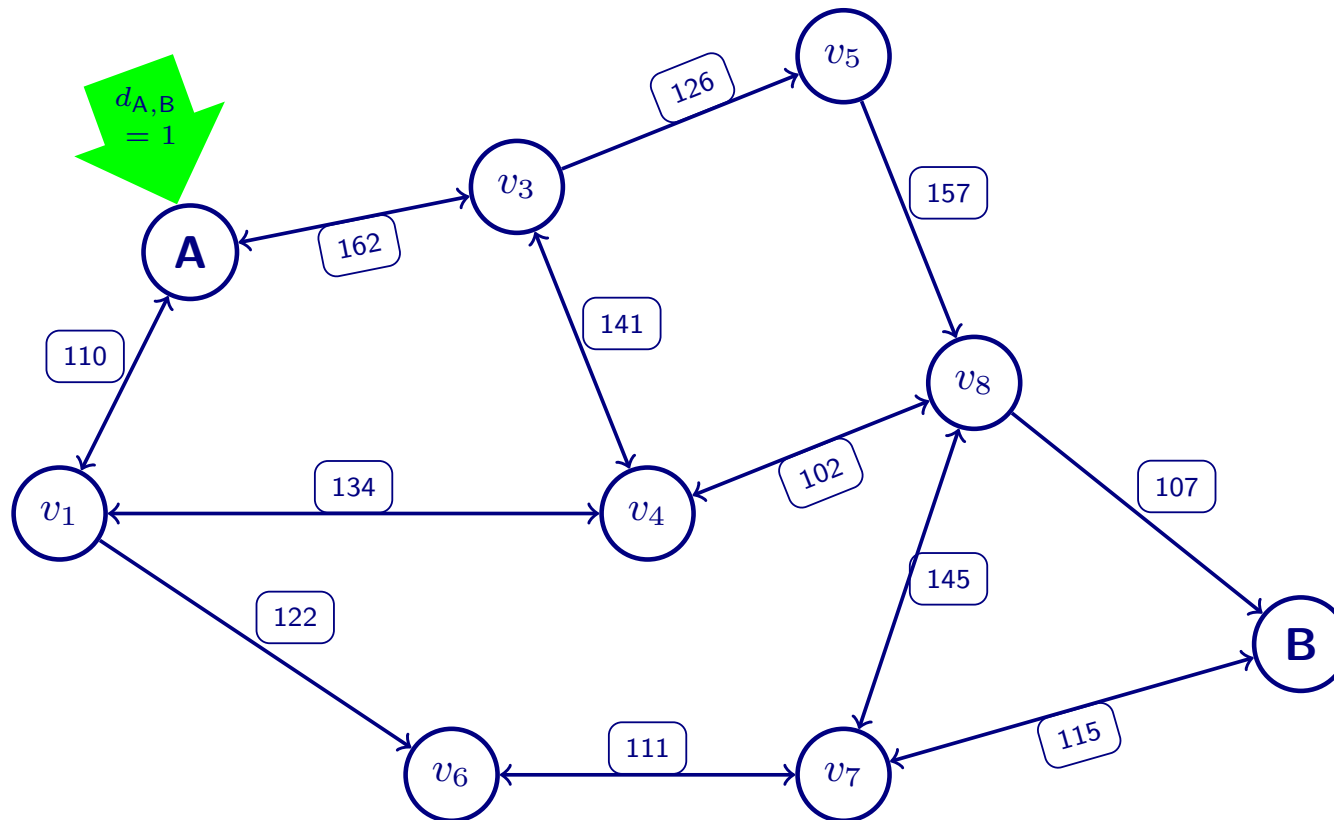
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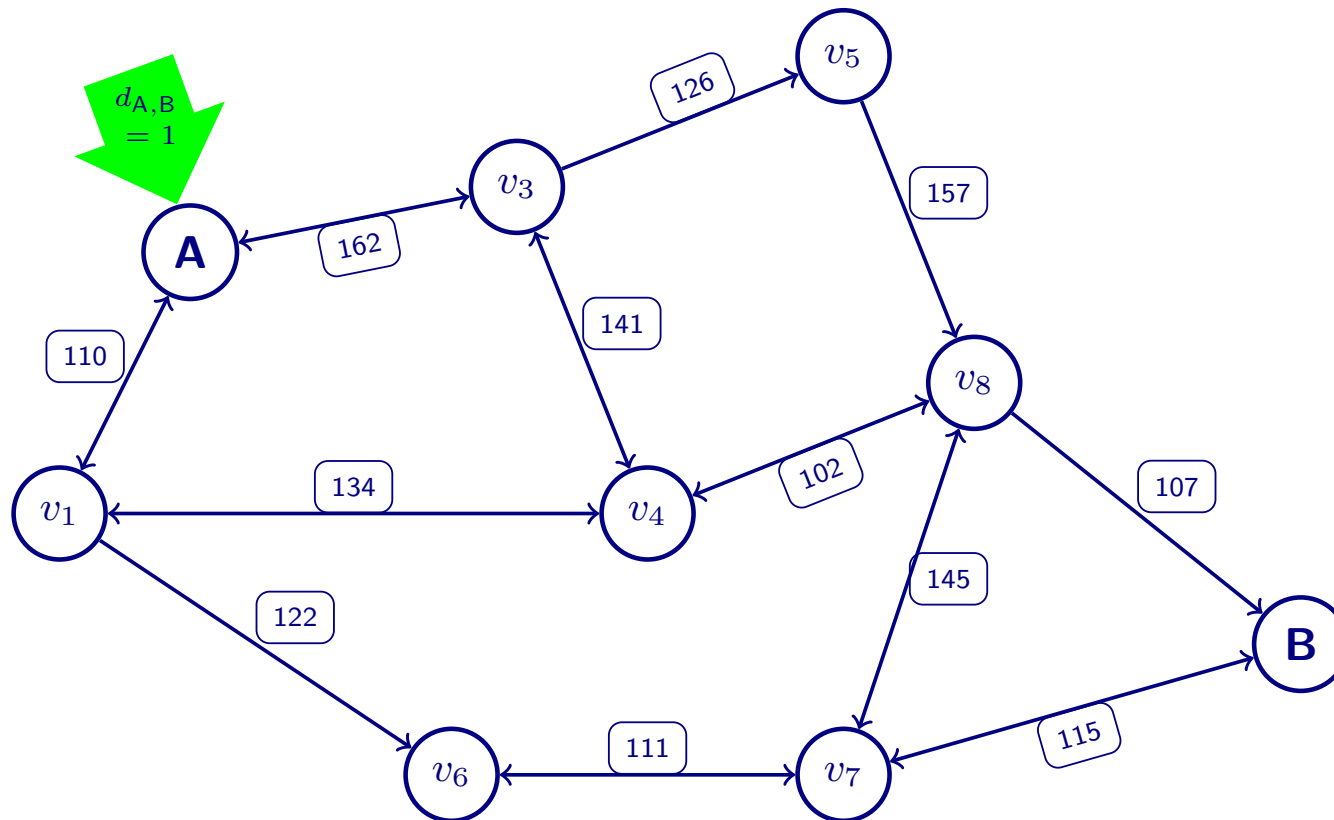
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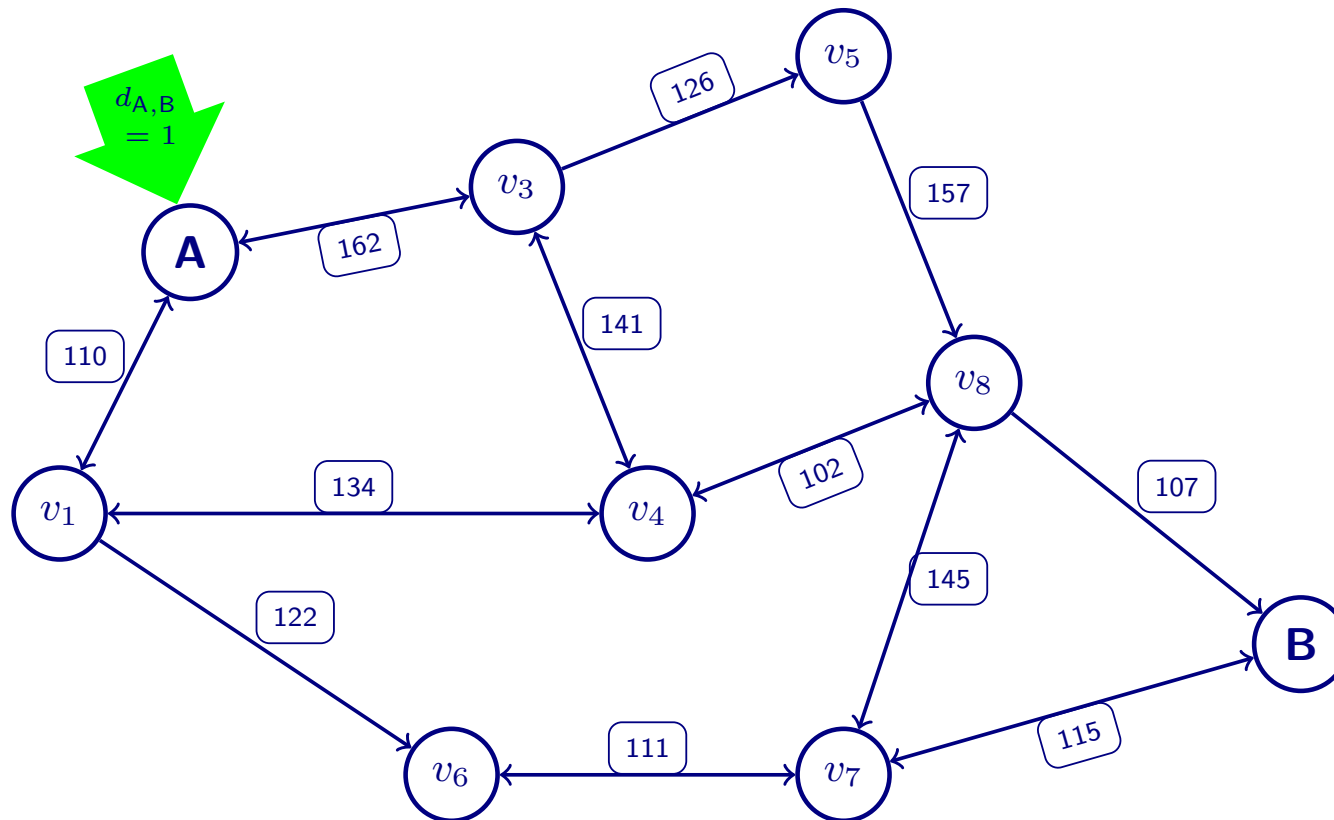
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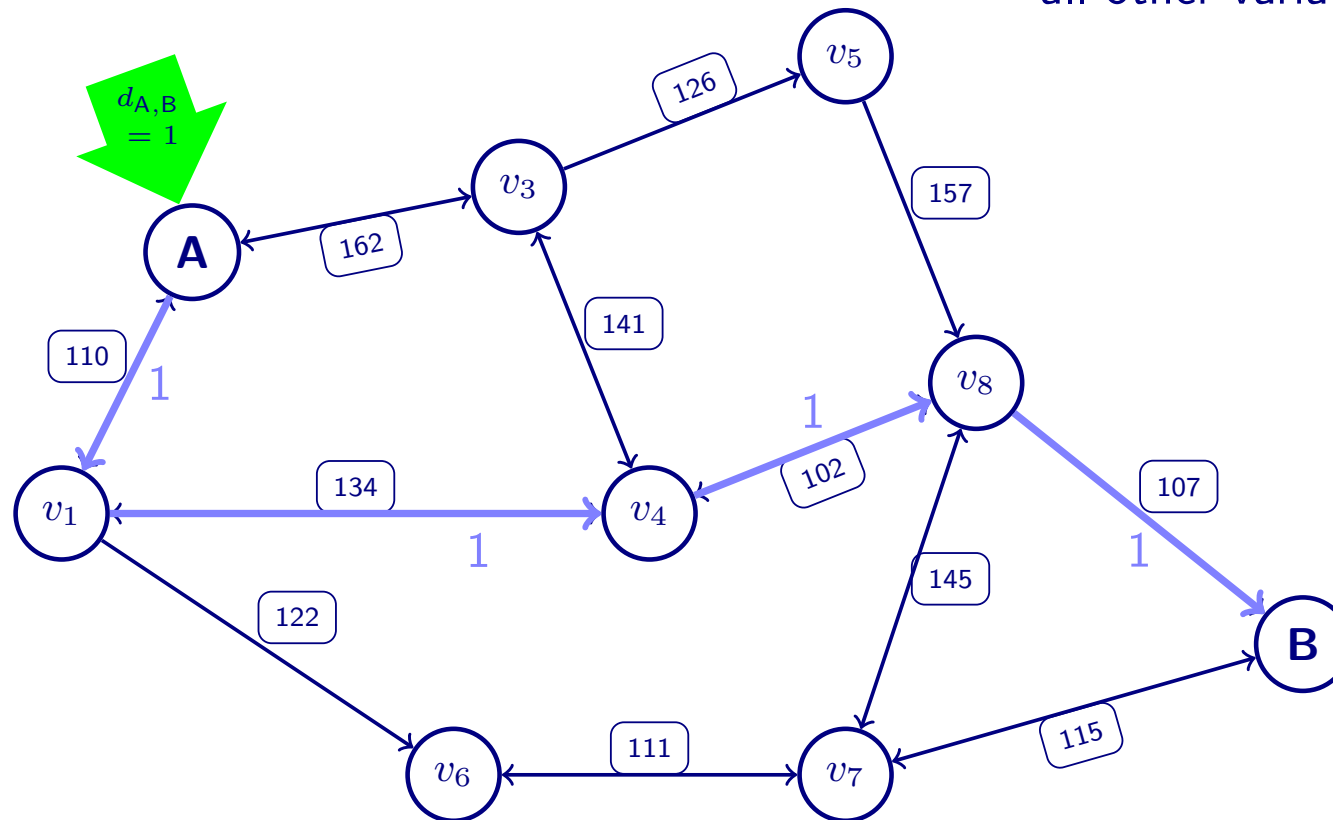


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➔ Optimal solution:

$y_{(A,v_1)} = y_{(v_1,v_4)} = y_{(v_4,v_8)} = y_{(v_8,B)} = 1$ ,  
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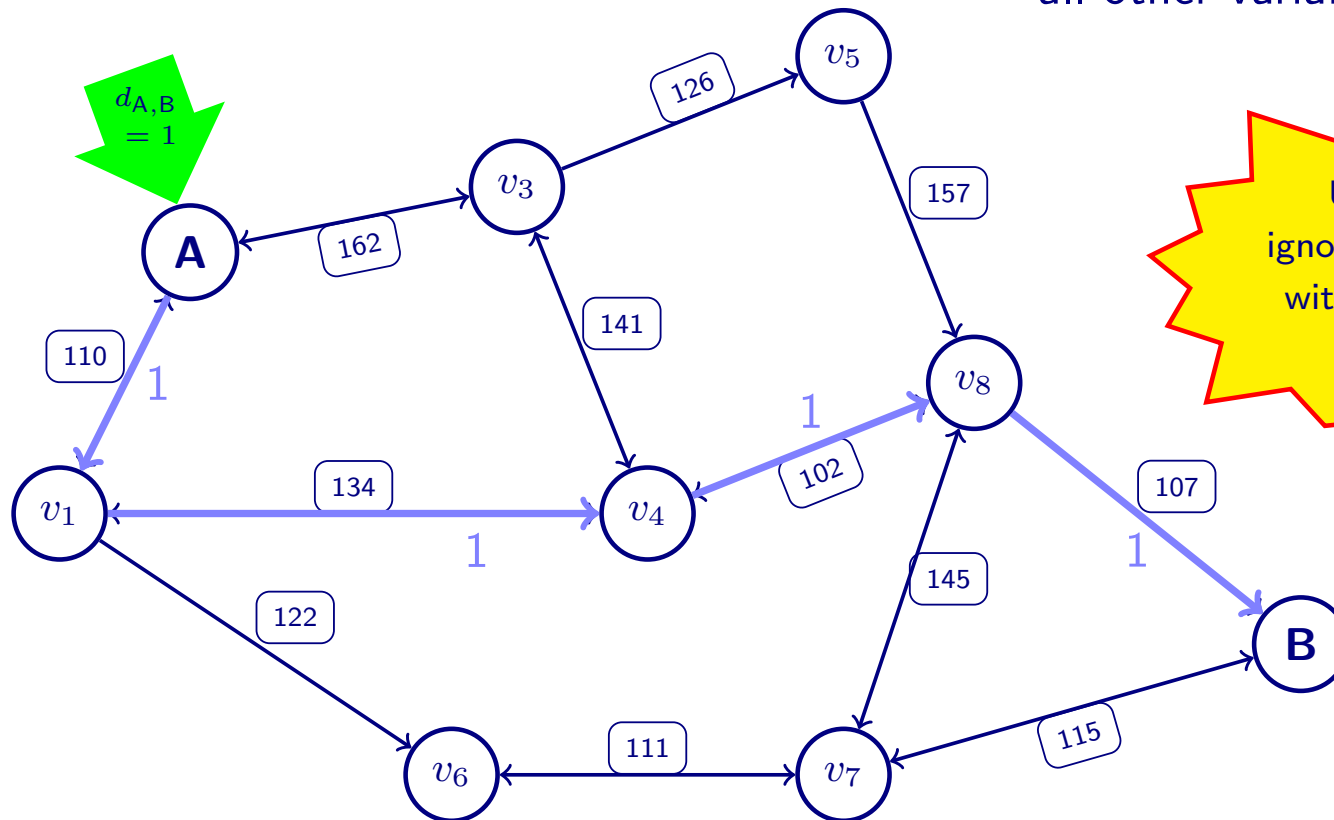
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Unsplittability can be ignored if the model is solved with the simplex algorithm → linear program!

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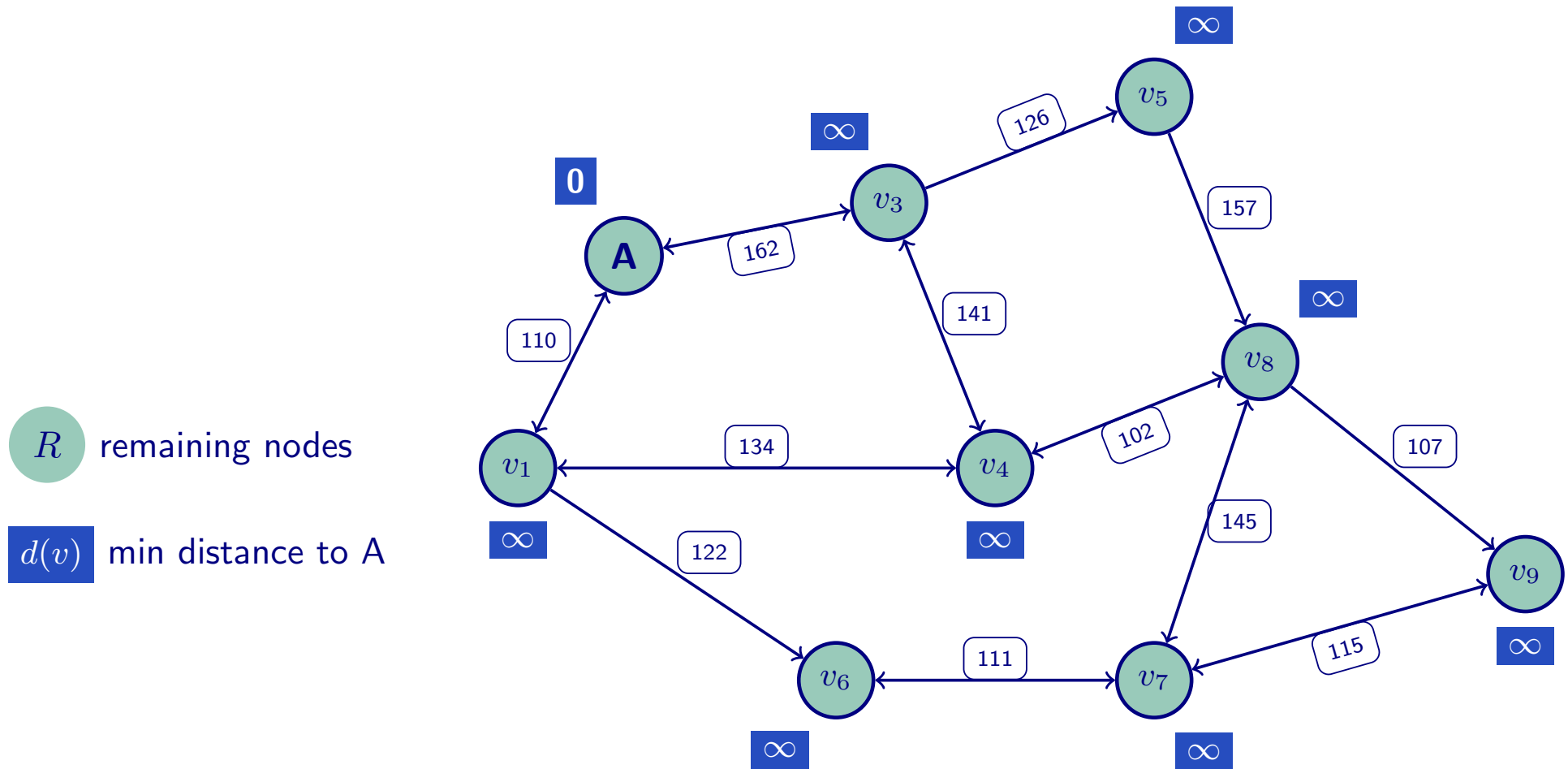
Edsger Wybe Dijkstra  
(1930–2002)

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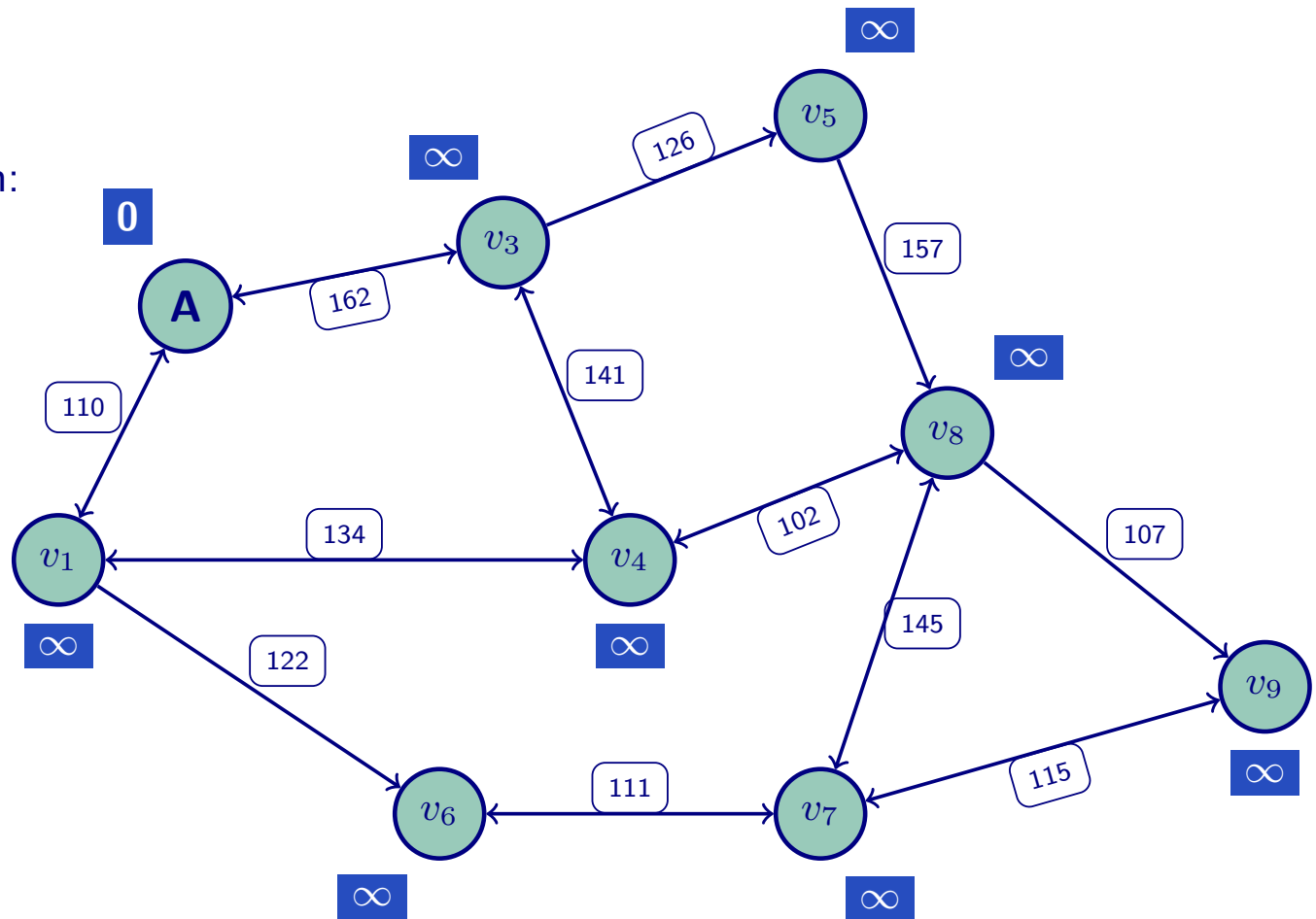
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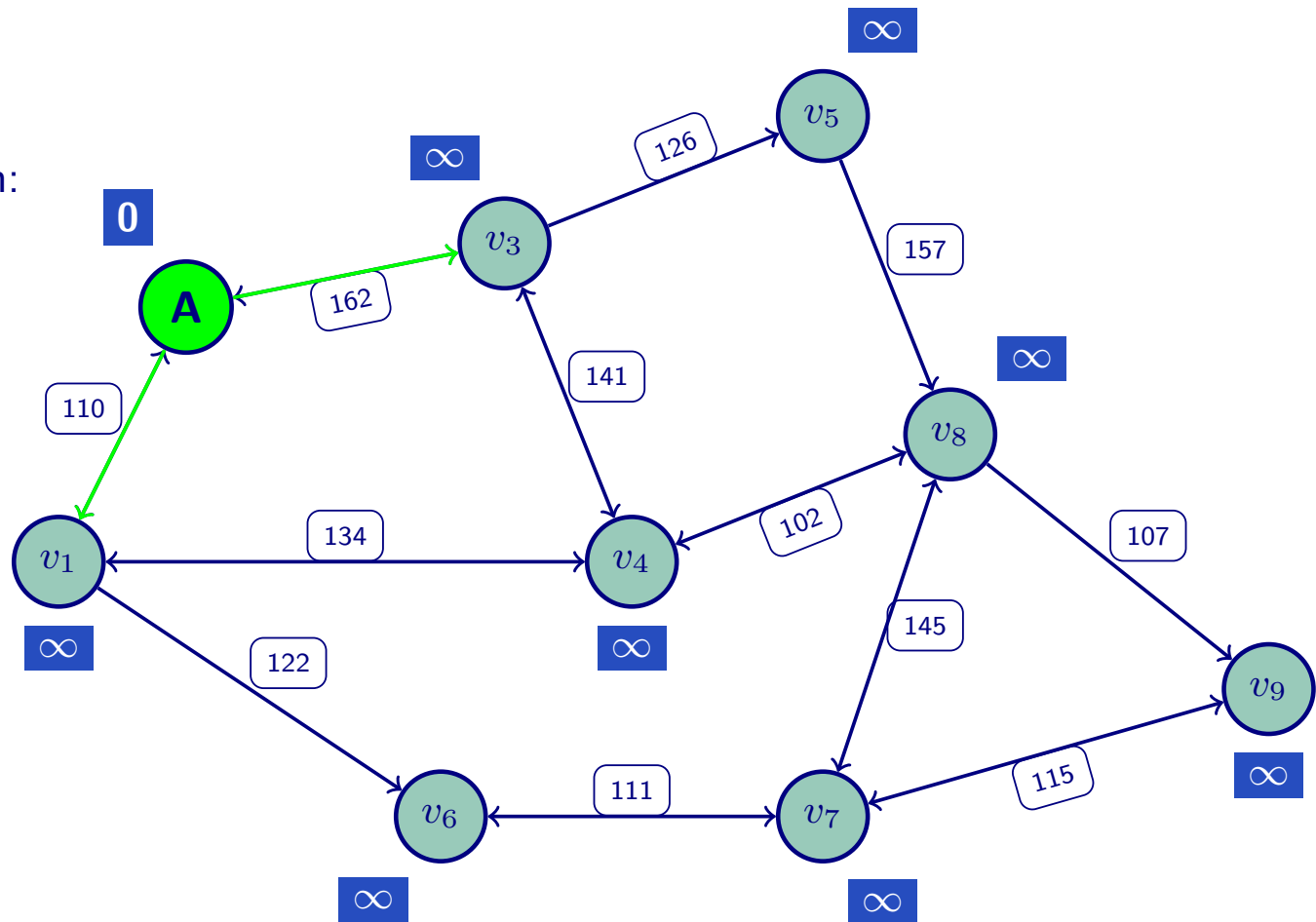
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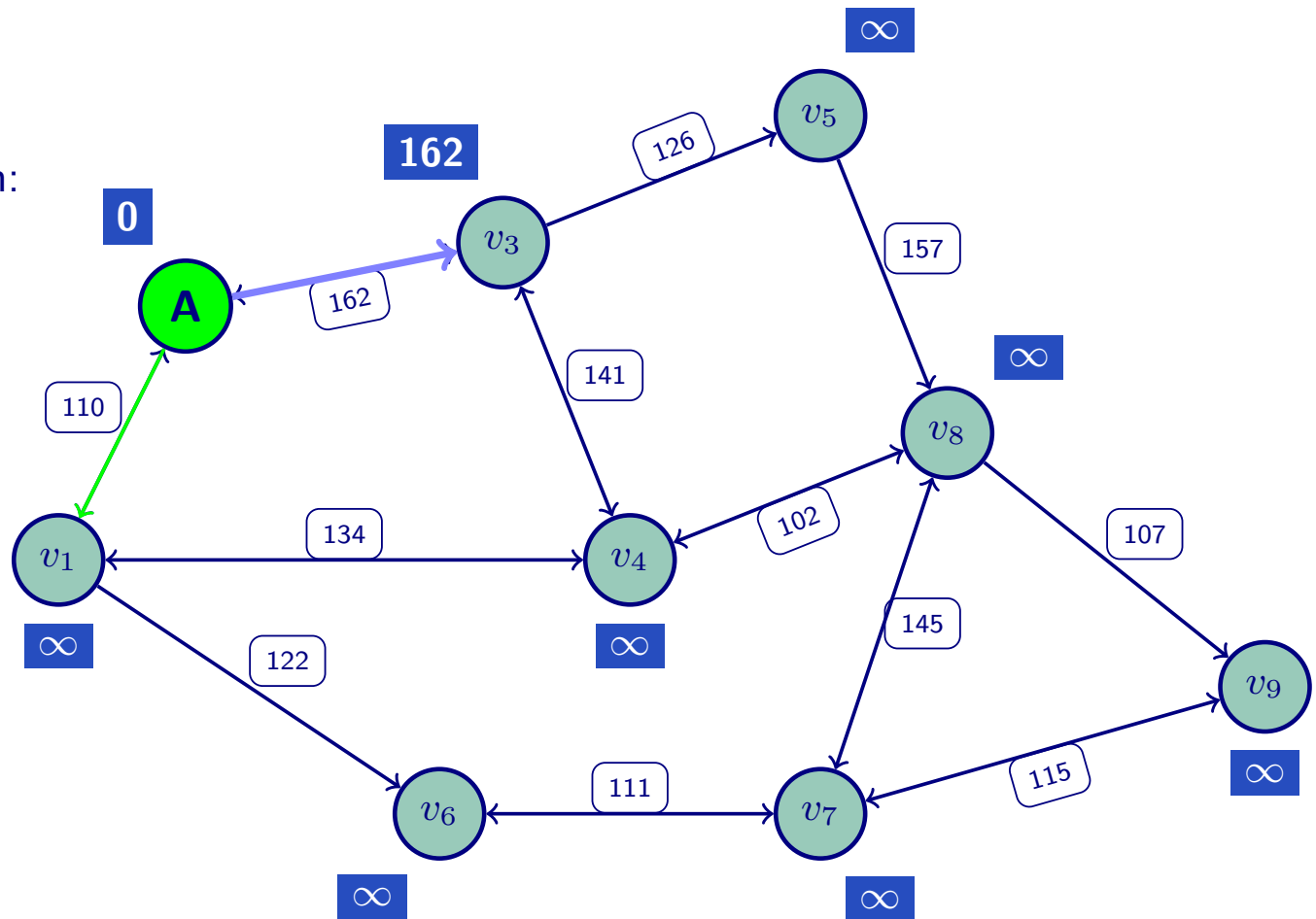
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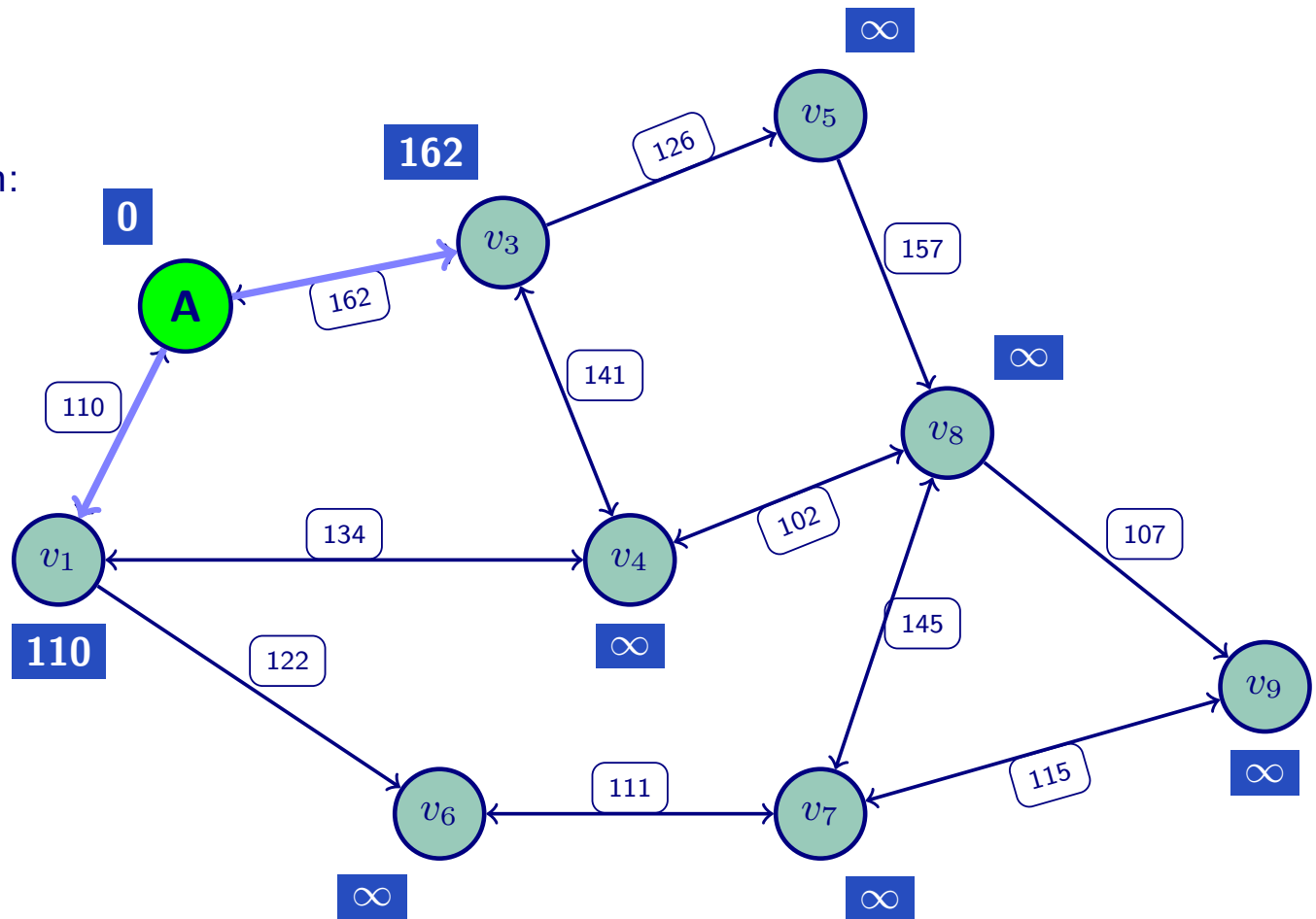
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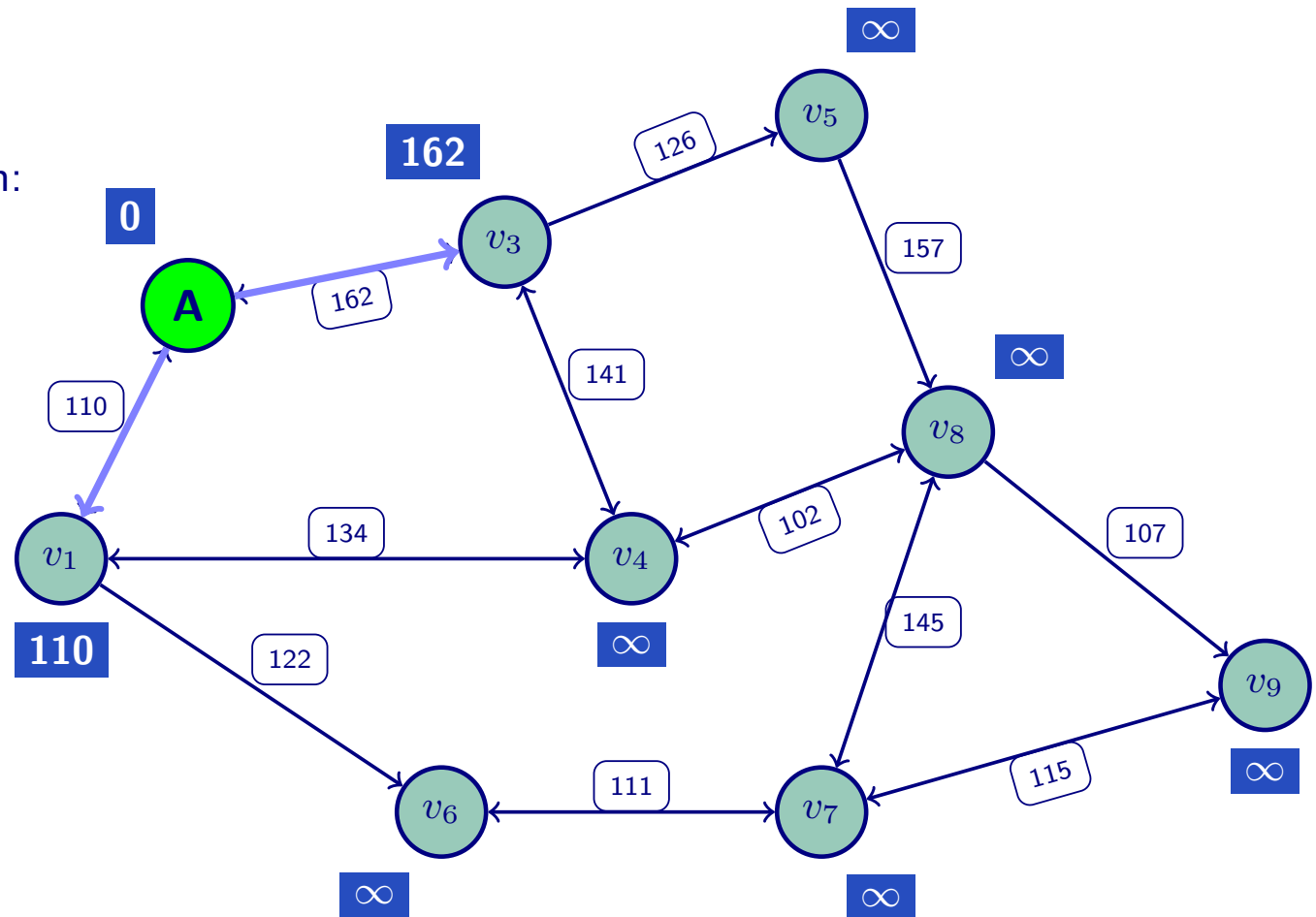
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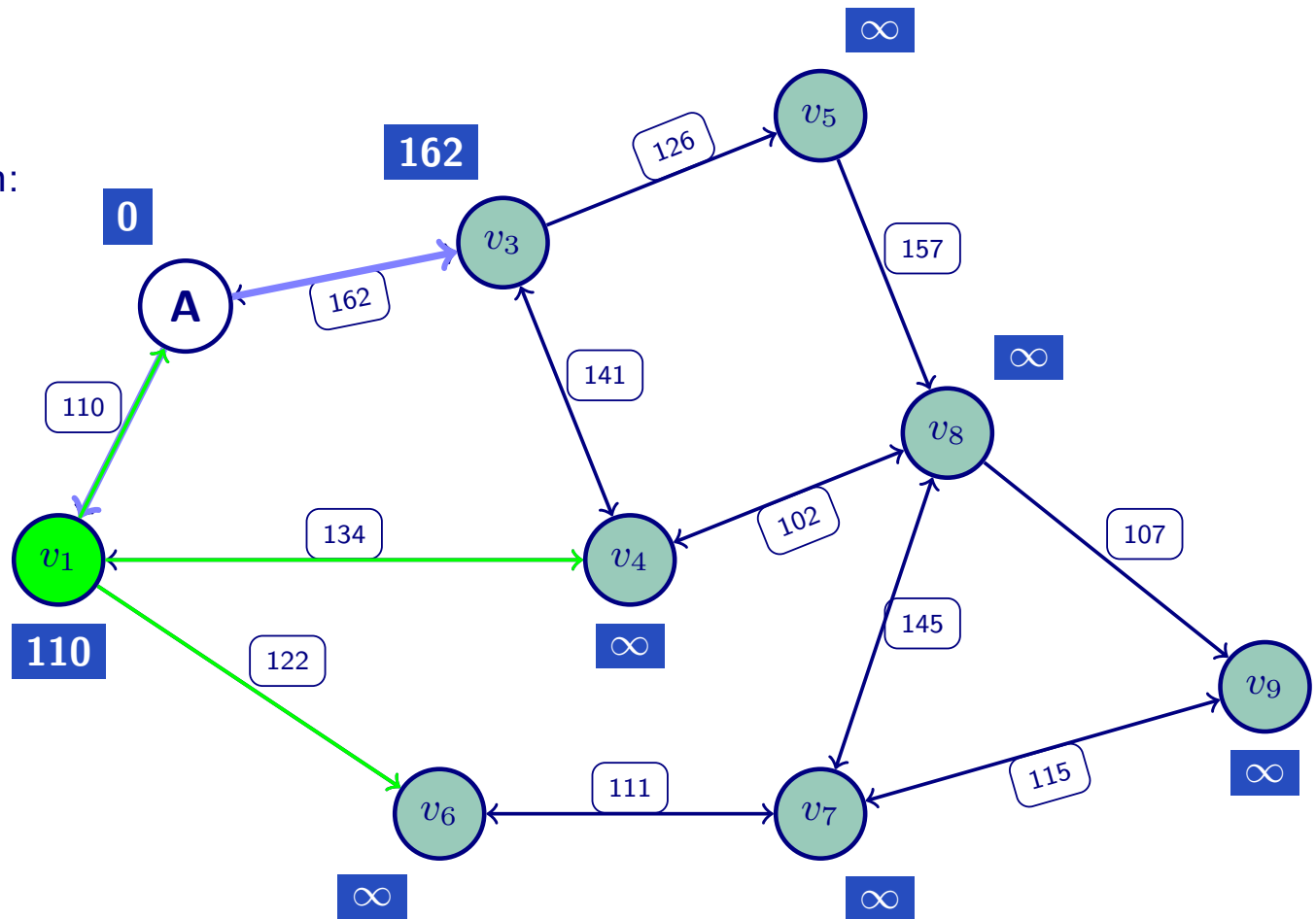
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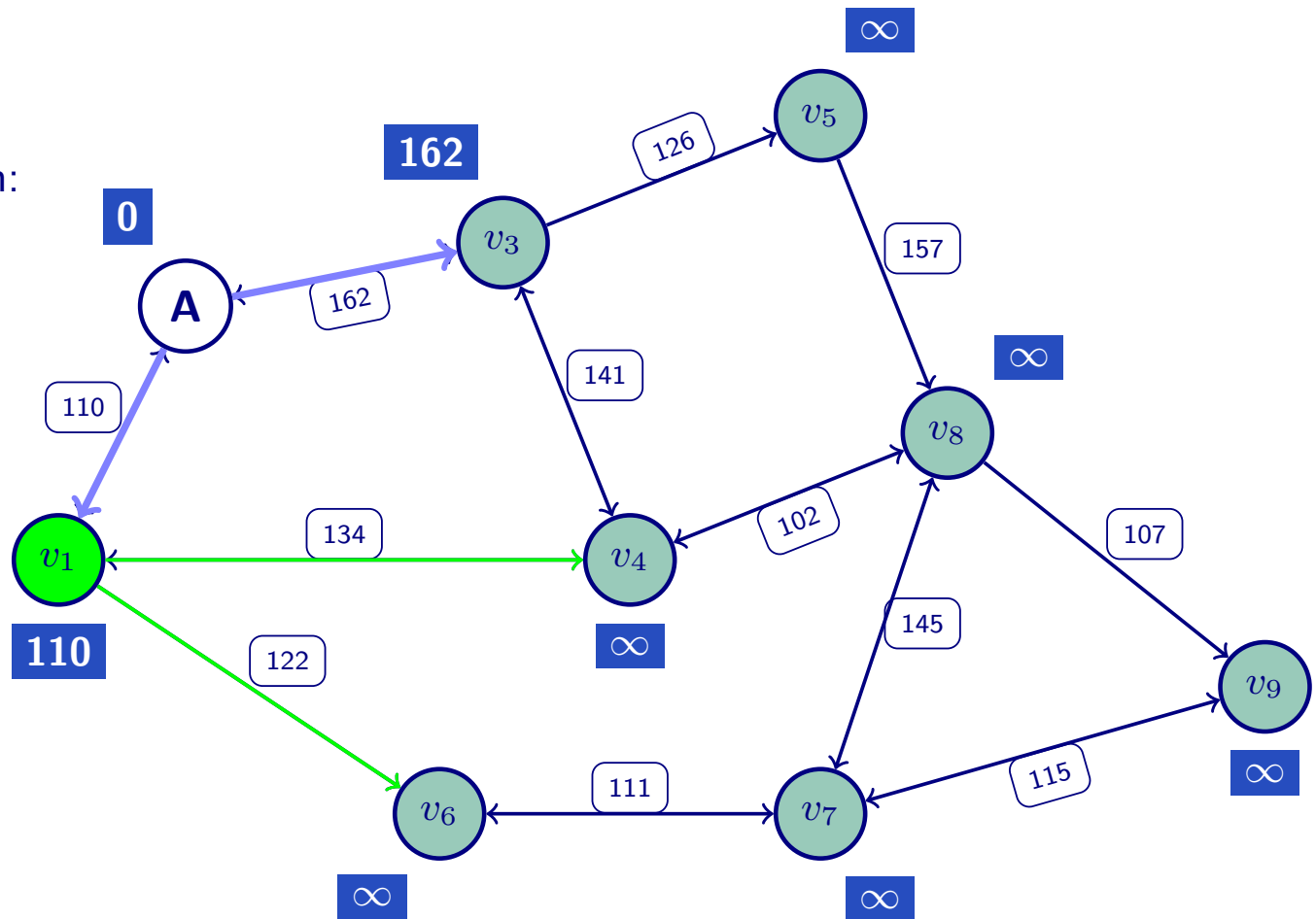
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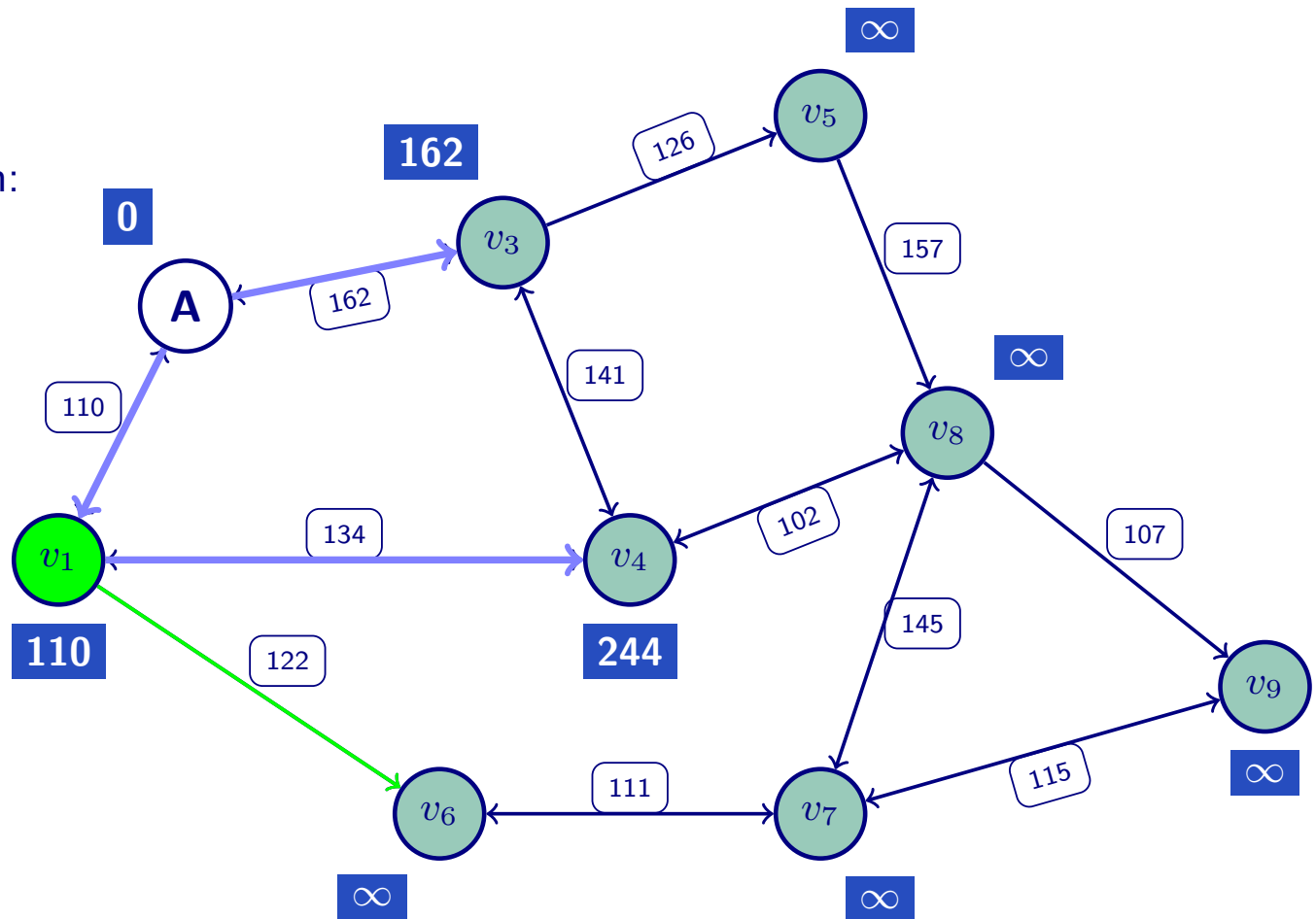
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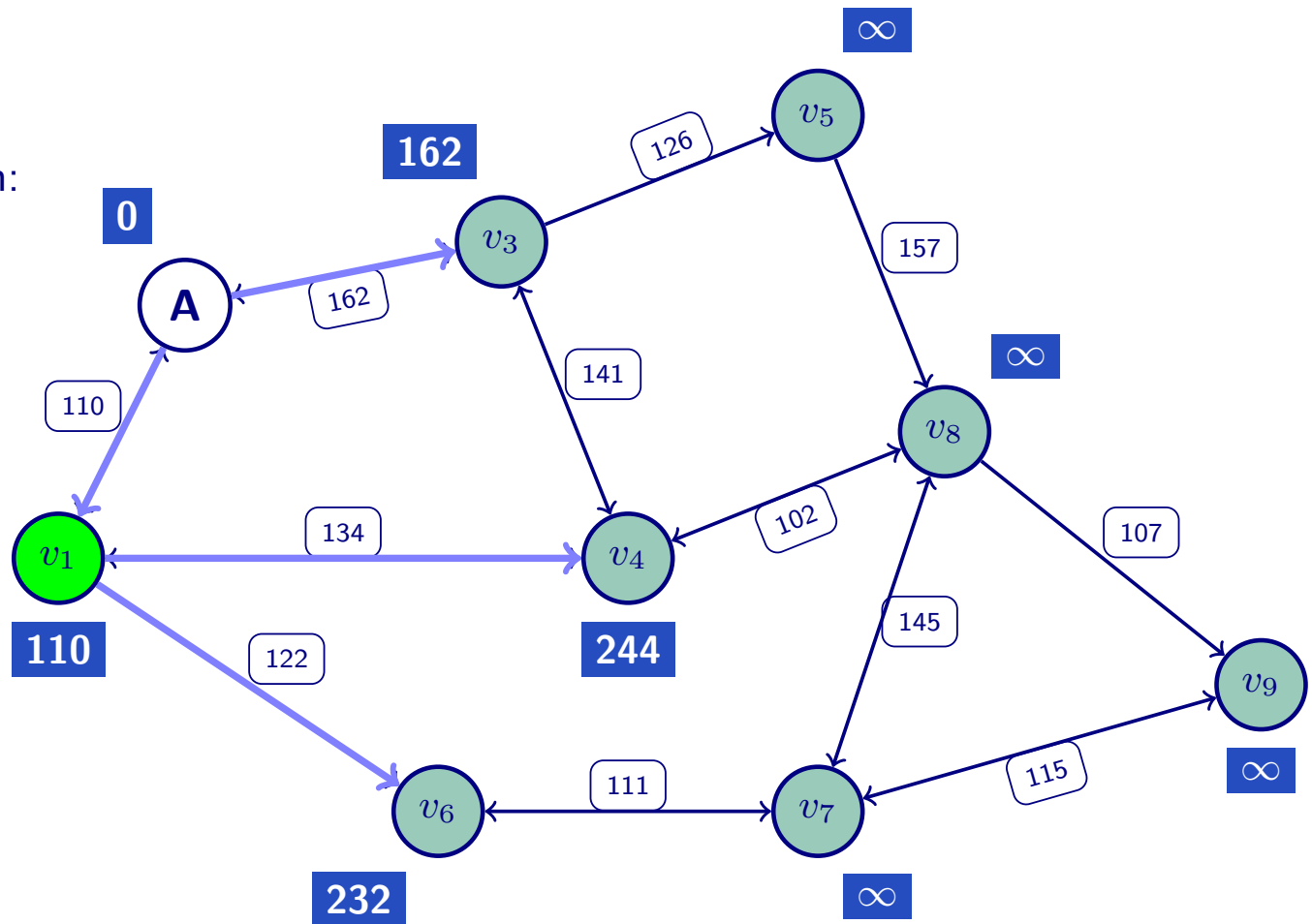
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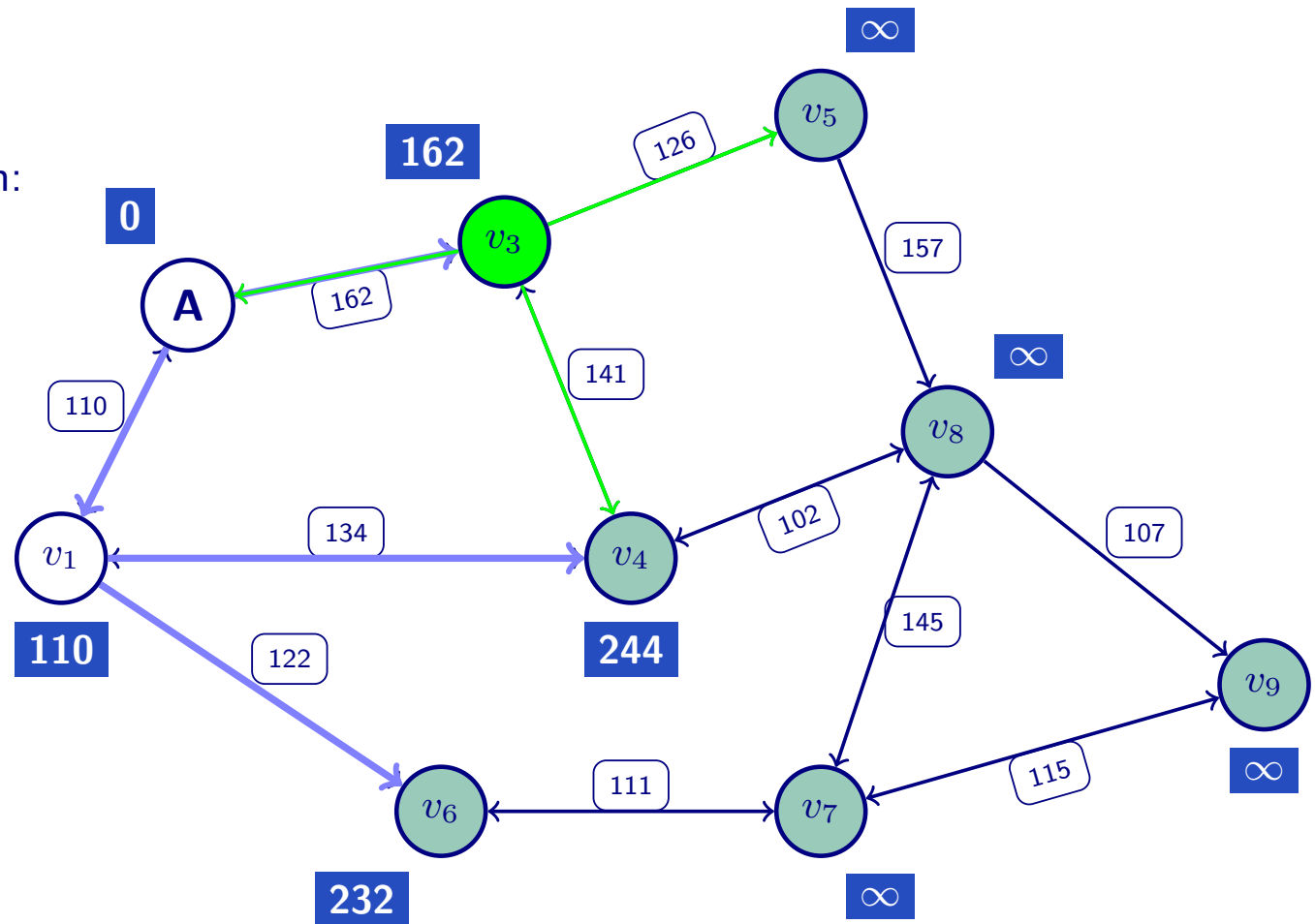
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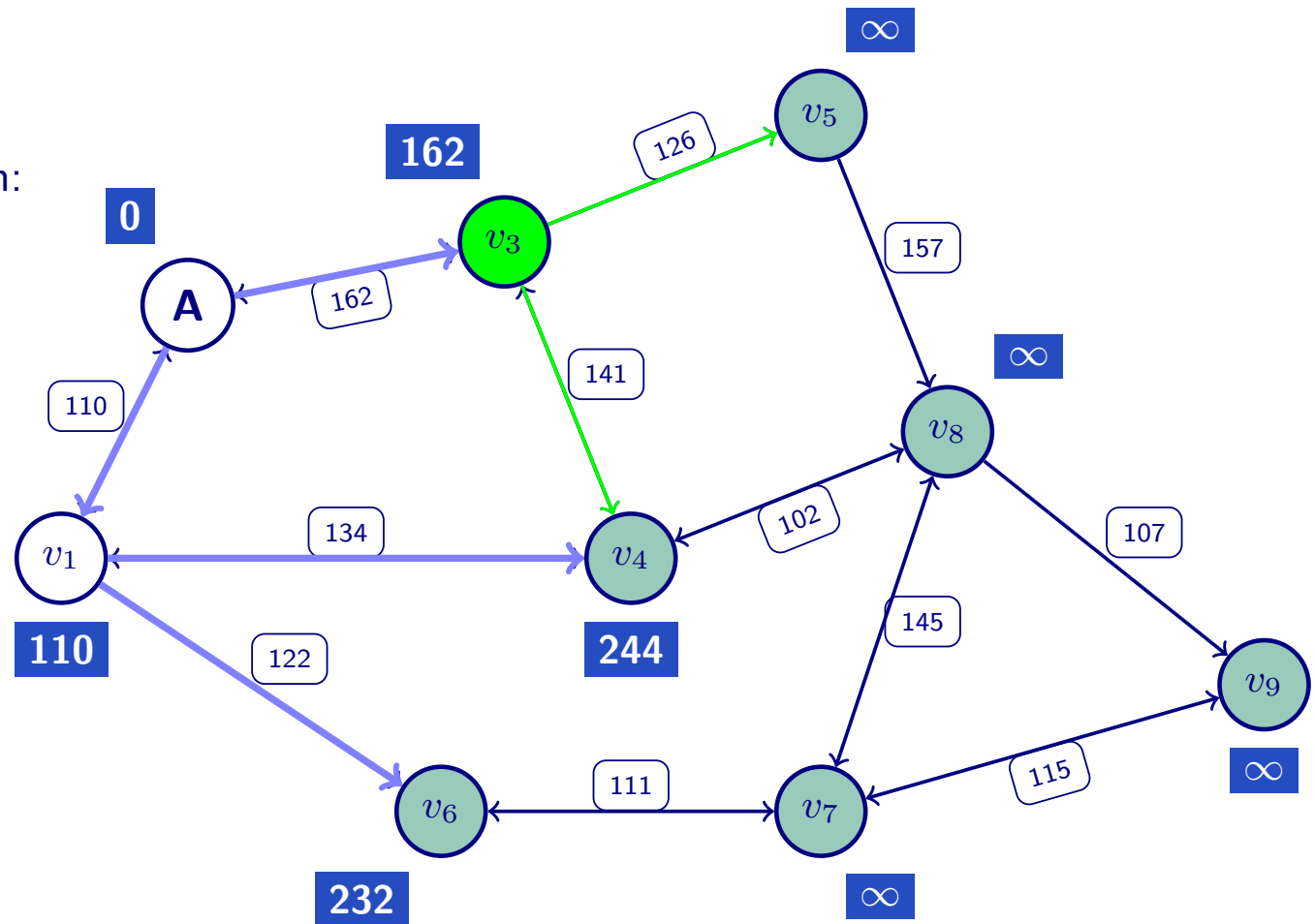
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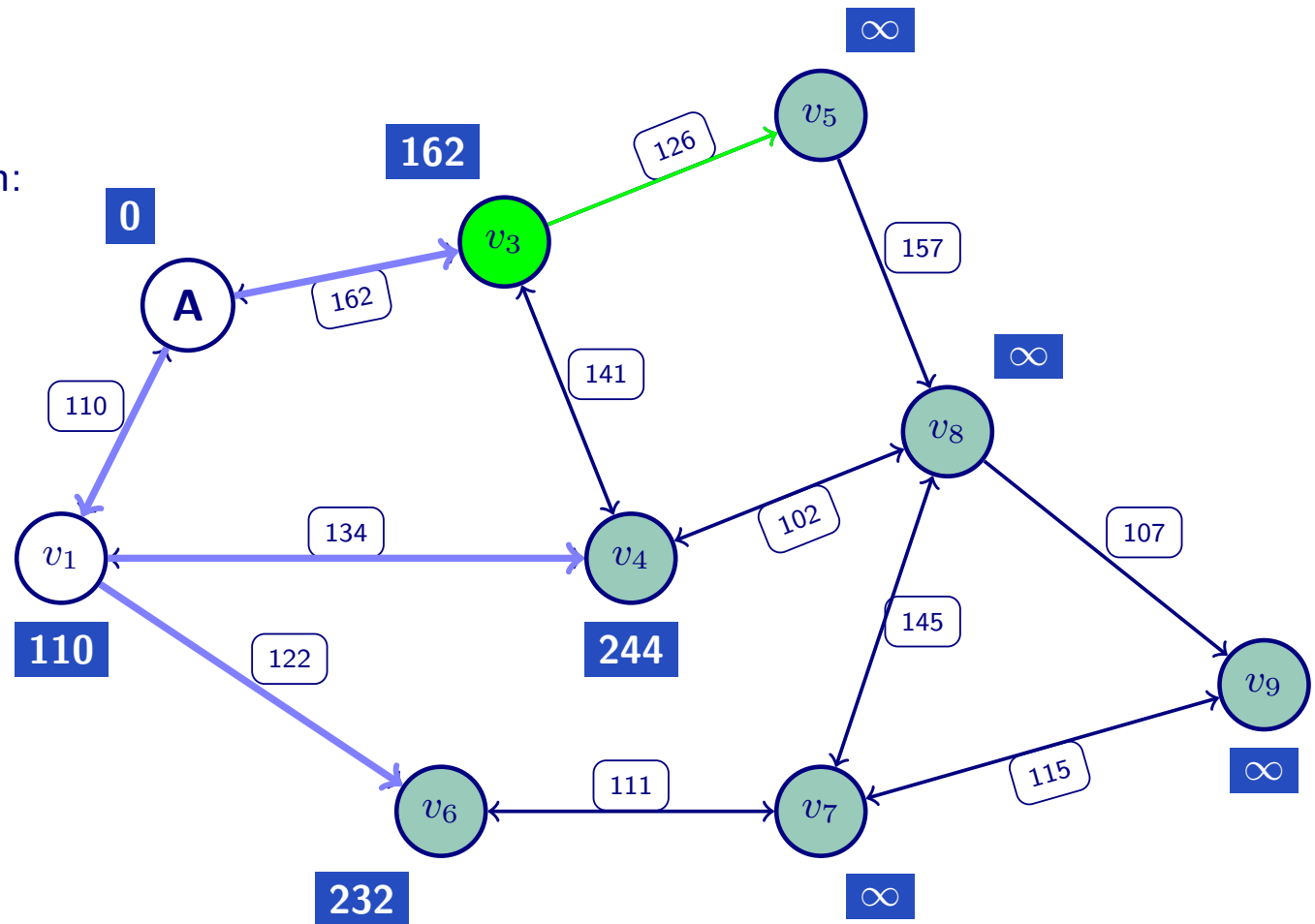
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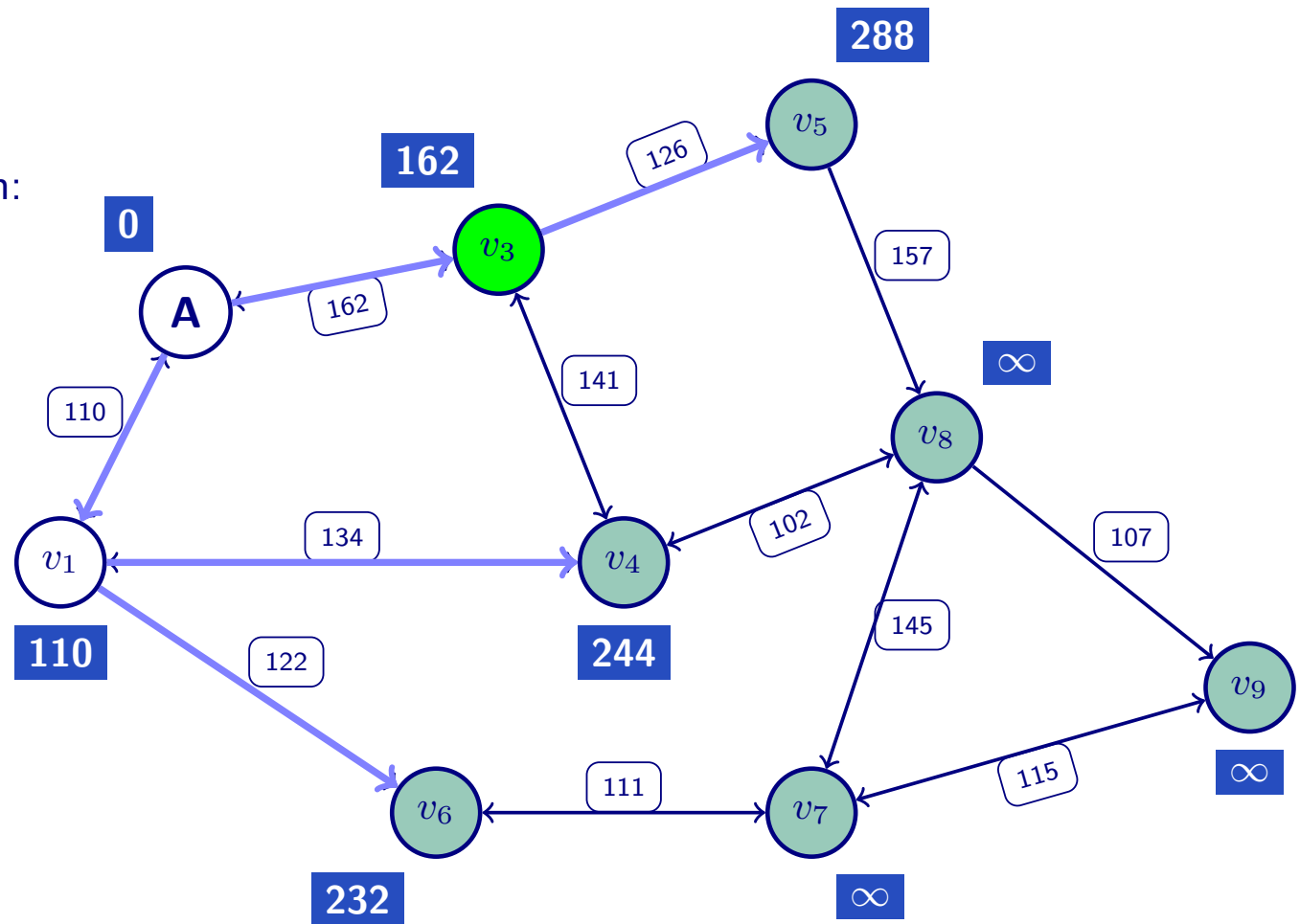
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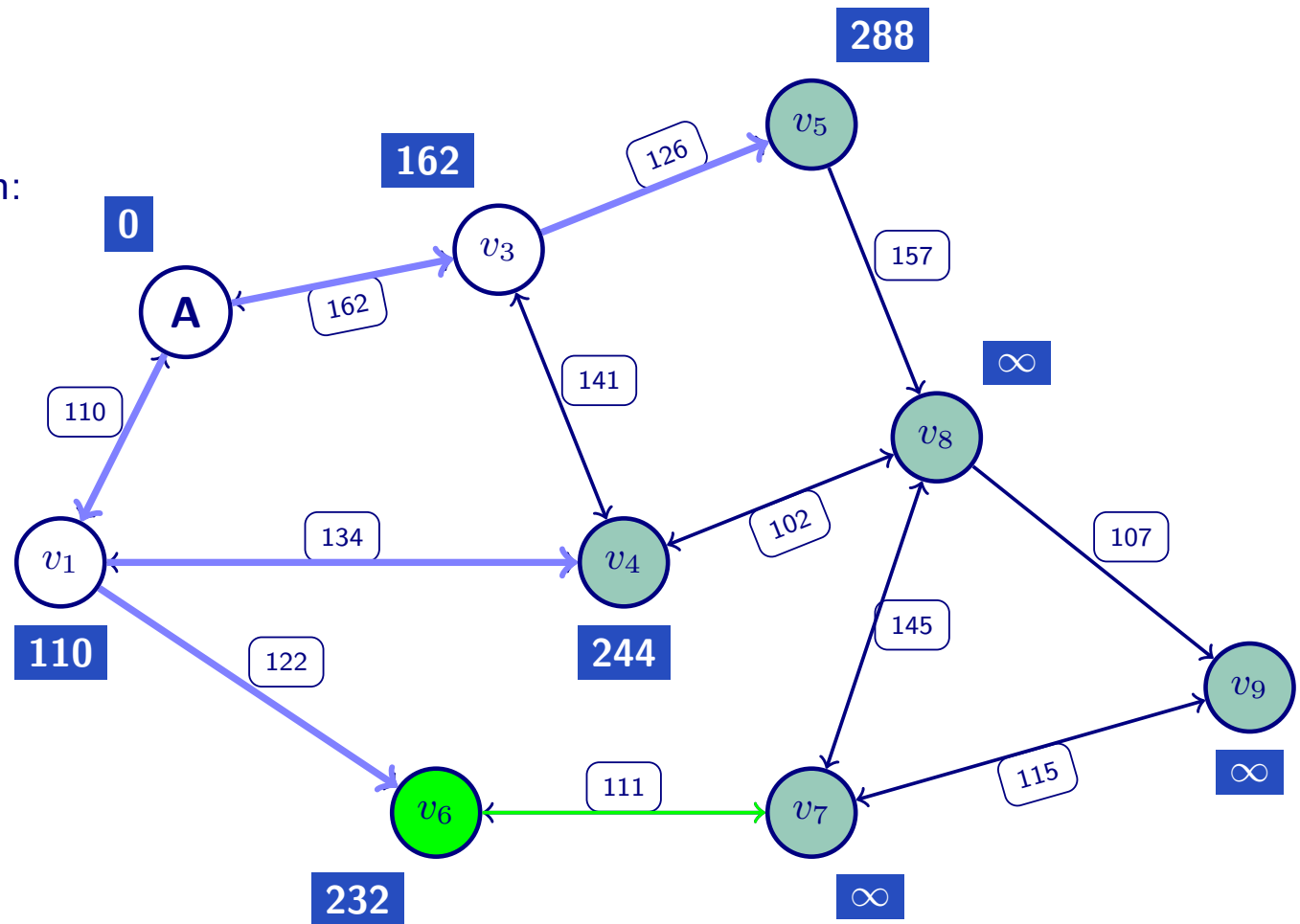
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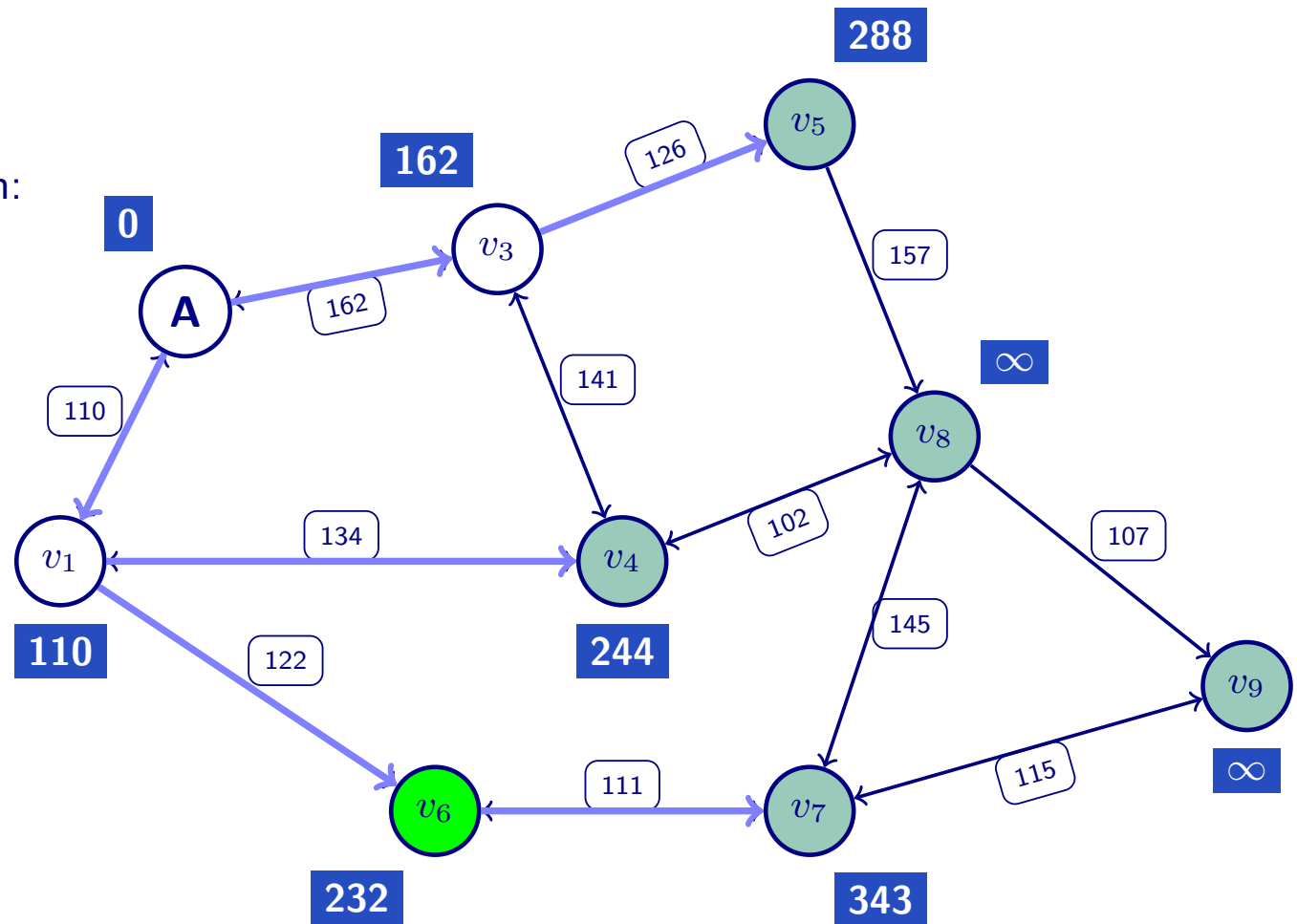
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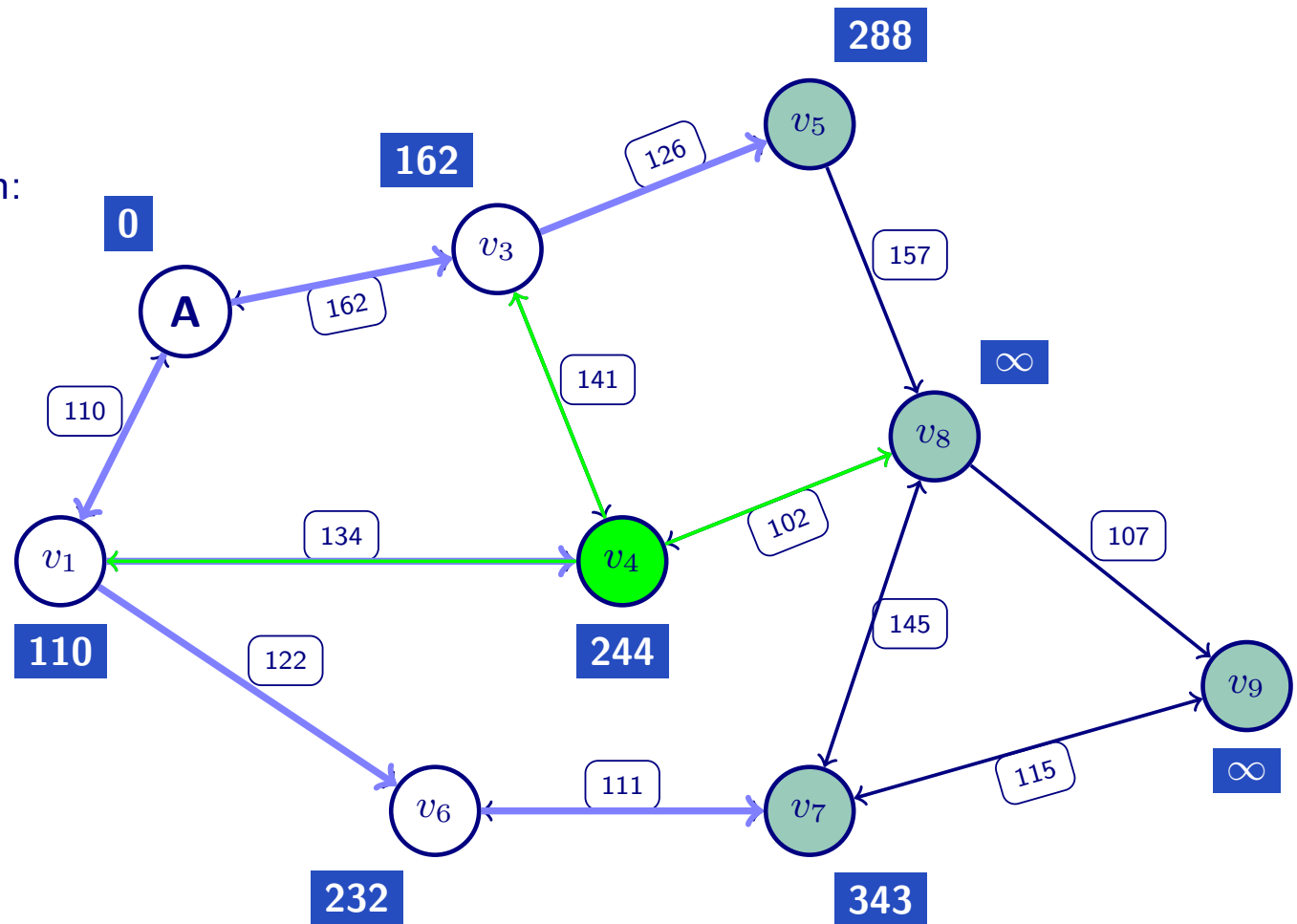
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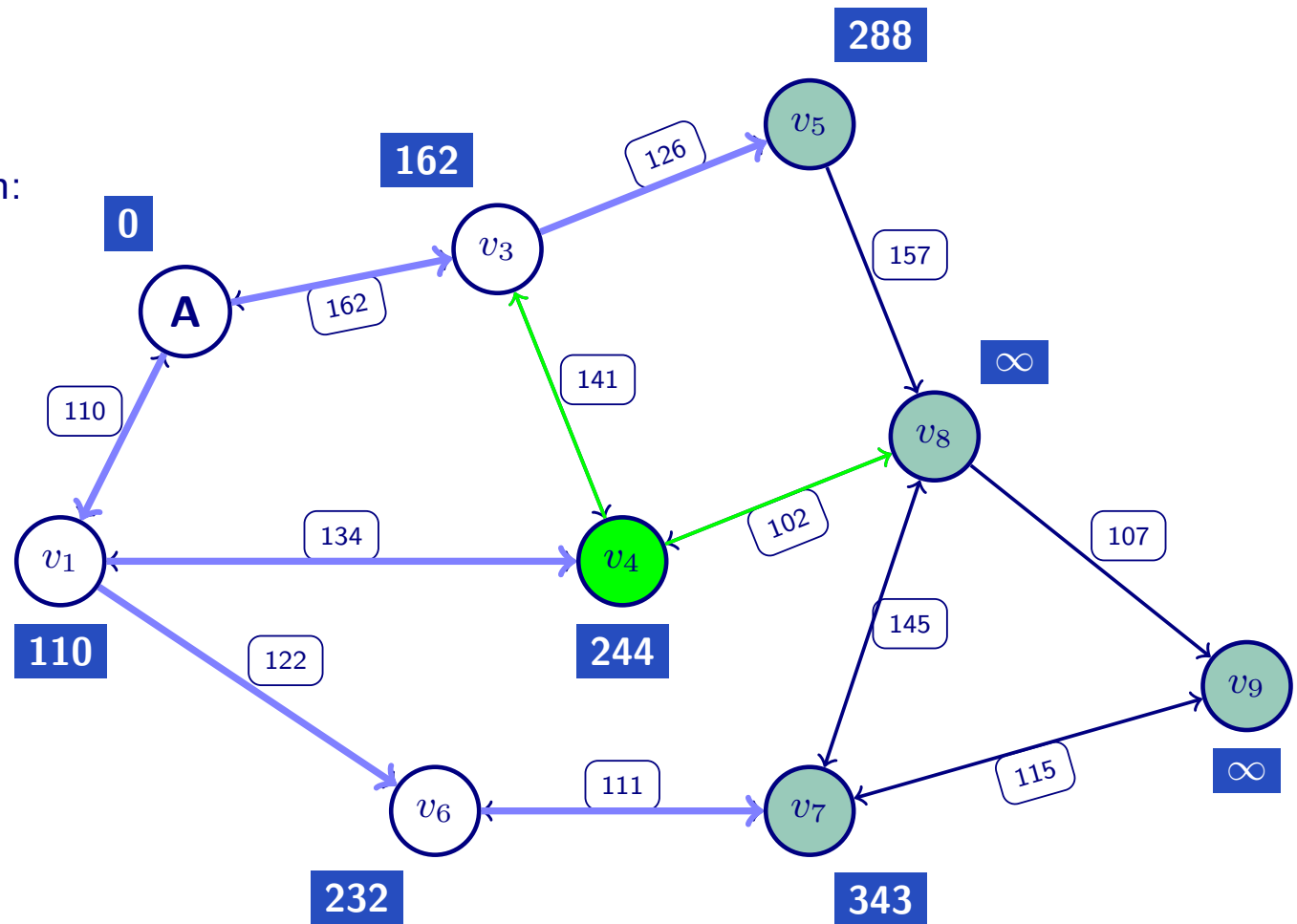
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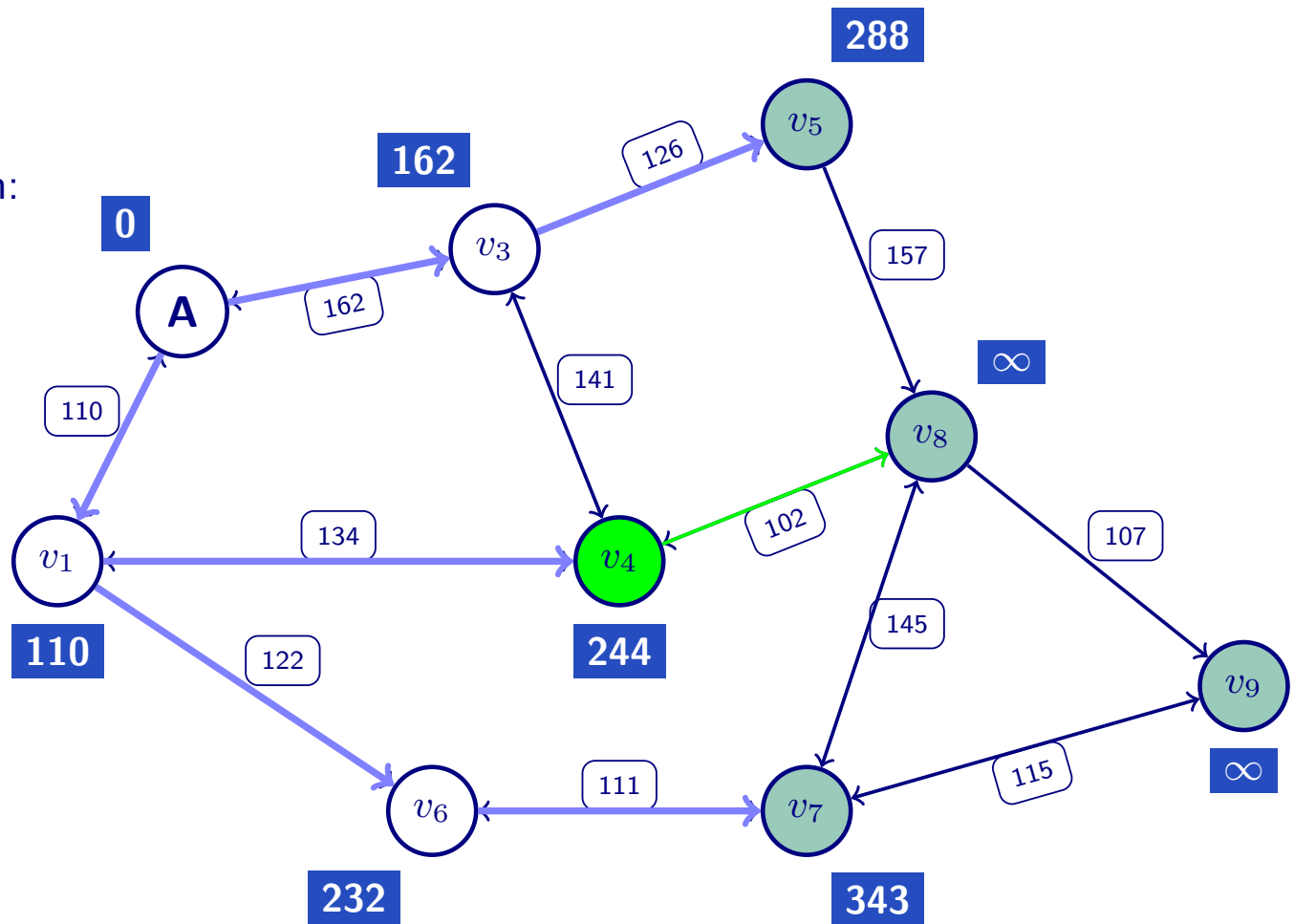
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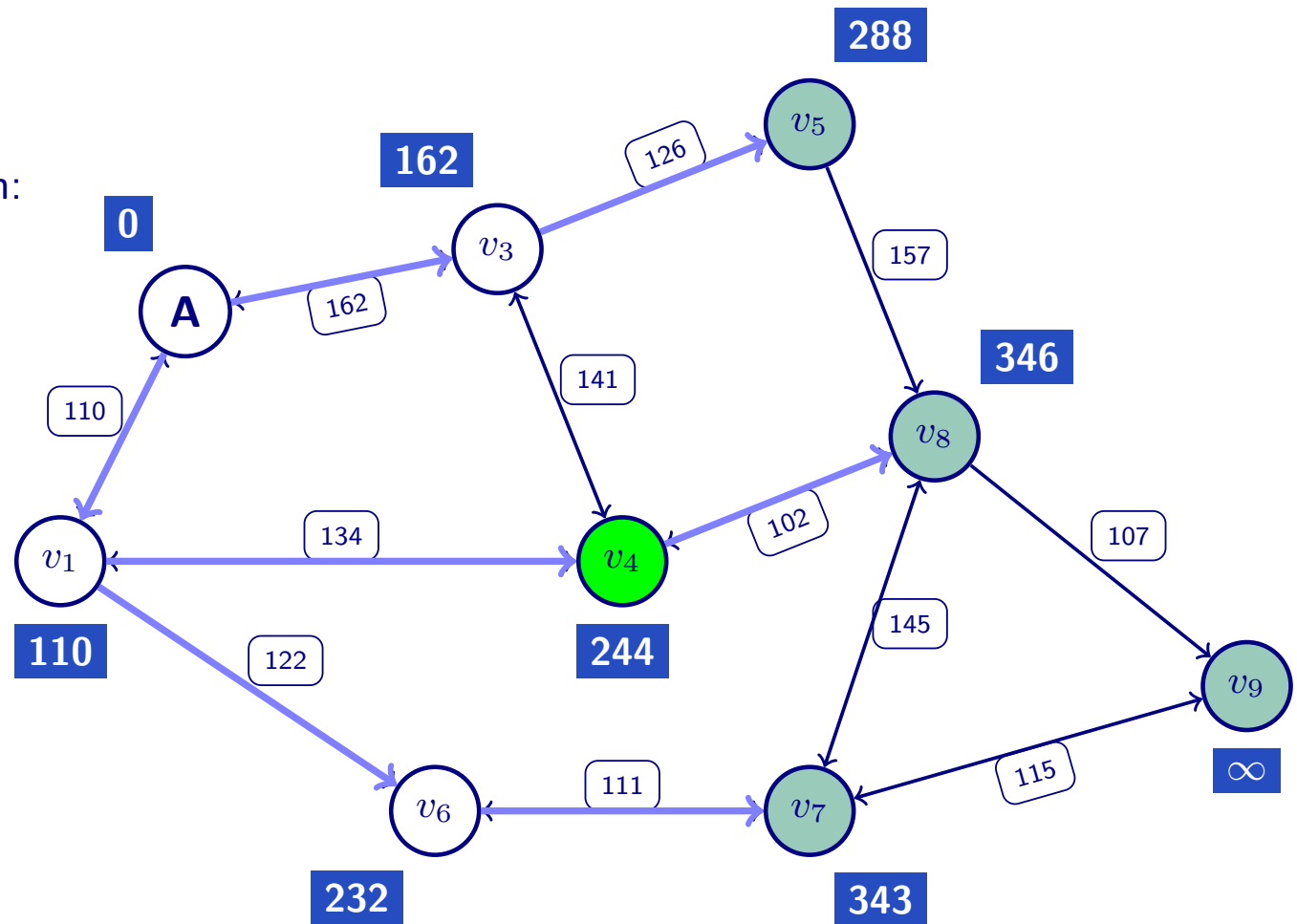
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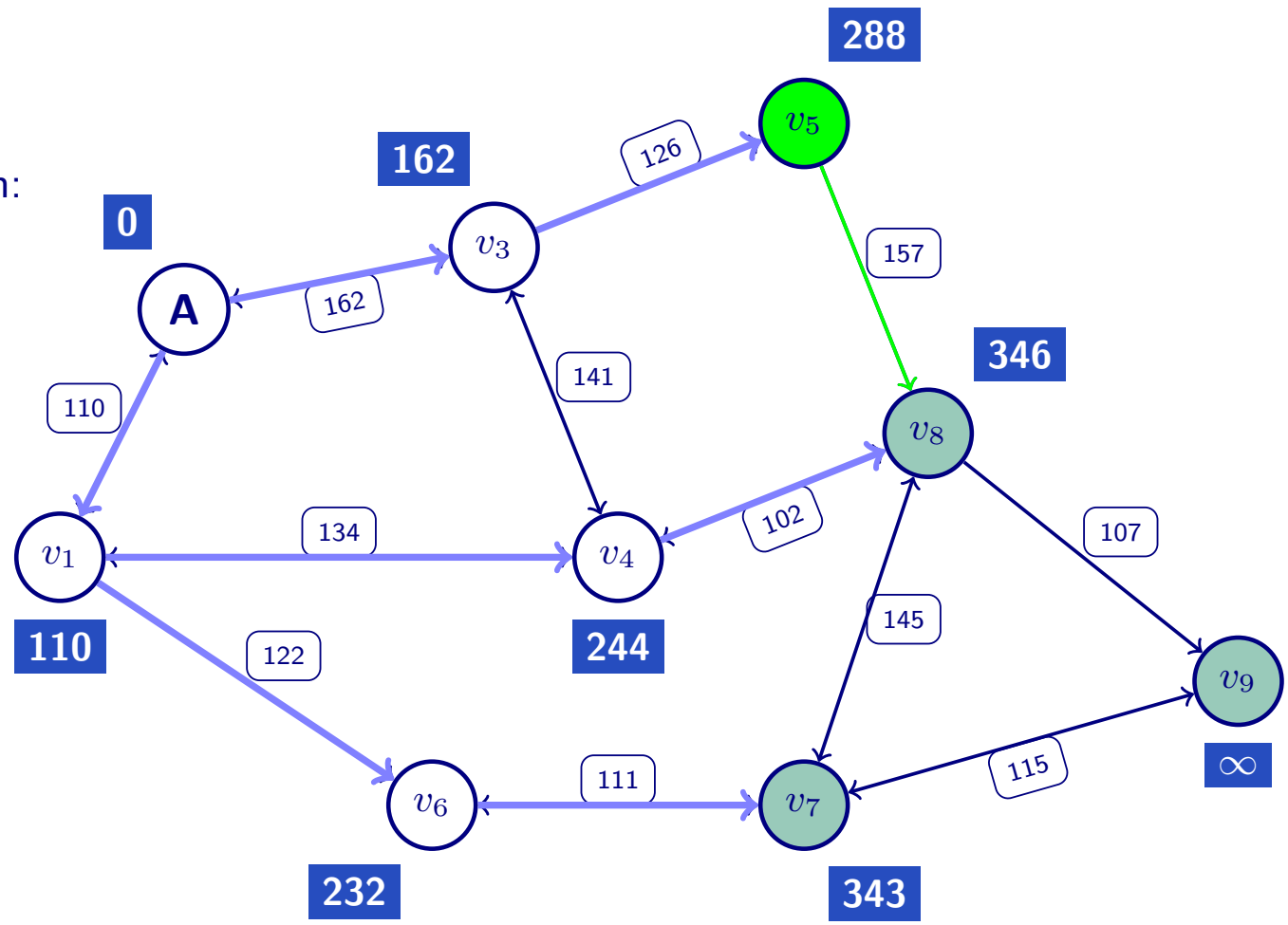
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...remove  $v$  from  $R$

  $R$  remaining nodes

  $d(v)$  min distance to A

 predecessor tree



▷ Dijkstra’s algorithm computes a shortest path tree from start node A to all other nodes:

Set remaining nodes  $R := V$ , and  $d(A) := 0$ ,  $d(v) := \infty$  for all nodes  $v \neq A$ ,  $\text{pred}(A) := A$

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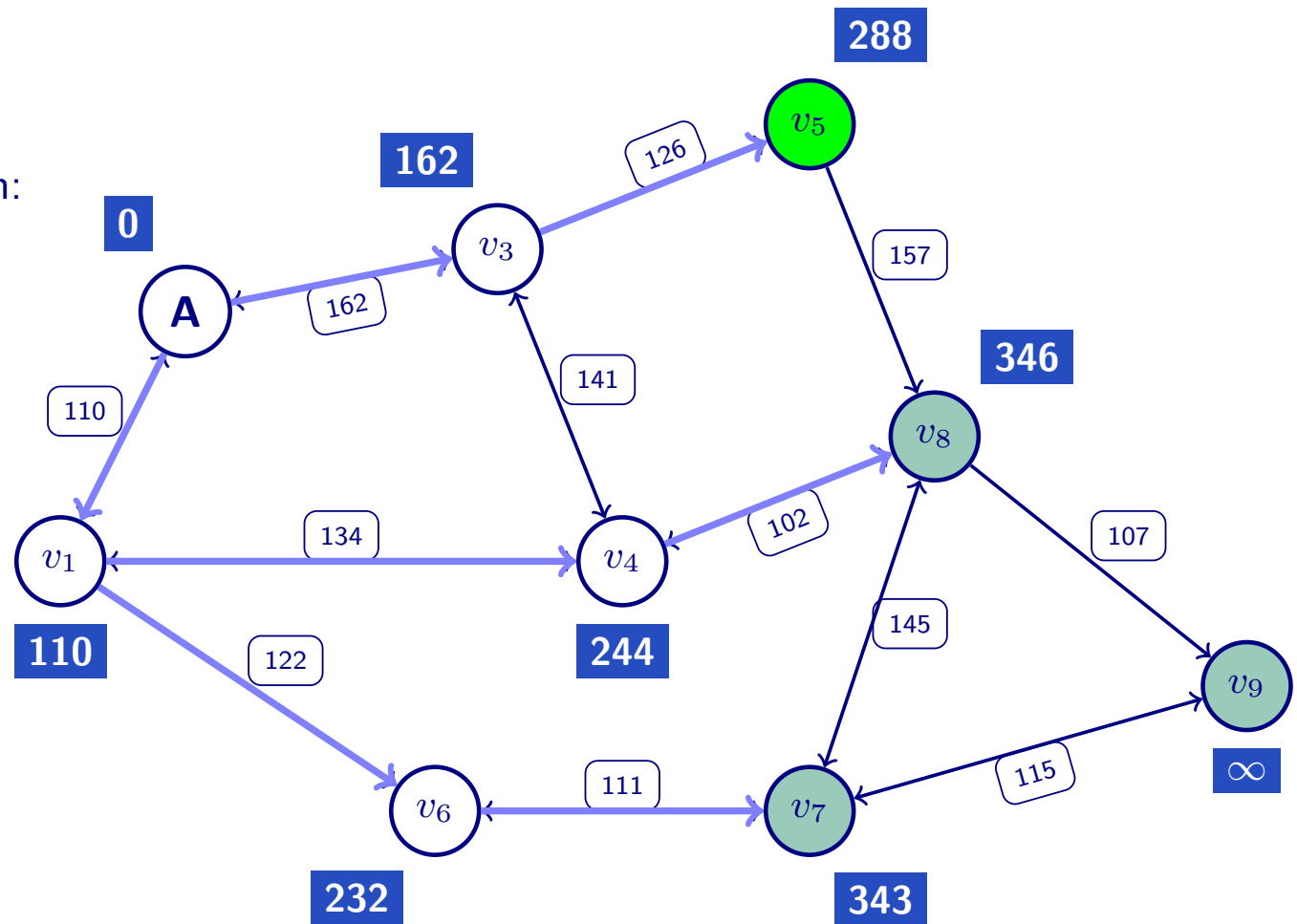
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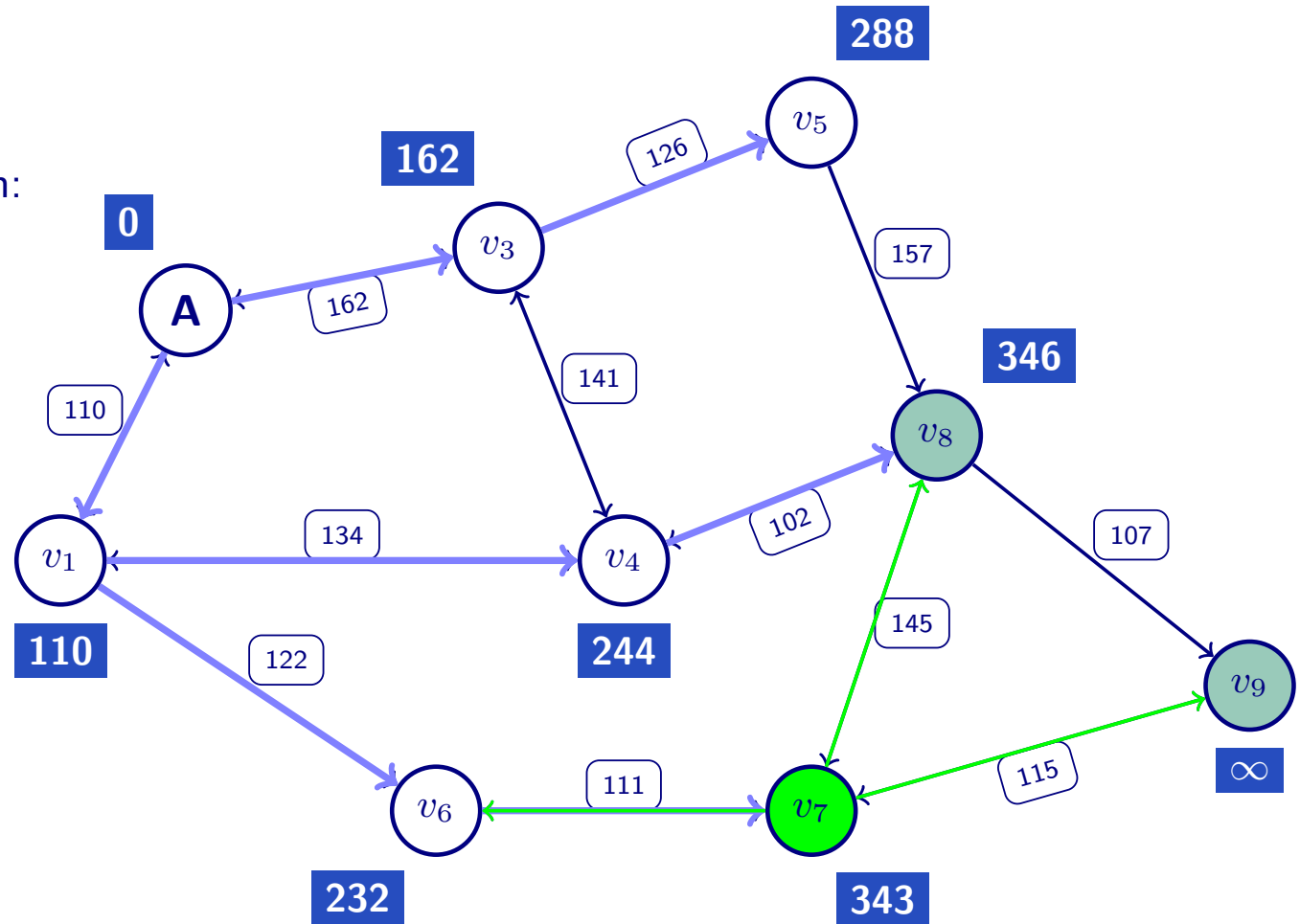
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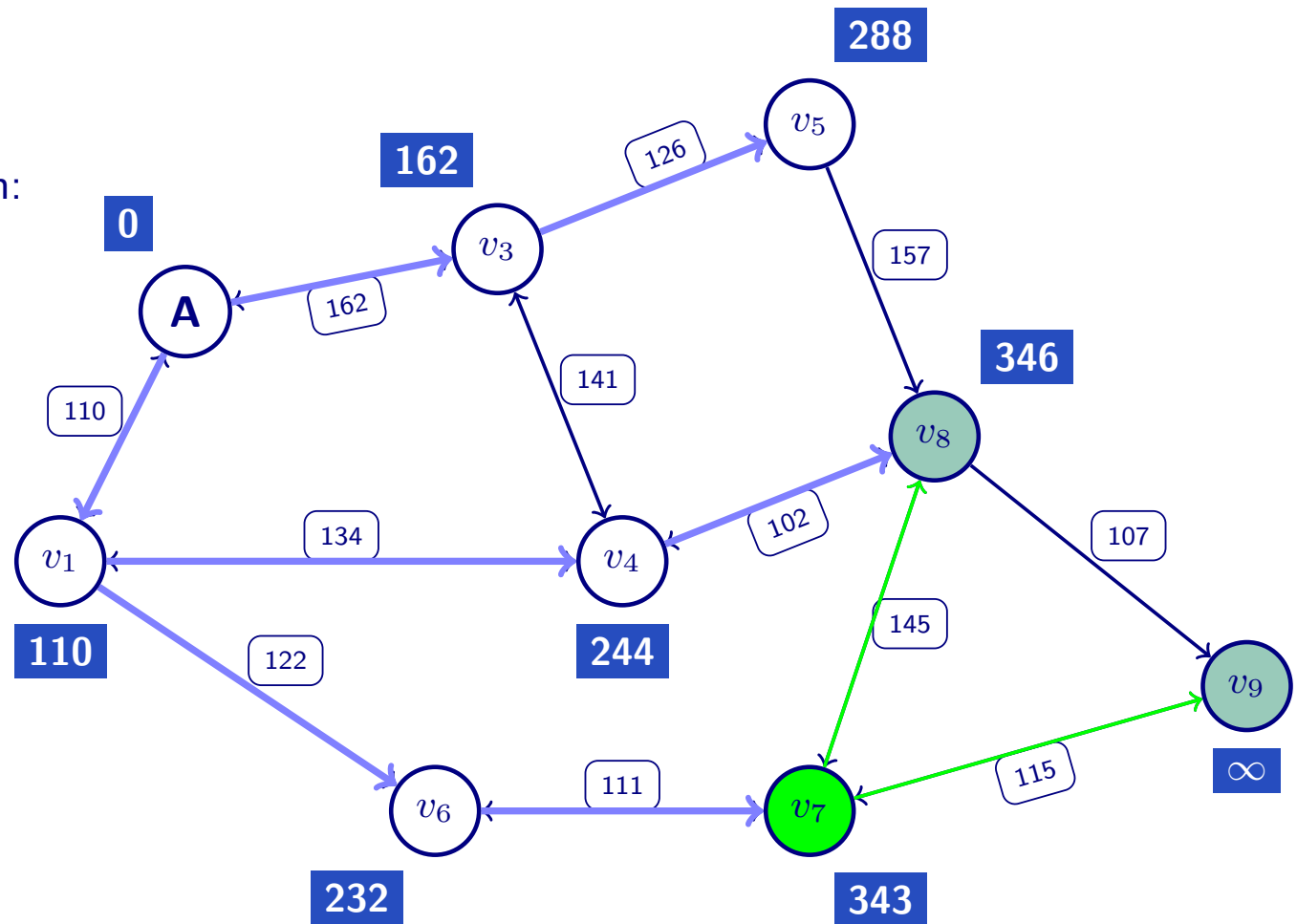
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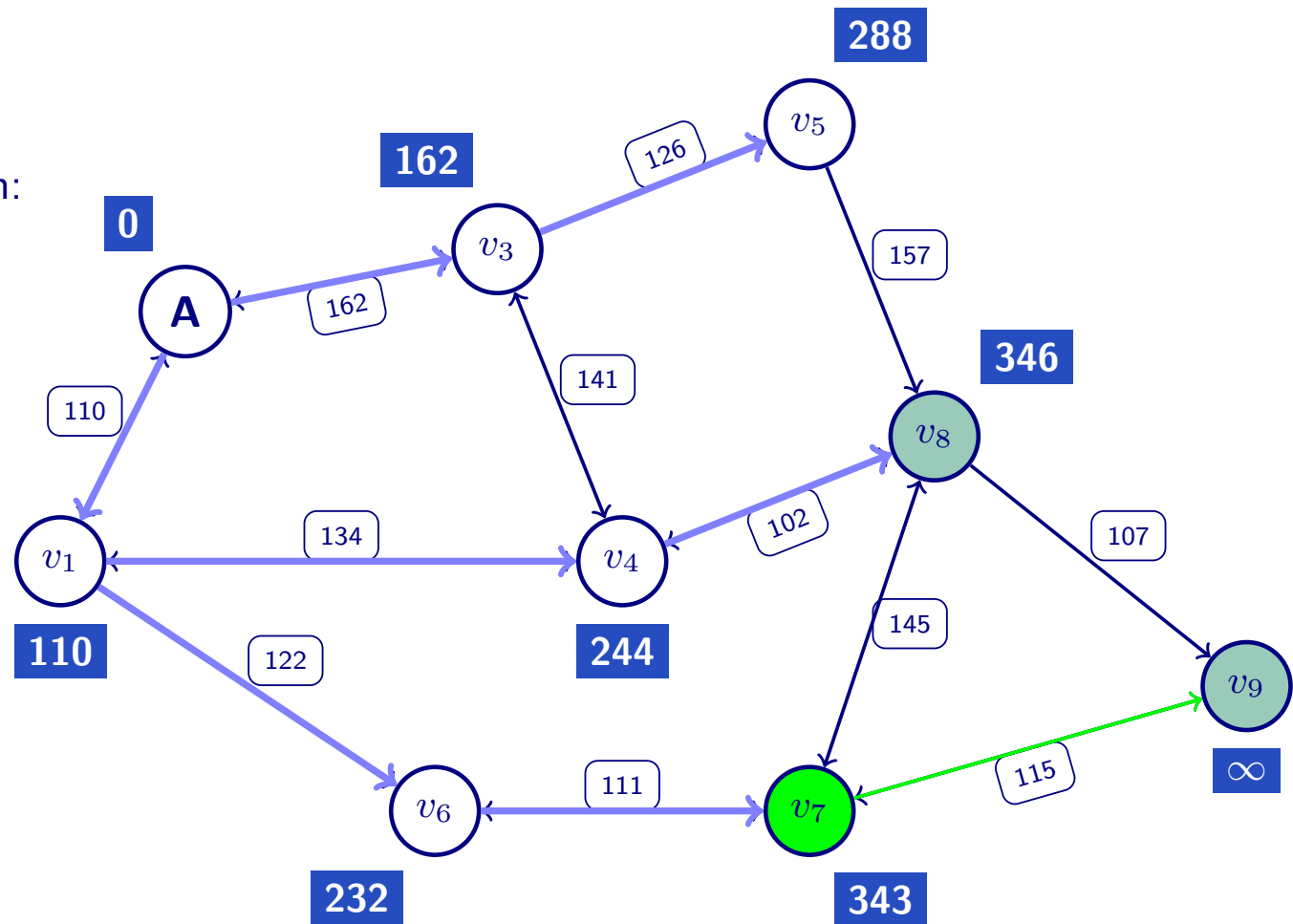
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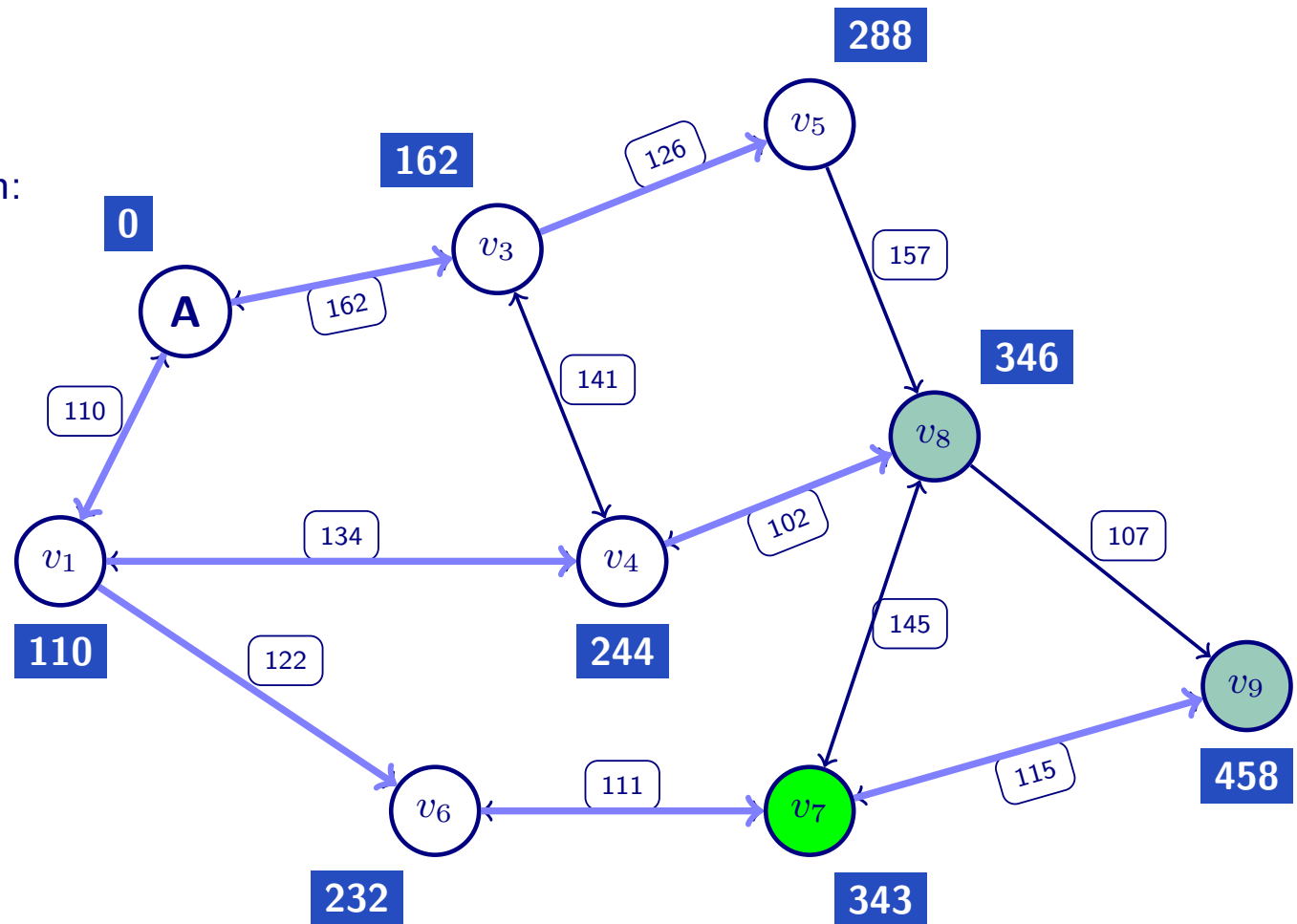
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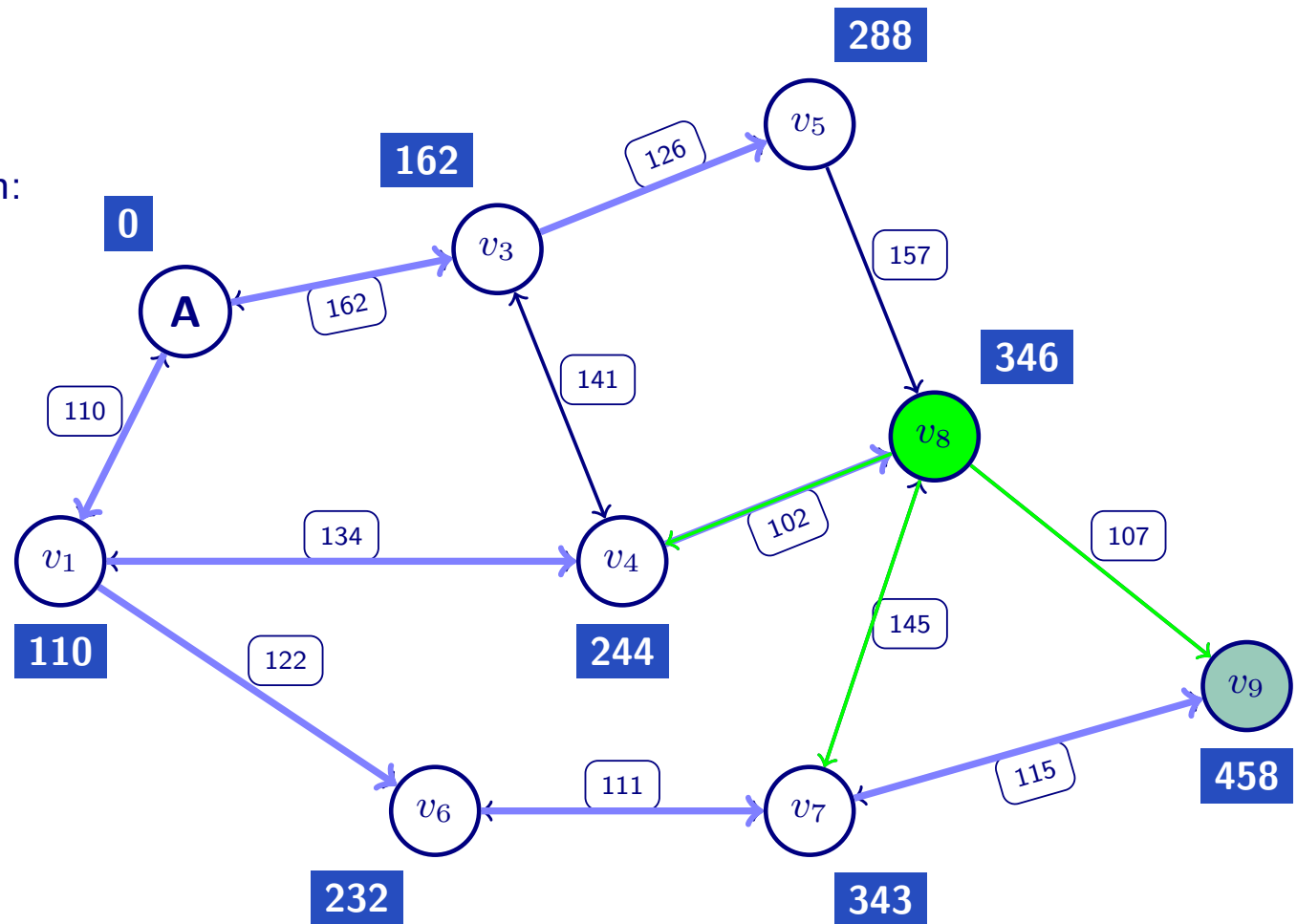
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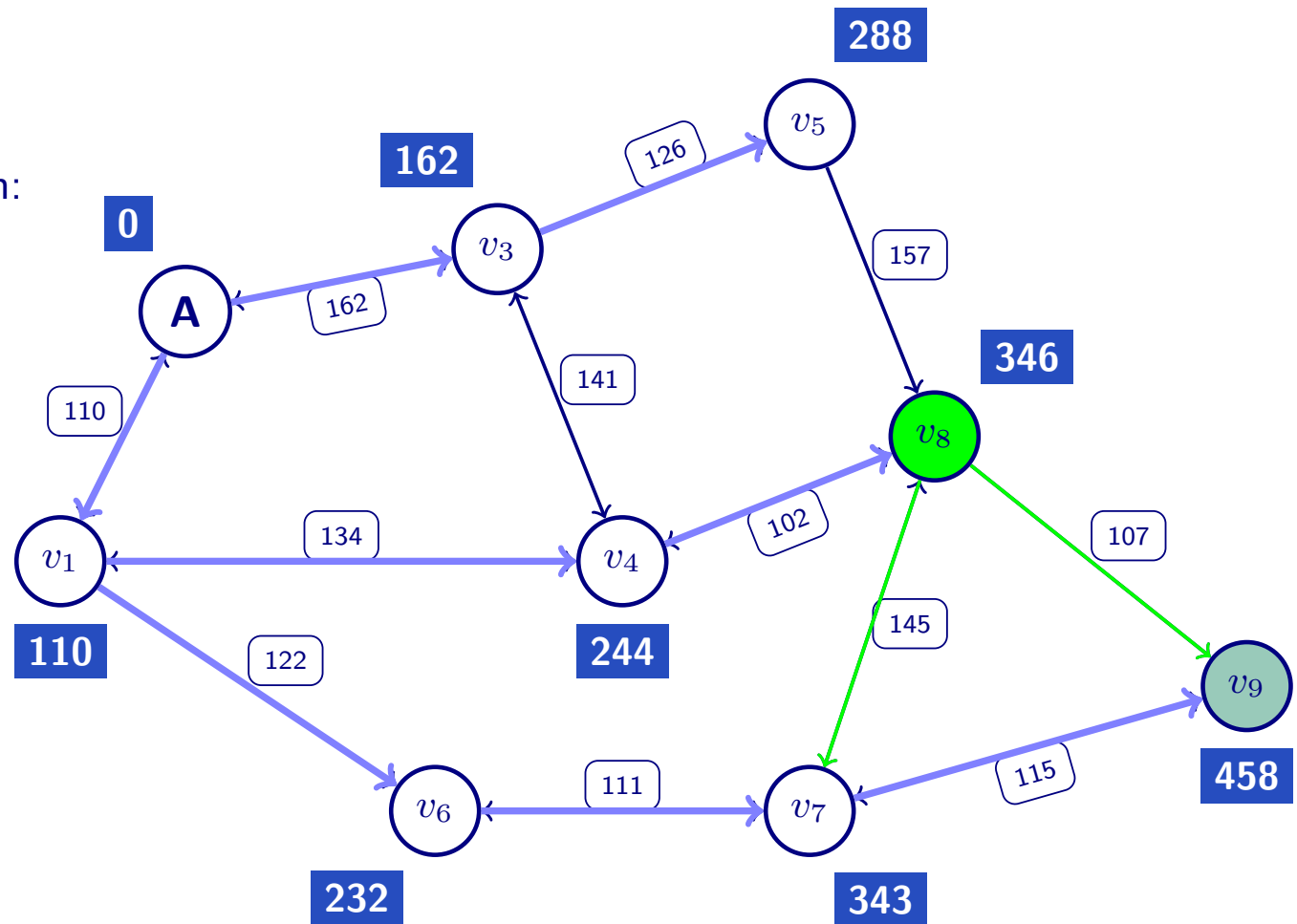
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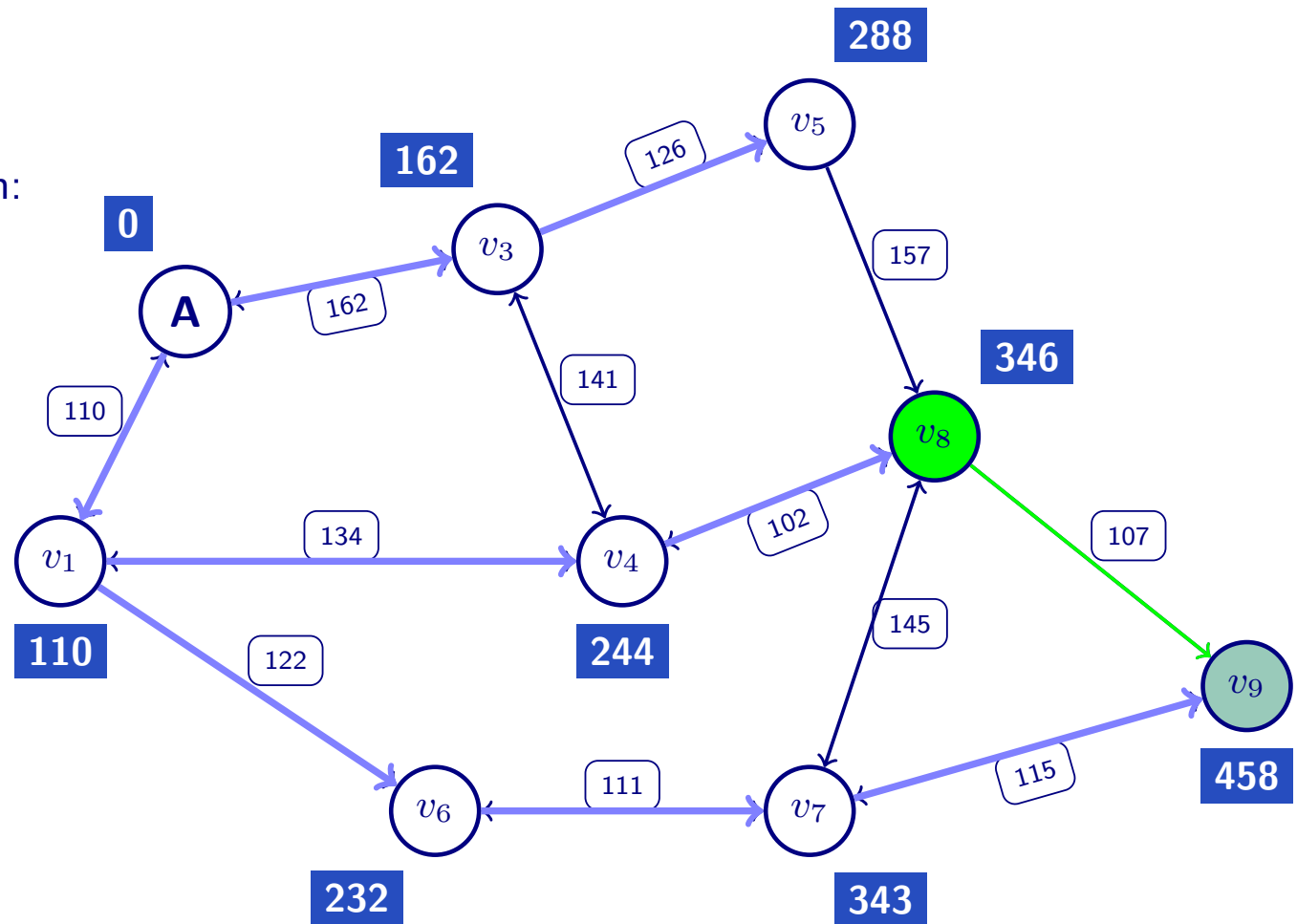
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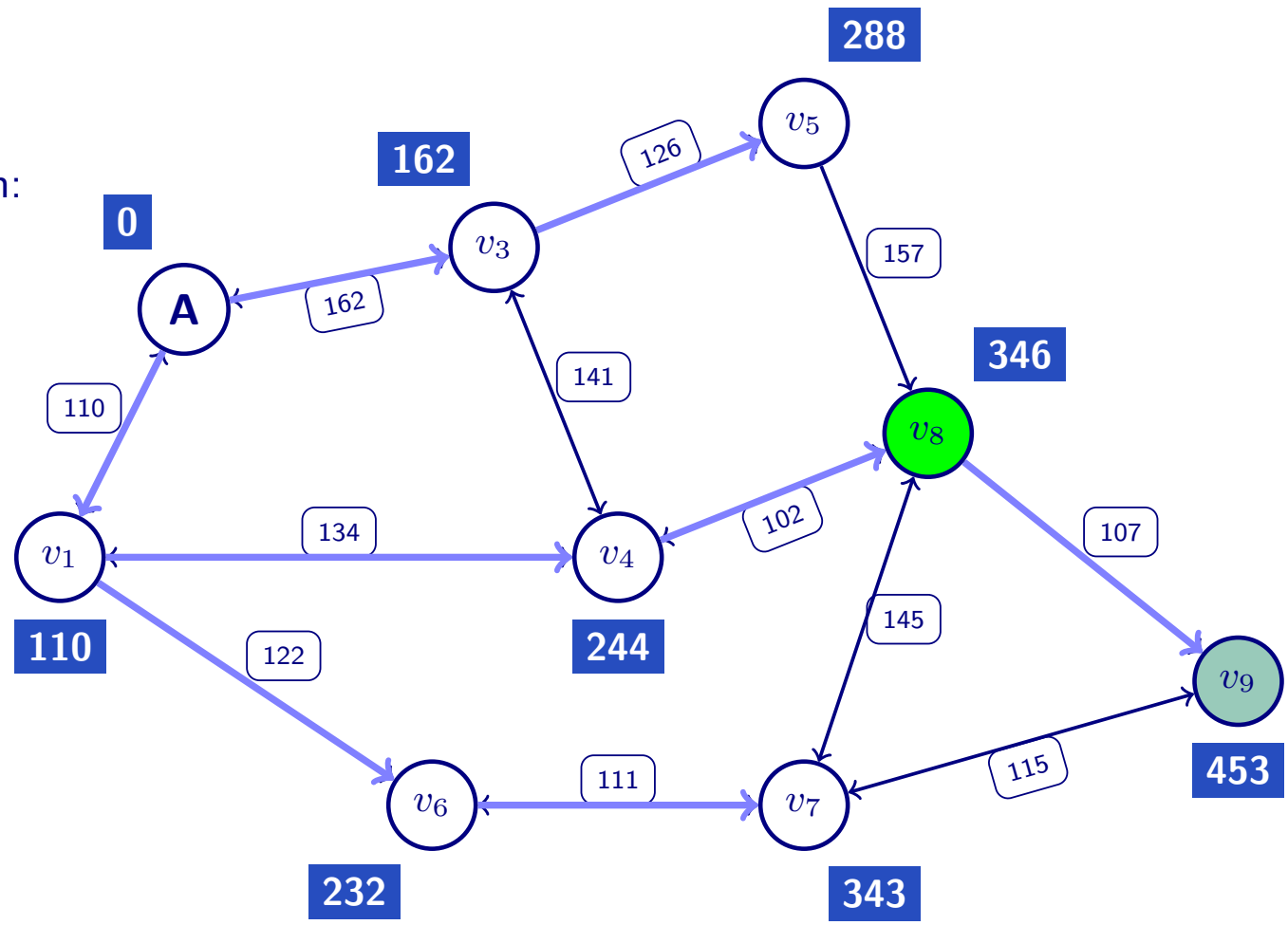
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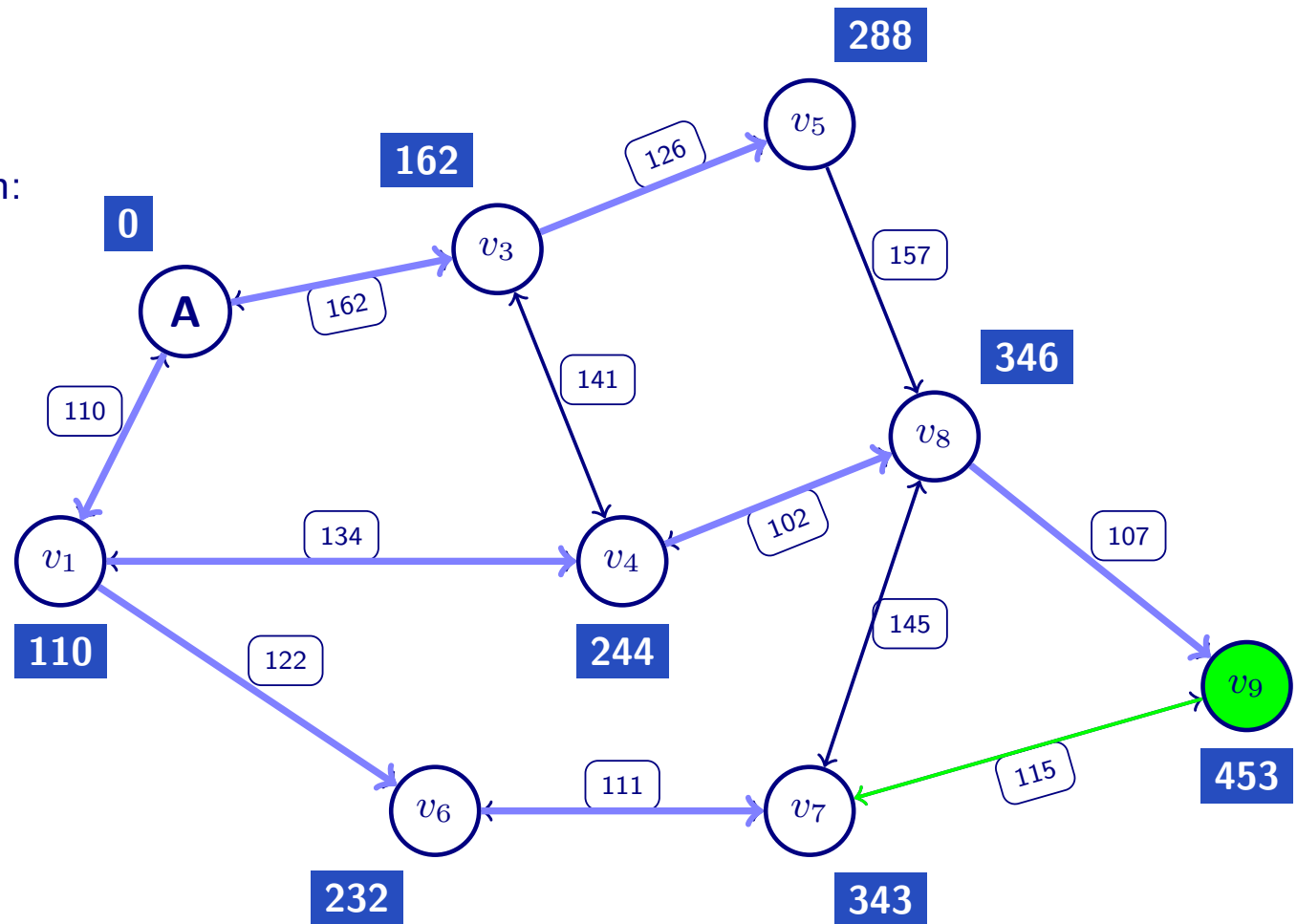
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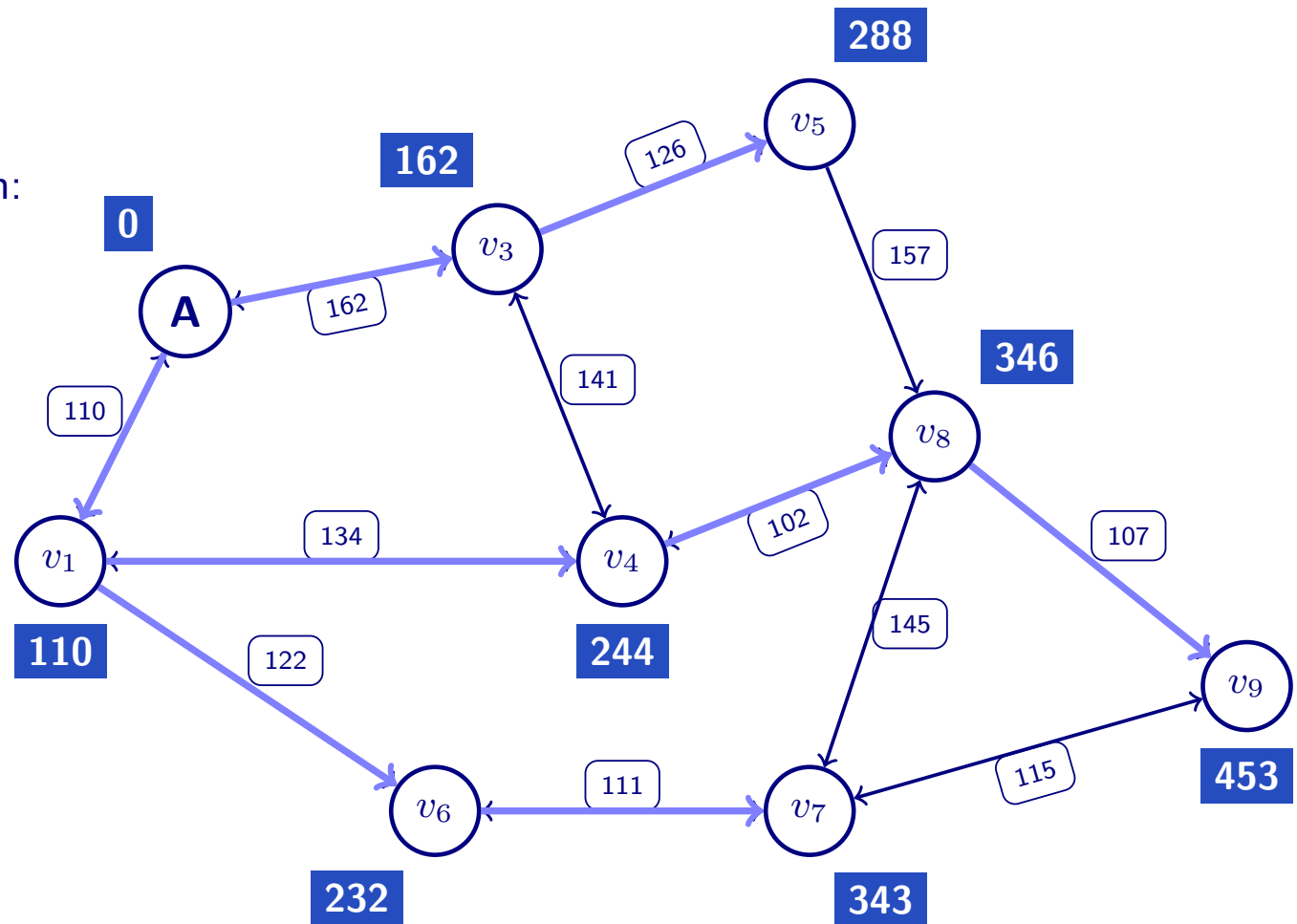
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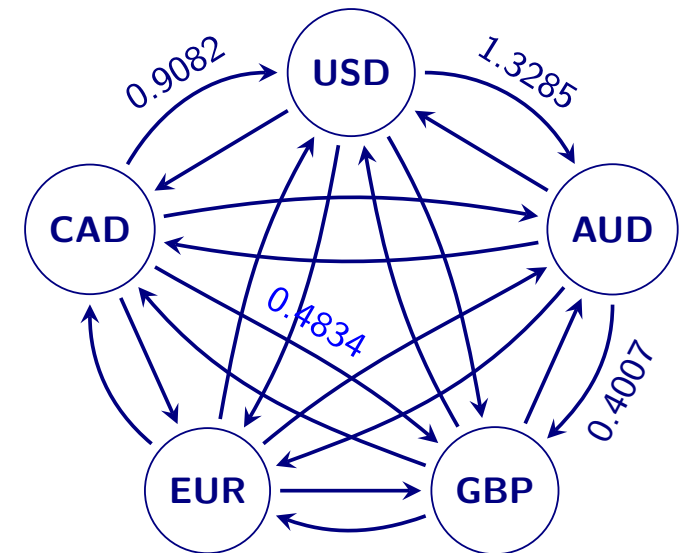


▷ Exchange 100 Mio Can-\$ into £

	<b>USD</b>	<b>GBP</b>	<b>CAD</b>	<b>EUR</b>	<b>AUD</b>
<b>USD</b>	1	1.8786	0.9082	1.2953	0.7527
<b>GBP</b>	0.5323	1	0.4834	0.6895	0.4007
<b>CAD</b>	1.1010	2.0685	1	1.4262	0.8288
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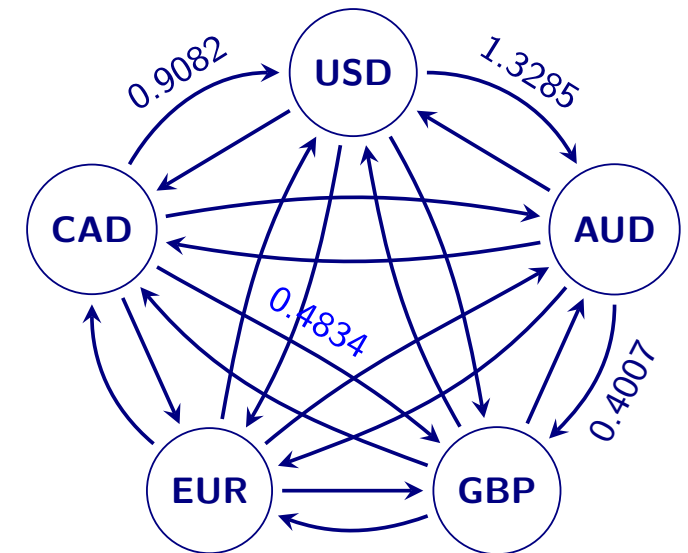
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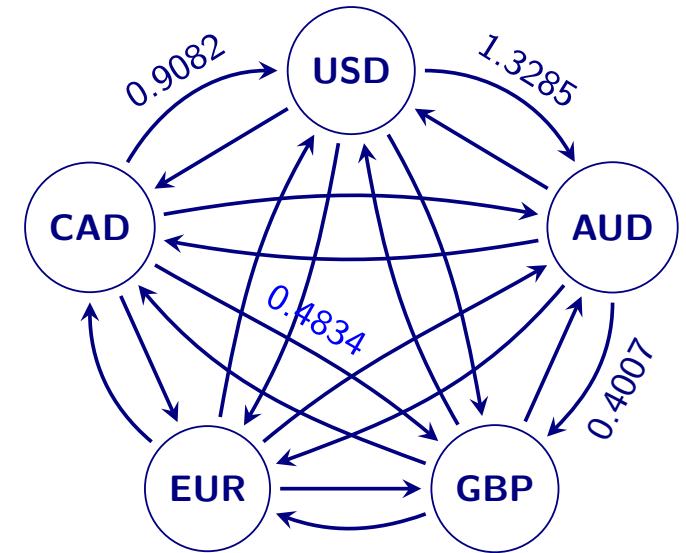
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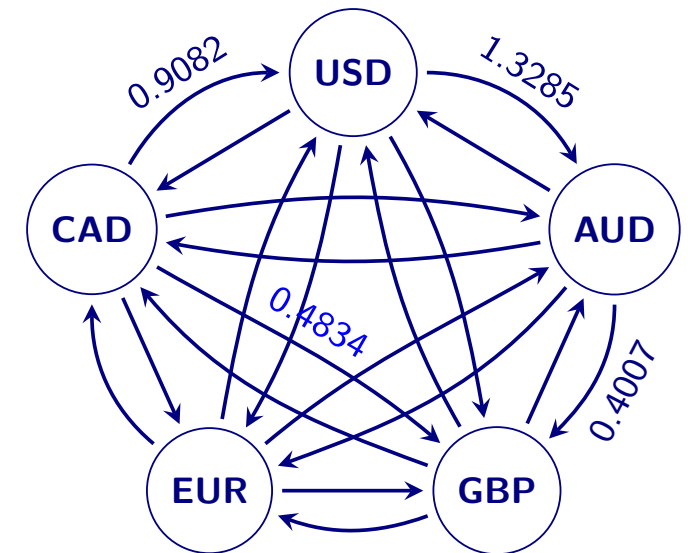
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➔ Rate:  $0.9082 \cdot 1.3285 \cdot 0.4007 = 0.483462 > 0.4834$



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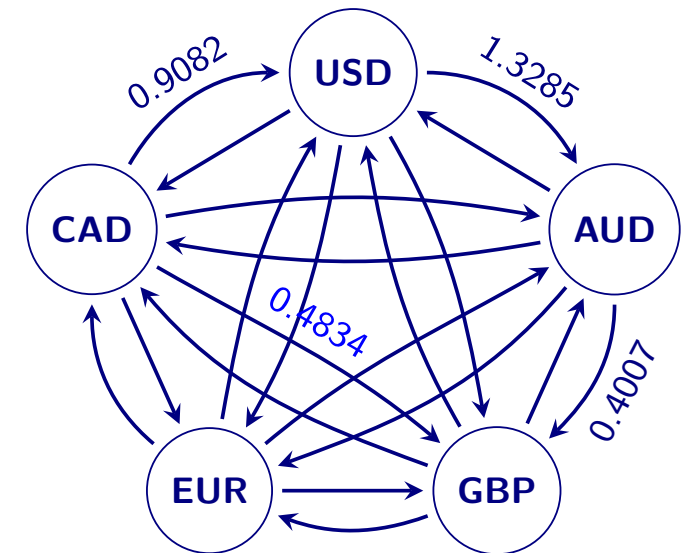
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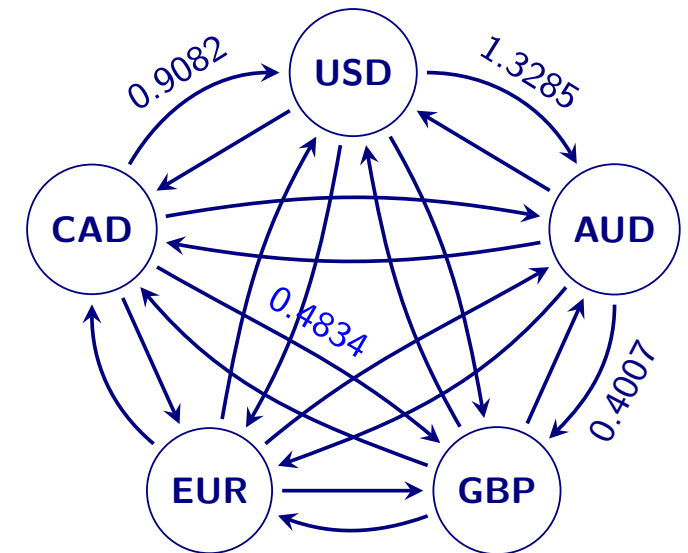
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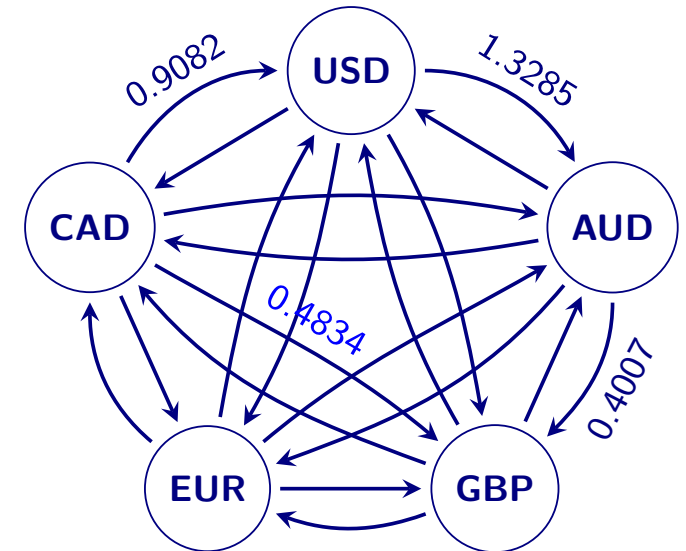
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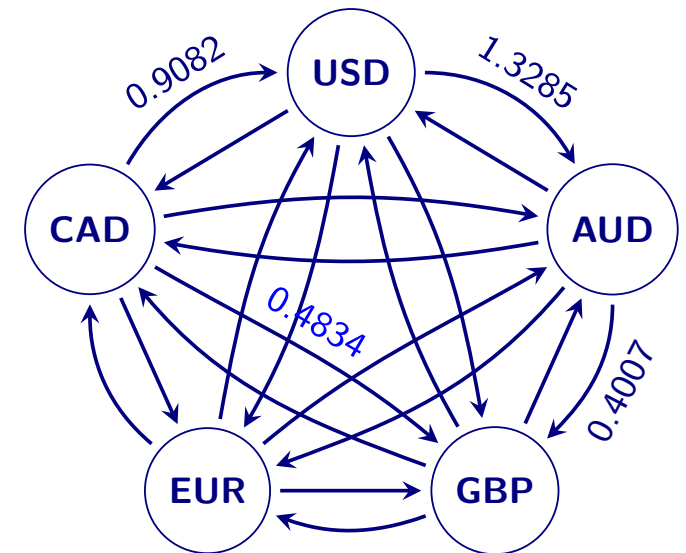
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  - ➔ Use logarithm:  $\log(a \cdot b) = \log a + \log b$  and  $\log a < \log b \iff a < b$
- ▷ Plus: search for a longest path (instead of a shortest)



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  - Algorithm: Set the current biggest number  $x_{\max} := -\infty$   
For all  $i$  from 1 to  $n$ ...  
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constant time

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➔ Input size:  $n$  numbers

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▷ Example: Determine the biggest number in a given list

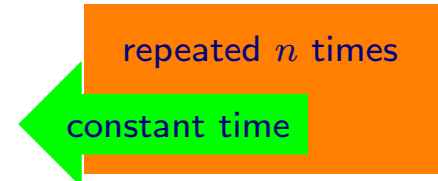
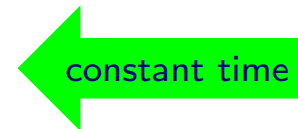
- Input: List  $x_1, \dots, x_n$  of numbers

- Algorithm: Set the current biggest number  $x_{\max} := -\infty$

For all  $i$  from 1 to  $n$ ...

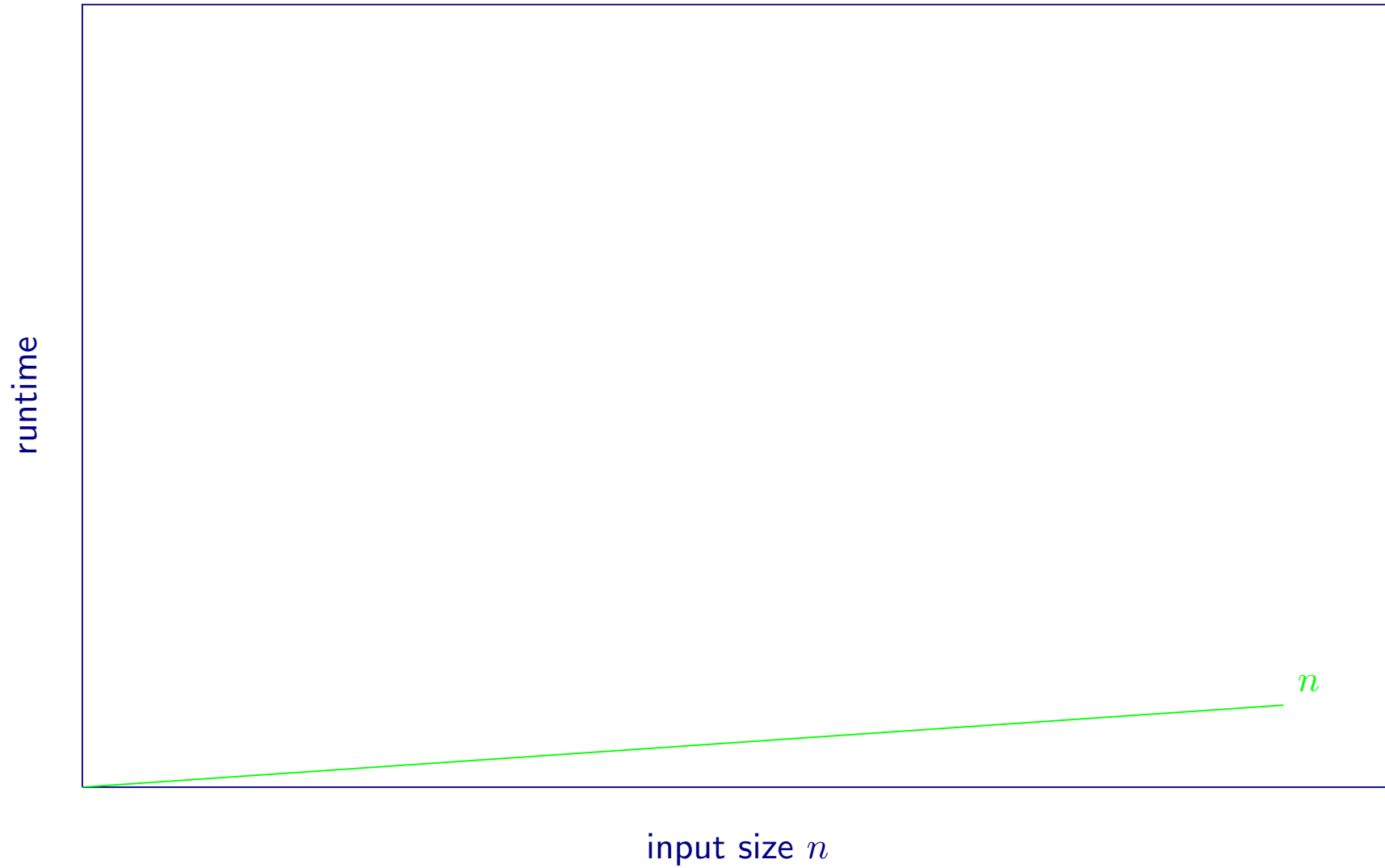
...if  $x_i > x_{\max}$  then set  $x_{\max} := x_i$

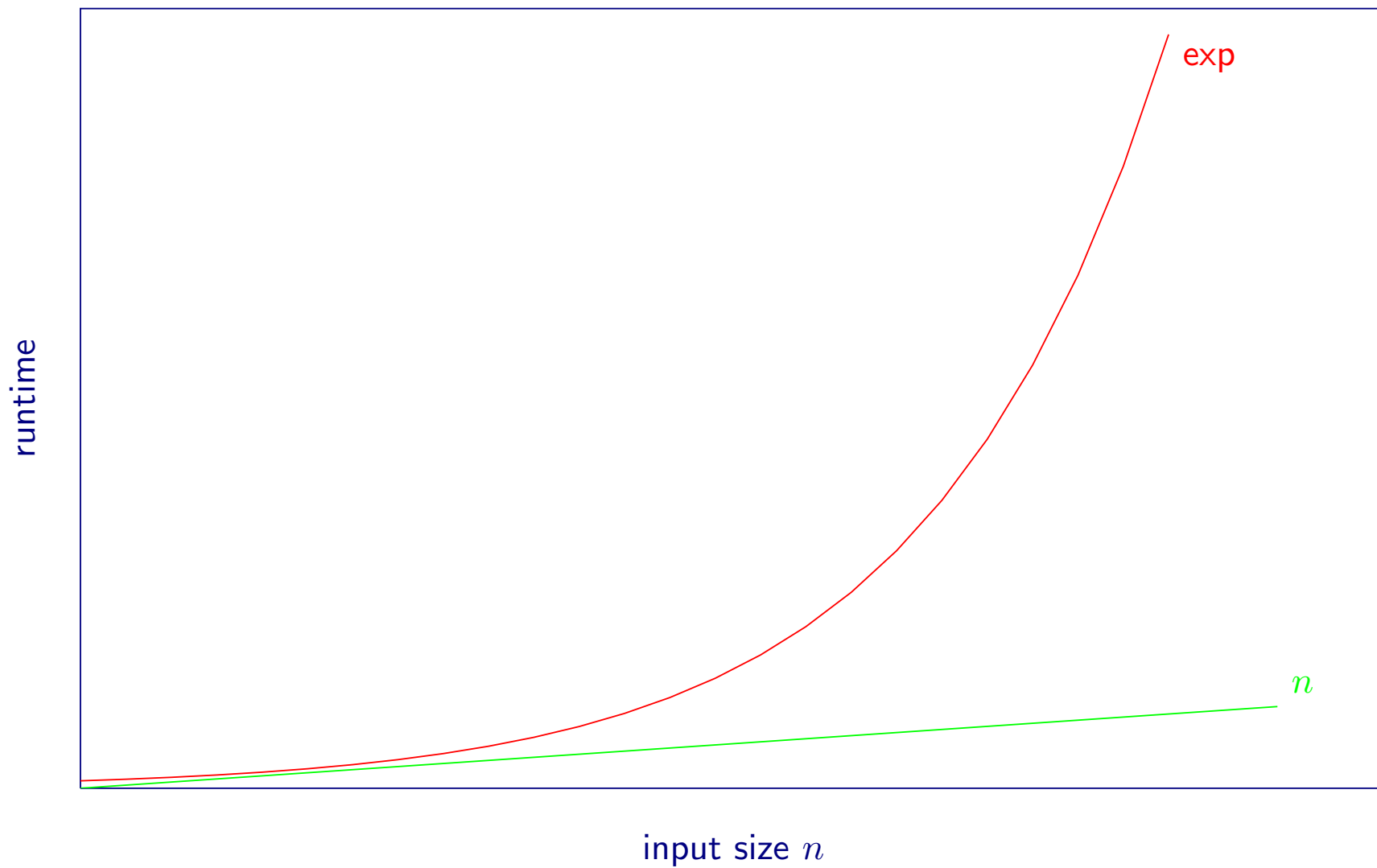
➔  $x_{\max}$  is the biggest number in the input

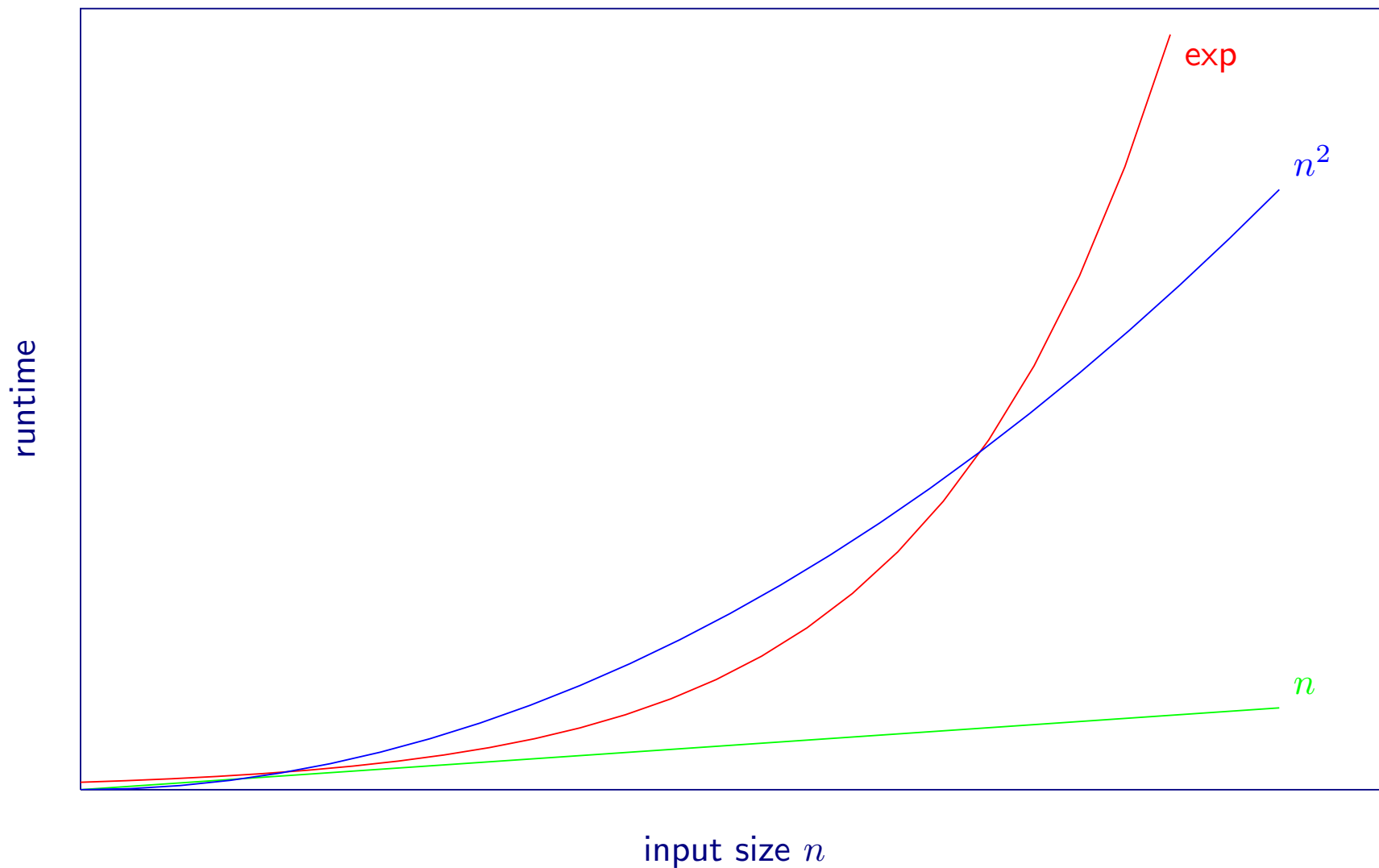


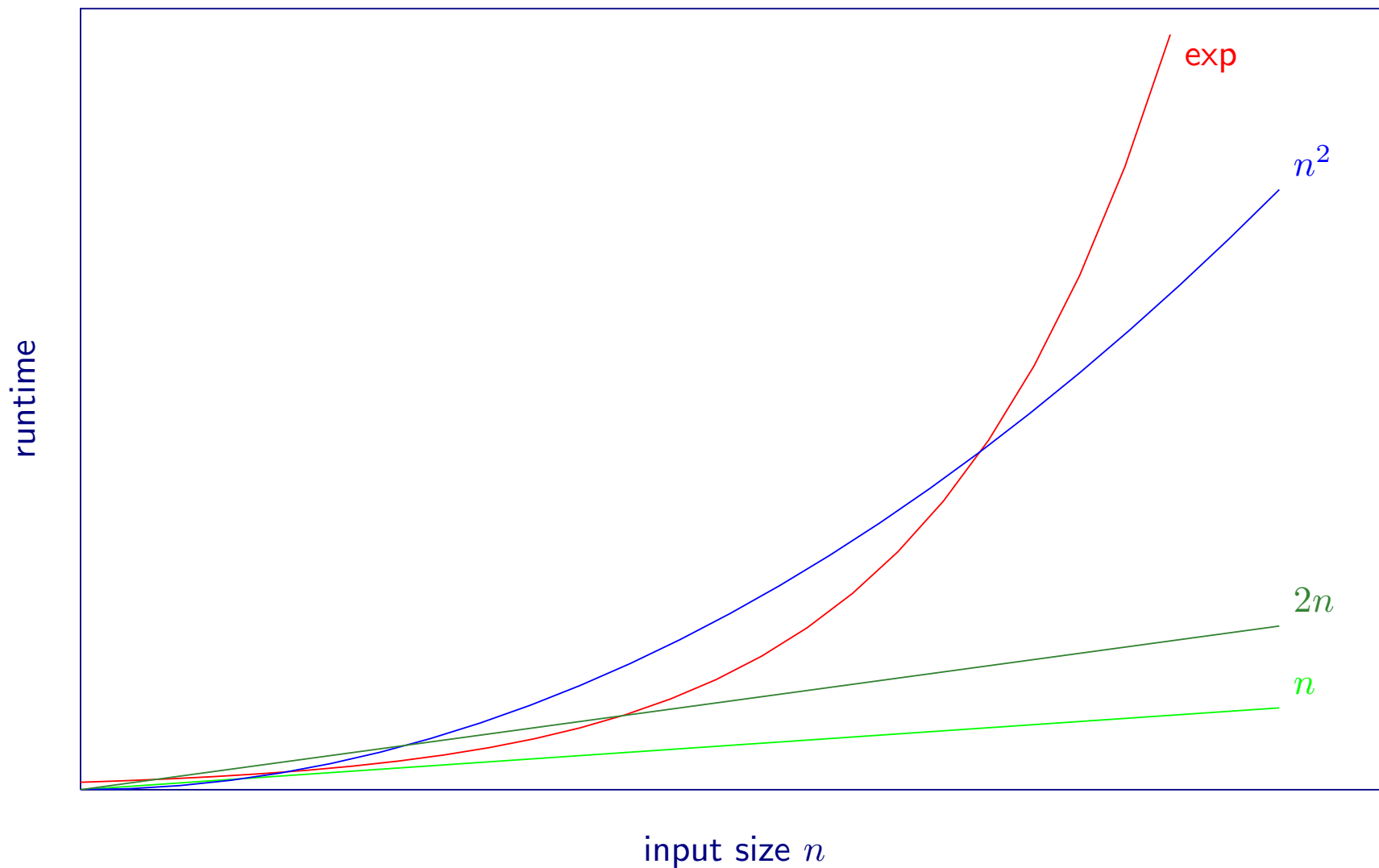
➔ Input size:  $n$  numbers

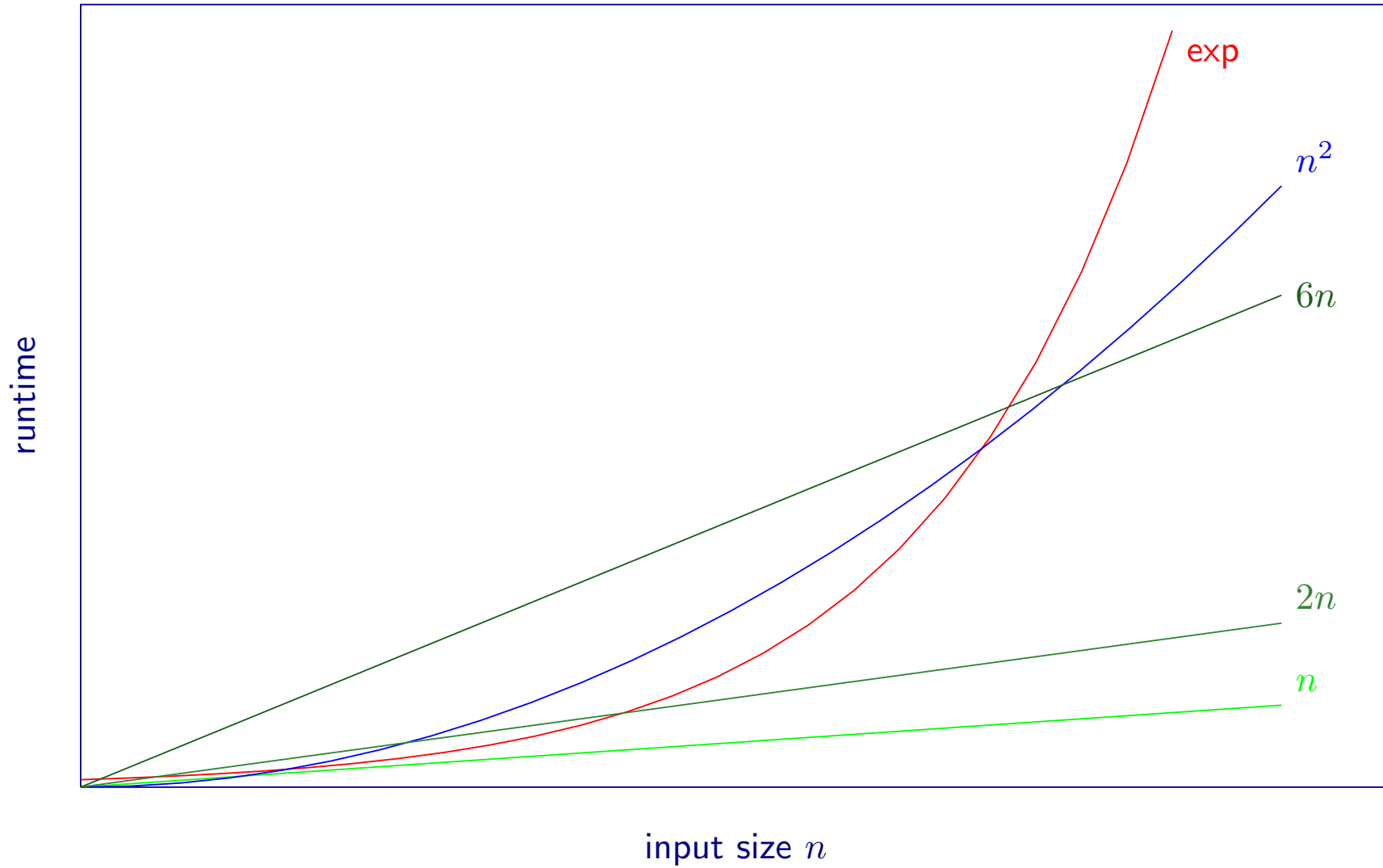
➔ Runtime:  $n + 1$  “basic steps” (order of  $n$ , linear runtime)

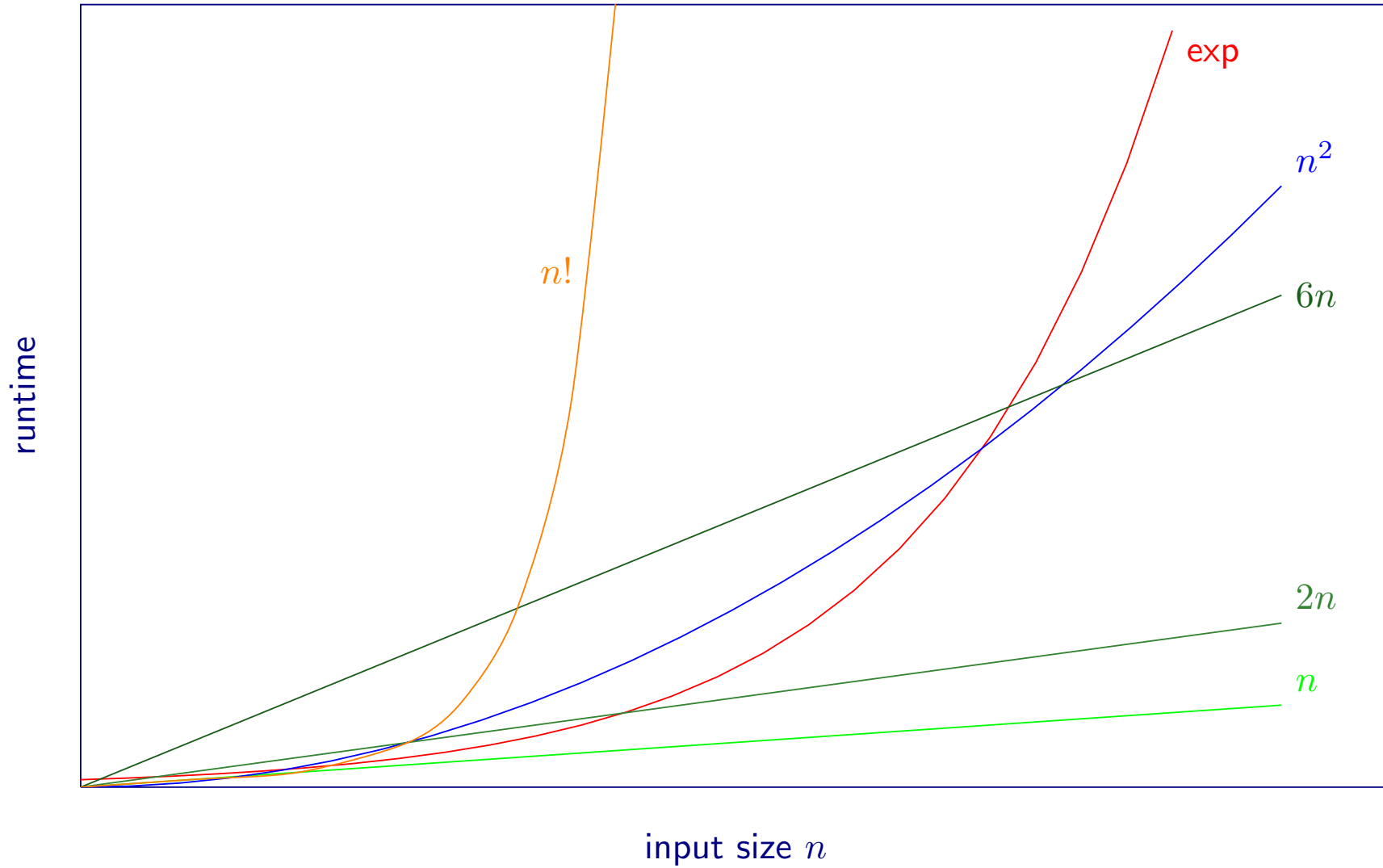




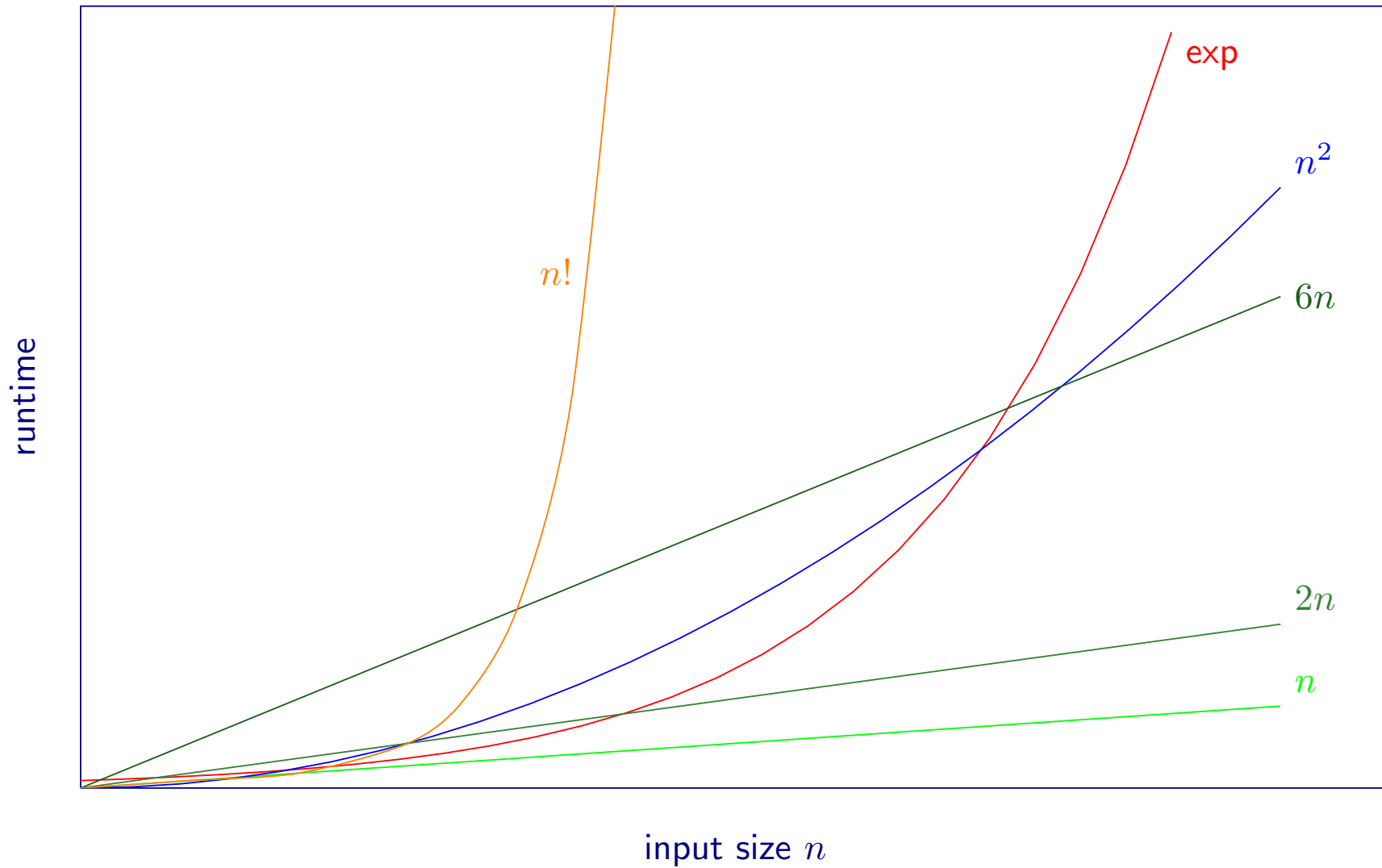












linear — polynomial — exponential

▷ Input: directed graph with  $n$  nodes  $V$

▷ Algorithm:

Set remaining nodes  $R := V$ , and  $d(A) := 0$ ,  $d(v) := \infty$  for all nodes  $v \neq A$ ,  $\text{pred}(A) := A$

While  $R$  is not empty...

...let  $v \in R$  with minimal  $d(v)$

...for all arcs  $(v, w)$ :

if  $d(w) > d(v) + \ell(v, w)$  then:

set  $d(w) := d(v) + \ell(v, w)$

set  $\text{pred}(w) := v$

...remove  $v$  from  $R$

▷ Input: directed graph with  $n$  nodes  $V$



Input size:  $n$

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$n$  basic steps

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...remove  $v$  from  $R$

repeated  $n$  times

$n$  basic steps

▷ Input: directed graph with  $n$  nodes  $V$

→ Input size:  $n$

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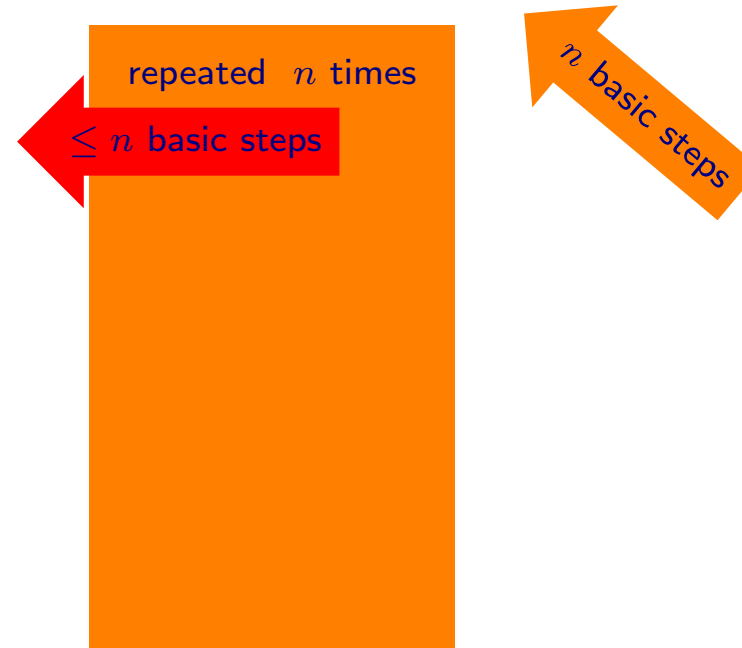
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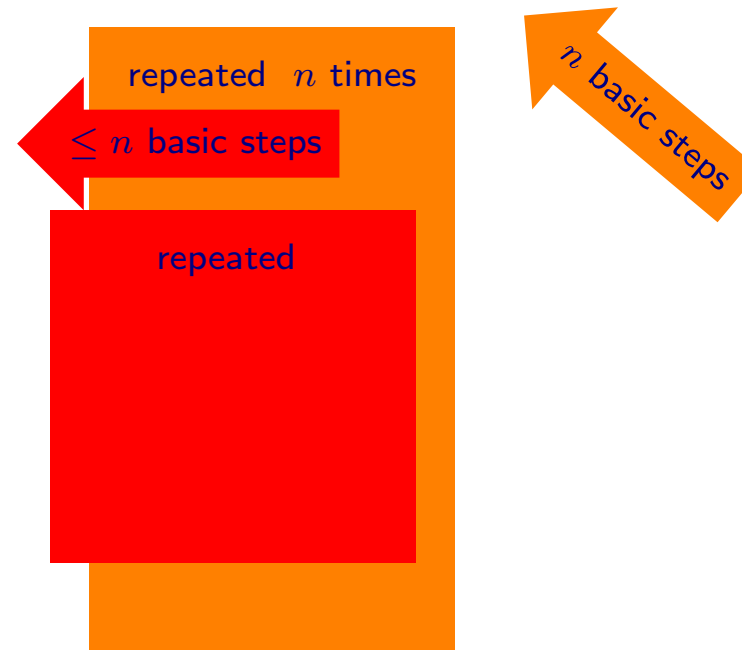
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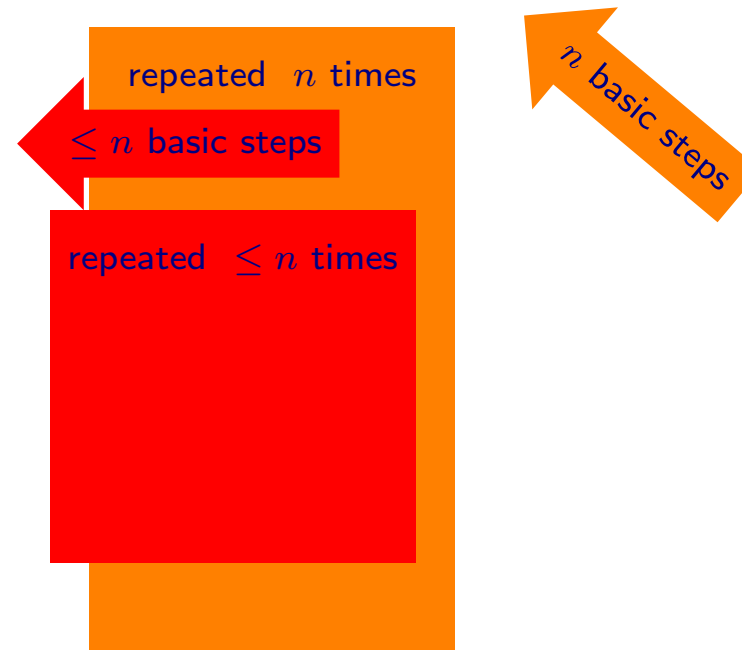
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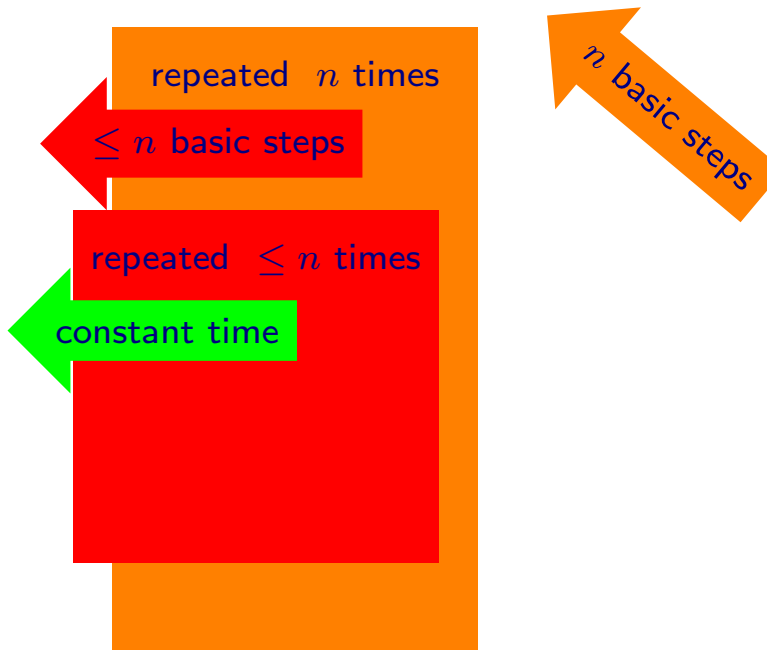
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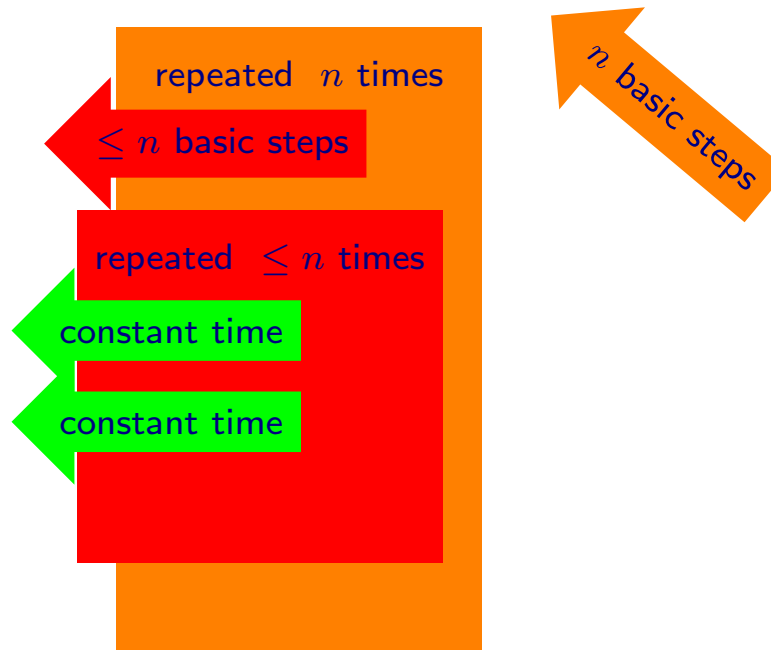
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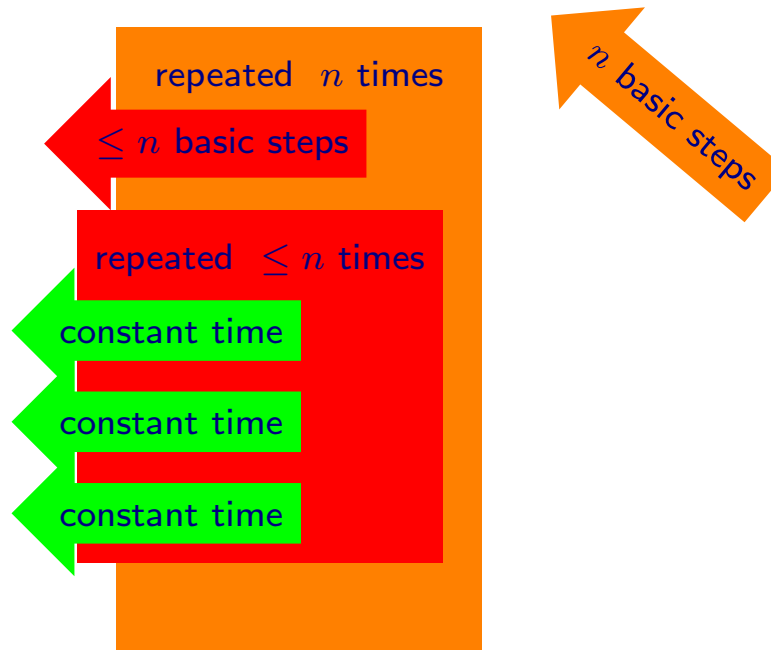
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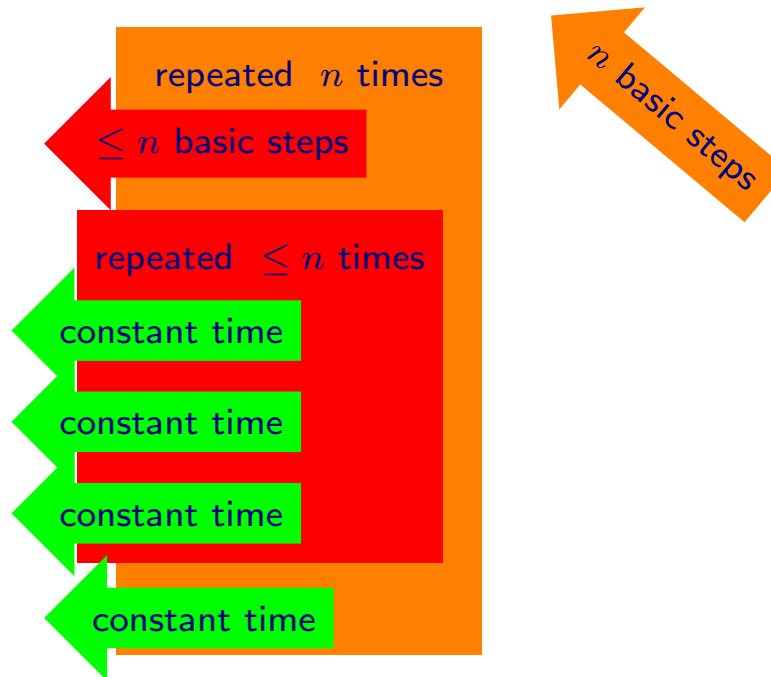
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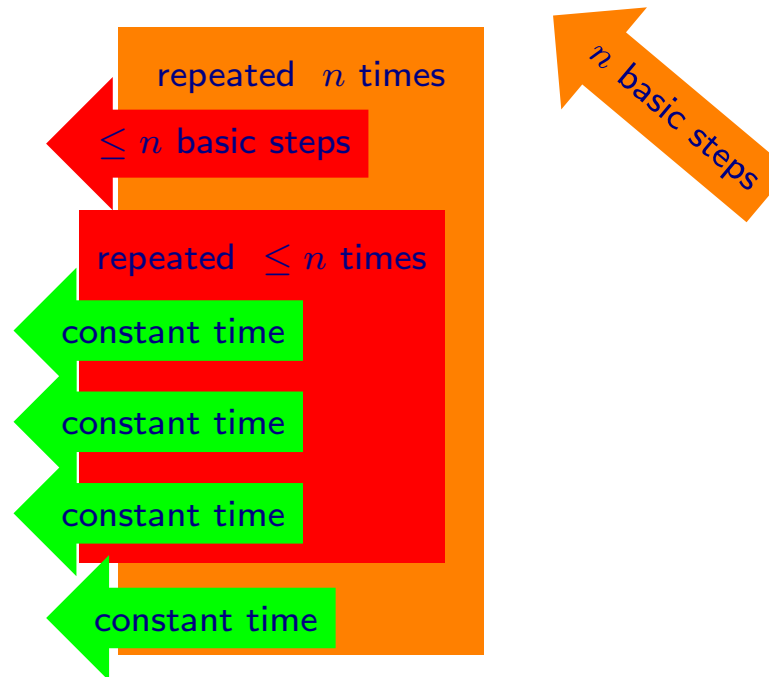
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→ Altogether: at most  $n \cdot (n + 3n + 1) = 4n^2 + n$  "basic steps"

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→ Input size:  $n$

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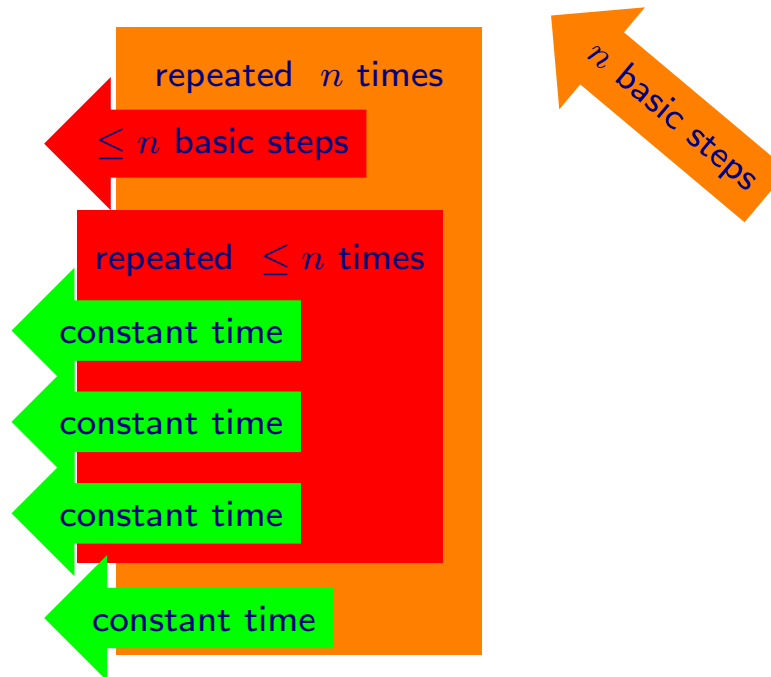
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→ Altogether: at most  $n \cdot (n + 3n + 1) = 4n^2 + n$  “basic steps”

→ Polynomial runtime ( $\mathcal{O}(n^2)$ )

- ▷ Models, Data and Algorithms
- ▷ Linear Optimization
- ▷ Mathematical Background: Polyhedra, Simplex-Algorithm
- ▷ Sensitivity Analysis; (Mixed) Integer Programming
- ▷ MIP Modelling
- ▷ MIP Modelling: More Examples; Branch & Bound
- ▷ Cutting Planes; Combinatorial Optimization: Examples, Graphs, Algorithms
- ▷ TSP-Heuristics
- ▷ Network Flows
- ▷ Shortest Path Problem
- ▷ Complexity Theory
- ▷ Nonlinear Optimization, Scheduling
- ▷ Lot Sizing, Multicriteria Optimization
- ▷ Oral exam