

## Lecture 14

# Lot Sizing & Multicriteria Optimization

01 Feb 2012

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## ▪ Lot-Sizing Problems



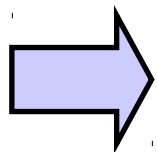
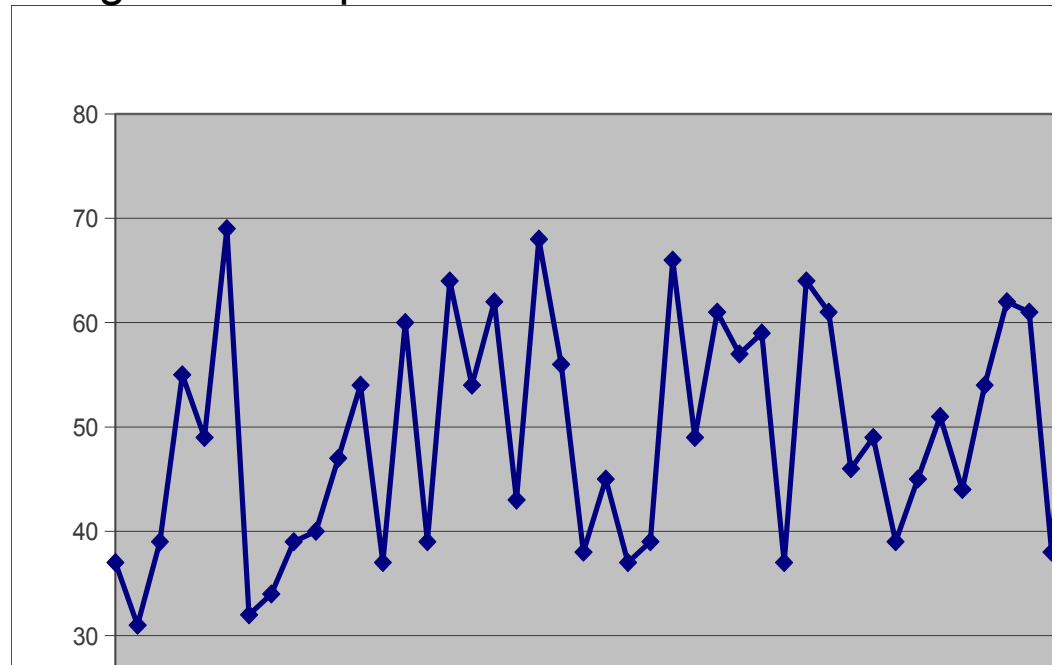
IDEA manufactures and sells furniture

KJELT



- Production of couches is performed in batches
- Inventory to meet demand

Selling numbers per week



**How large should be the batch size;  
When should be produced?**

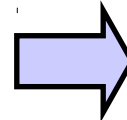
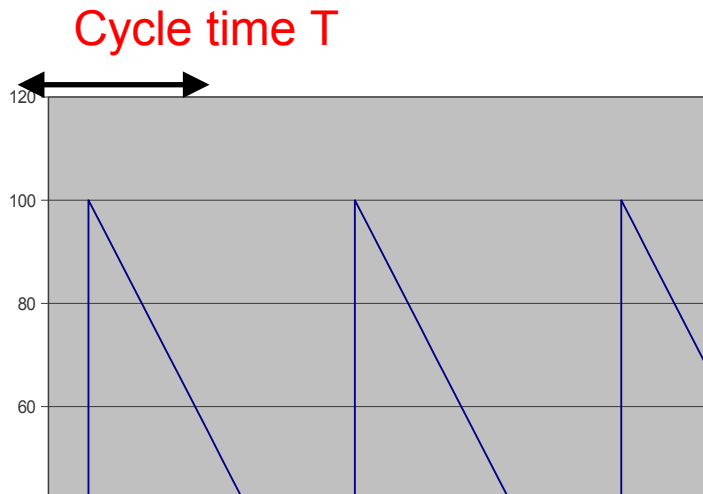
Matching of Batch Size and Inventory such that cost are minimized

- Demand fluctuates per time unit
- Backorders are sometimes allowed
- Production involves a fixed setup cost (order cost)
- Lead time for delivery is instantaneous

## Basic EOQ Model

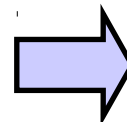
- Demand is known with certainty and fixed at  $D$  per time unit
- Shortages are not permitted
- Lead time for delivery is instantaneous
- **Cost per order:**  $K$
- **Unit holding cost** per time unit:  $h$ 
  - Physical storage cost
  - Cost of Capital invested in inventory

**Objective:** Minimize average costs per time unit over an infinite time horizon

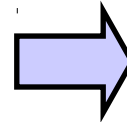


Order whenever inventory hits zero

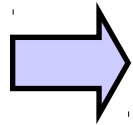
Order size:  $Q$



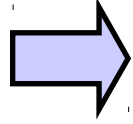
$T = Q / D$  or  $Q = T \cdot D$



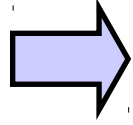
Holding cost per cycle =  $\frac{1}{2}hTQ$



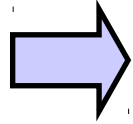
Holding cost per cycle =  $\frac{1}{2}hTQ$



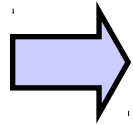
Cost per order =  $K$



Total cost per cycle =  $K + \frac{1}{2}hTQ$



Average cost per time unit  $C(Q) = (K + \frac{1}{2}hTQ) / T = KD / Q + \frac{1}{2}hQ$



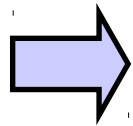
Find  $Q$  that minimizes average cost per time unit !

$$T = Q / D \quad \text{or} \quad Q = T \cdot D$$

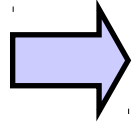
$$\frac{dC}{dQ} = 0 \Leftrightarrow \frac{-KD}{Q^2} + \frac{h}{2} = 0$$

$$Q = \sqrt{\frac{2KD}{h}}$$

$$C(Q) = \sqrt{2KDh}$$

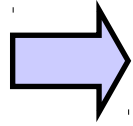


Holding cost per cycle =  $\frac{1}{2}hTQ$

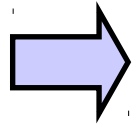


Cost per order of size  $Q = K + pQ$

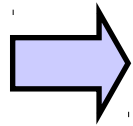
$$p \text{ Unit production cost}$$
$$T = Q / D \quad \text{or} \quad Q = T \cdot D$$



Total cost per cycle =  $K + pQ + \frac{1}{2}hTQ$



Average cost per time unit  $C(Q) = (K + pQ + \frac{1}{2}hTQ) / T$   
 $= KD / Q + pD + \frac{1}{2}hQ$

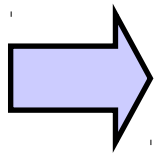


Find  $Q$  that minimizes average cost per time unit !

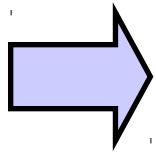
$$\frac{dC}{dQ} = 0 \Leftrightarrow \frac{-KD}{Q^2} + \frac{h}{2} = 0$$

$$Q = \sqrt{\frac{2KD}{h}}$$

$$C(Q) = \sqrt{2KDh} + pD$$



**Demand is not stationary but fluctuates over time: What to do?**



**Finite time horizon models**

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Wagner-Within Model

- Shortages are not permitted
- Starting inventory is zero
- Linear Holding cost  $h$
- Fixed order cost  $K$



$D_t$  Demand in period  $t$

$y_t$  Production in period  $t$

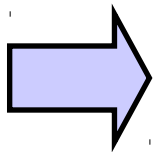
$x_t$  Inventory at the end of period  $t$

$\delta(y)$  1 if  $y > 0$ , 0 if  $y = 0$

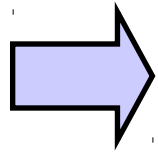
$$x_t = \sum_{j=1}^t (y_j - D_j)$$

$$\min \sum_{t=1}^T K_t \delta(y_t) + h_t x_t$$

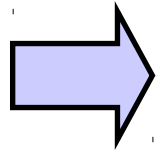
$$\begin{aligned} \text{s.t.} \quad x_t &= \sum_{j=1}^t (y_j - D_j) \quad \forall t = 1, \dots, T \\ x_t &\geq 0, x_0 = 0 \end{aligned}$$



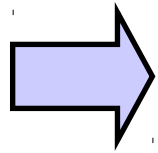
**Observation:  $y_t x_{t-1} = 0$  in optimal solution**



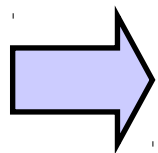
**Observation:  $y_t x_{t-1} = 0$  in optimal solution**



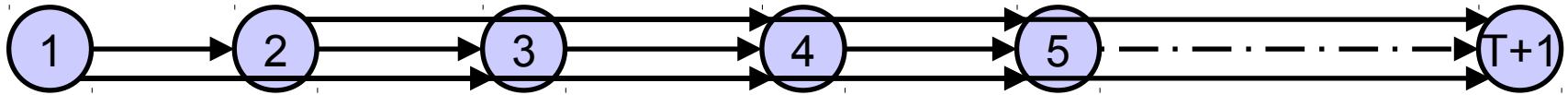
**$y_t > 0$  if  $x_{t-1} = 0$ , e.g., inventory zero**



**$y_t \in \{0, D_t, D_t + D_{t+1}, D_t + D_{t+1} + D_{t+2}, \dots\}$**

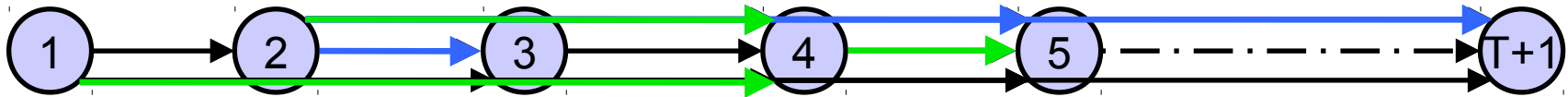


**Optimal Solution can be found by shortest path computation**



- Node for every point in time  $1, \dots, T+1$
- Arc  $(i, j)$  for all  $i < j$
- Length of arc  $(i, j)$  equals cost of ordering in period  $i$  to satisfy demand through period  $j-1$ :

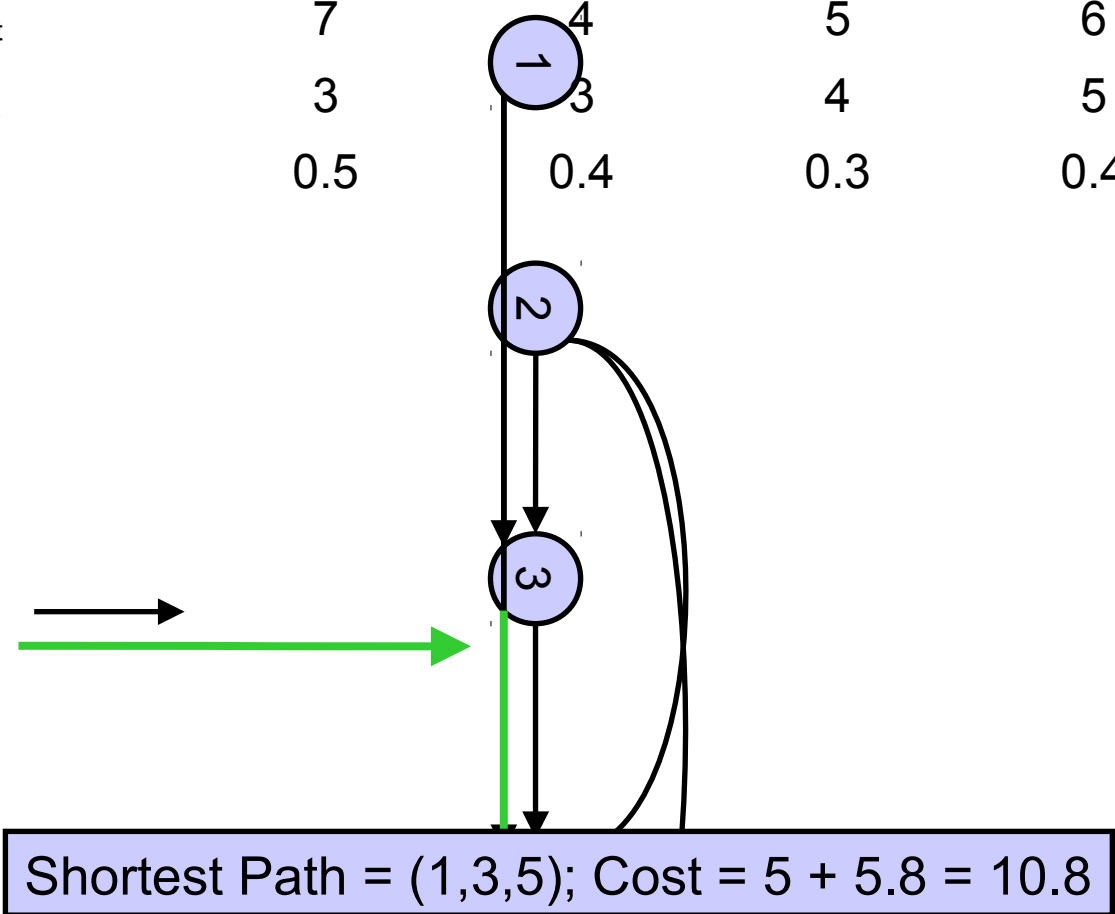
$$c_{ij} = K + \underbrace{\sum_{t=i}^{j-2} h_t \left( \underbrace{\sum_{u=t+1}^{j-1} D_u}_{\text{Inventory}} \right)}_{\text{Total Inventory Cost}}$$



- For every node  $i$  select at most one outgoing arc  $(i,j)$ :  
decide that order at time  $i$  must satisfy demand until period  $j-1$   
("no parallel stocks")
- For every node  $j$  with  $1 < j < T+1$ :  
(incoming arc selected  $\Leftrightarrow$  stock empty at end of period  $j-1$ )  
 $\Rightarrow$  (order at begin of period  $j \Leftrightarrow$  select outgoing arc)
- For node 1 select one outgoing arc  $\Leftrightarrow$  satisfy first demand
- For node  $T+1$  select one incoming arc  $\Leftrightarrow$  satisfy last demand

# Mathematical Tools for Engineering and Management

period	1	2	3	4	Arc	$c(i,j)$	$y(l)$
$D_t$	7	4	5	6	(1,2)	3	7
$K_t$	3	3	4	5	(1,3)	5	11
$h_t$	0.5	0.4	0.3	0.4	(1,4)	9.5	16
					(1,5)	16.7	22
					(2,3)	3	4
					(2,4)	5	9
					(2,5)	9.2	15
					(3,4)	4	5
					(3,5)	5.8	11
					(4,5)	5	6



**Example**

## Maximum Inventory Volume

- All arcs for which (Production – Demand of period  $i$ ) is too large have to be removed from network

## Maximum Batch Size

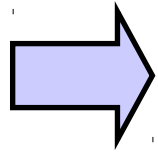
- Rule  $y_t x_{t-1} = 0$  does not hold anymore
- New Rule:  $y_t (B_t - y_t) x_{t-1} = 0$
- NP-hard problem

## Fixed Batch Size

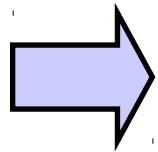
- Produce either 0 or  $B$  in each time period (all-or-nothing strategy)
- Known as Discrete Lot Sizing (DLS)

## Backordering

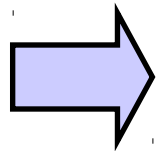
- Generalized efficient algorithm



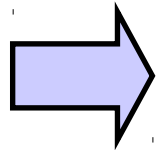
**Constant Demand is very easy**



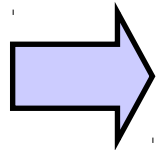
**Variable Demand can be solved by shortest path computation**



**Production limitations makes problem NP-hard**



**Demand is stochastic**



**Multi-product Lot-Sizing**

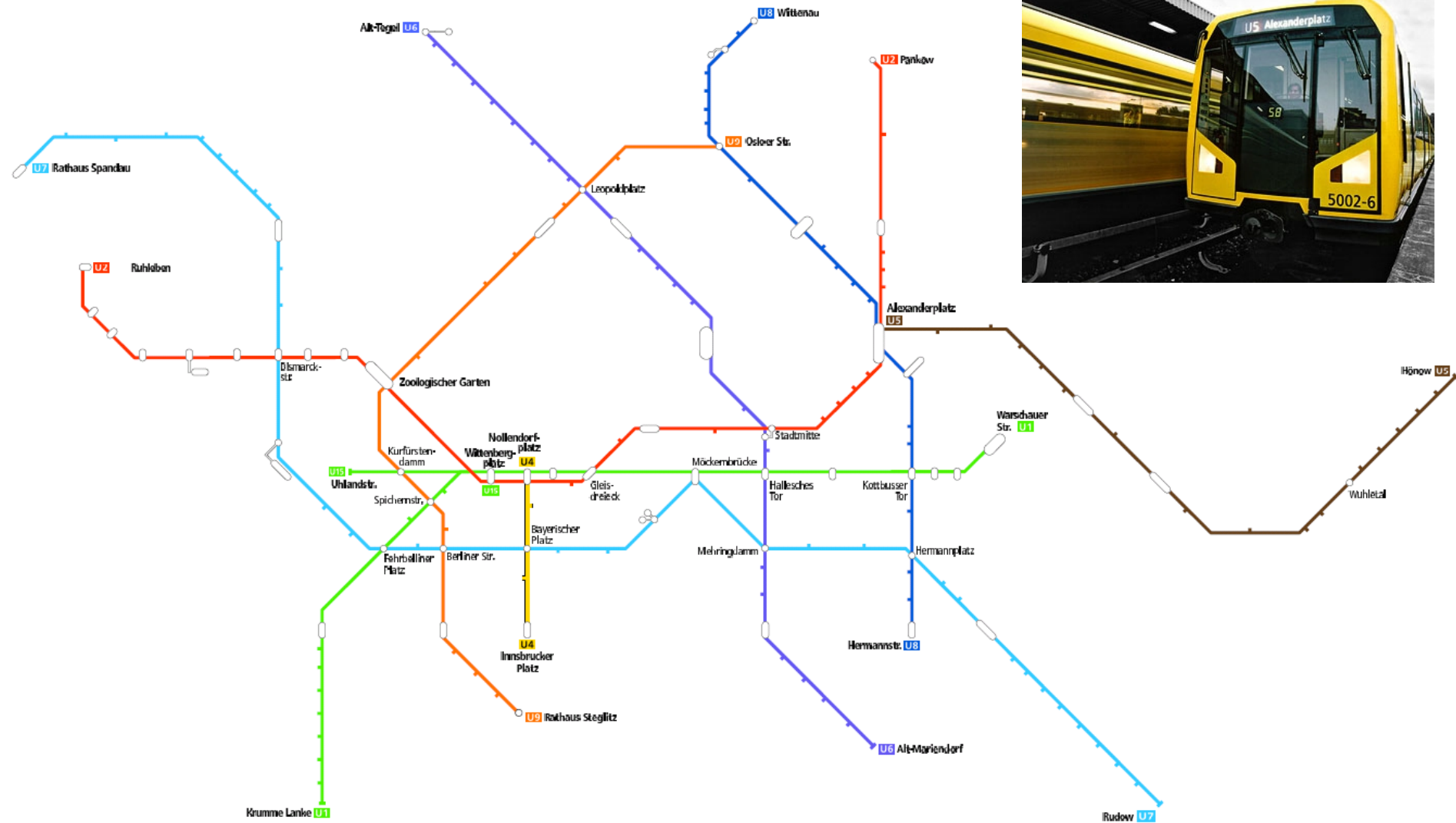
- 
- **Multi-criteria Optimization**
  - **Multi-criteria Linear Problem**
  - **Multi-criteria Integer Problem**
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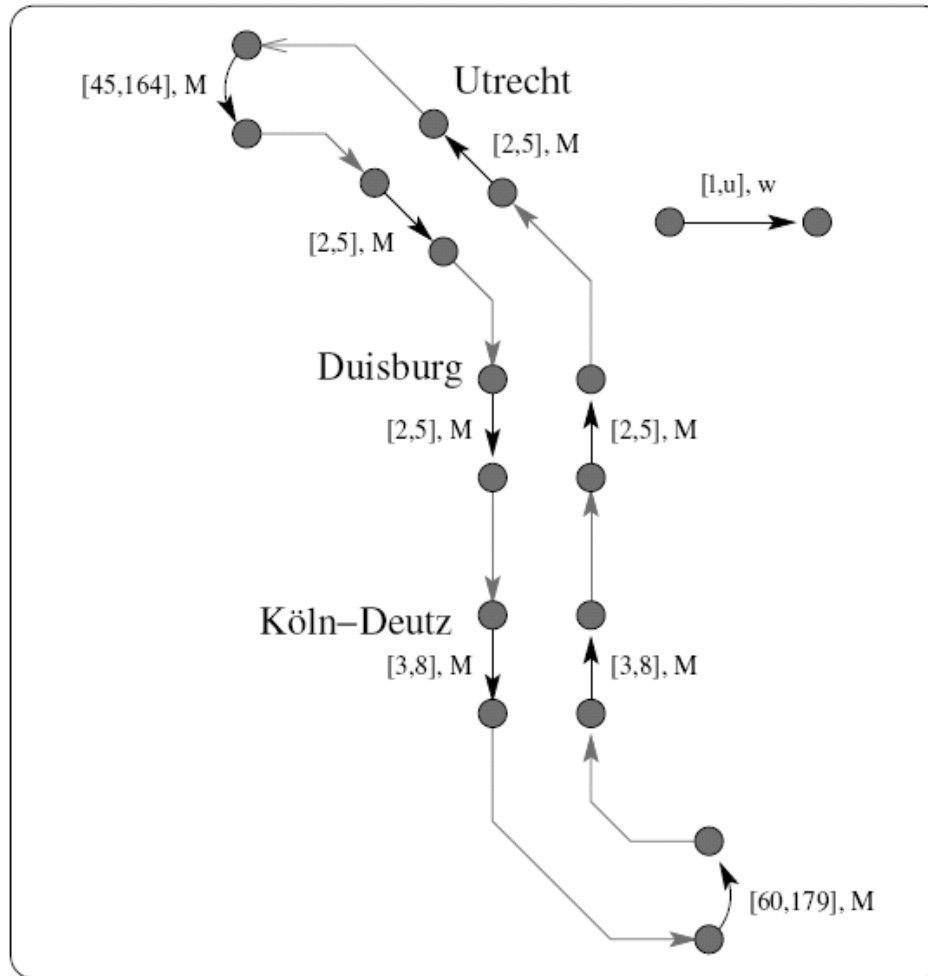


# Mathematical Tools for Engineering and Management

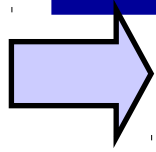
Zug	<b>RB</b> 27945 🚲	<b>RE</b> 33105 🚗	<b>IC</b> 2571 	<b>RB</b> 27949 🚲	<b>IR</b> 2285 🚲	<b>RE</b> 33107 🚗	<b>EC</b> 175 ◆	<b>RB</b> 27953 🚲
von		Rostock	Hamburg			Rostock	Aarhus	
Berlin-Spandau		11 15	<b>8 11 21</b>			13 15	<b>13 23</b>	
Berlin Zoologischer Garten		11 26	<b>11 35</b>		<b>13 02</b>	13 26	<b>13 35</b>	
Berlin Friedrichstr		11 33				13 33		
Berlin Alexanderplatz		11 36				13 36		
Berlin Ostbahnhof		11 41	<b>11 49</b>		<b>13 15</b>	13 41	<b>13 49</b>	
Berlin-Karlshorst		11 48				13 48		
Berlin-Schönefeld Flughafen ← 204		12 00	<b>12 06</b>		<b>13 31</b>	14 00	<b>14 06</b>	
Blankenfelde (Teltow-Fläming) 205		12 08				14 08		
Dahlewitz		12 10				14 10		
Rangsdorf		12 20				14 20		
Dabendorf		12 25				14 25		
Zossen		12 28				14 28		
Wünsdorf-Waldstadt		12 34				14 34		
Neuhof (b Zossen)		12 38				14 38		
Baruth (Mark)		12 45				14 45		
Klasdorf		12 49				14 49		
Golßen (Niederlausitz)		12 53				14 53		
Drahnsdorf		12 58				14 58		
Luckau-Uckro 205		13 04				15 04		
Walddrehna		13 12				15 12		
Doberlug-Kirchhain 205.215.520 7 ○		13 23			<b>14 19</b>	15 23		
Doberlug-Kirchhain		13 24			<b>14 23</b>	15 24		

# Mathematical Tools for Engineering and Management

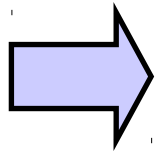




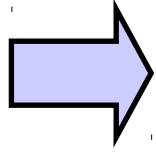
Problem: timetable has influence on passenger waiting time **AND** costs



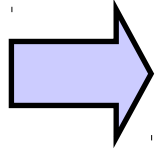
**Short passenger waiting times at transfers are a very natural goal**



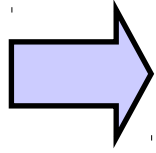
**Removing timetables with long waiting times, we could miss some of small cost**



**passenger waiting times should be small**



**But small number of trains is sought, too**



**Multi-criteria Optimization!**

- **Minimize number of trains**

- subject to restricted passenger waiting time

- **Minimize passenger waiting time**

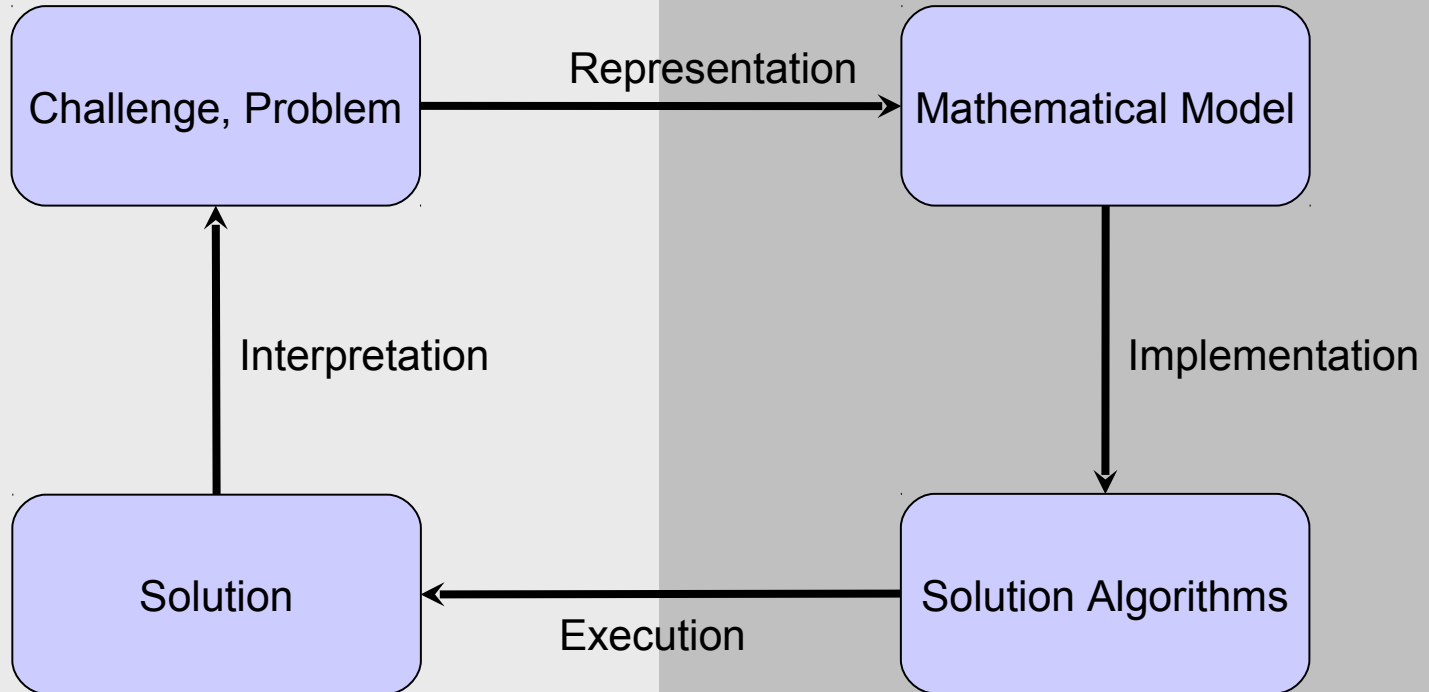
- subject to limited number of trains

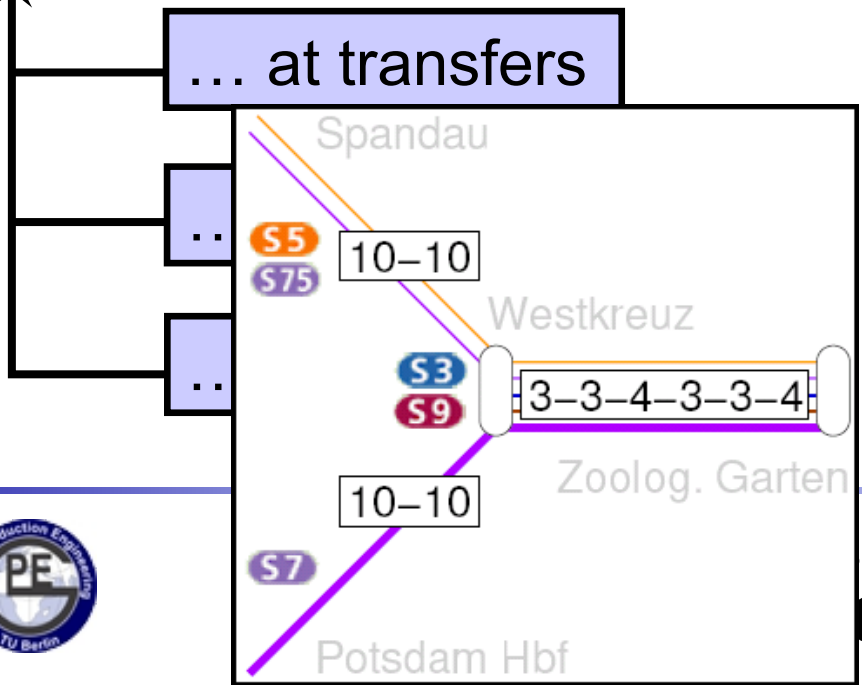
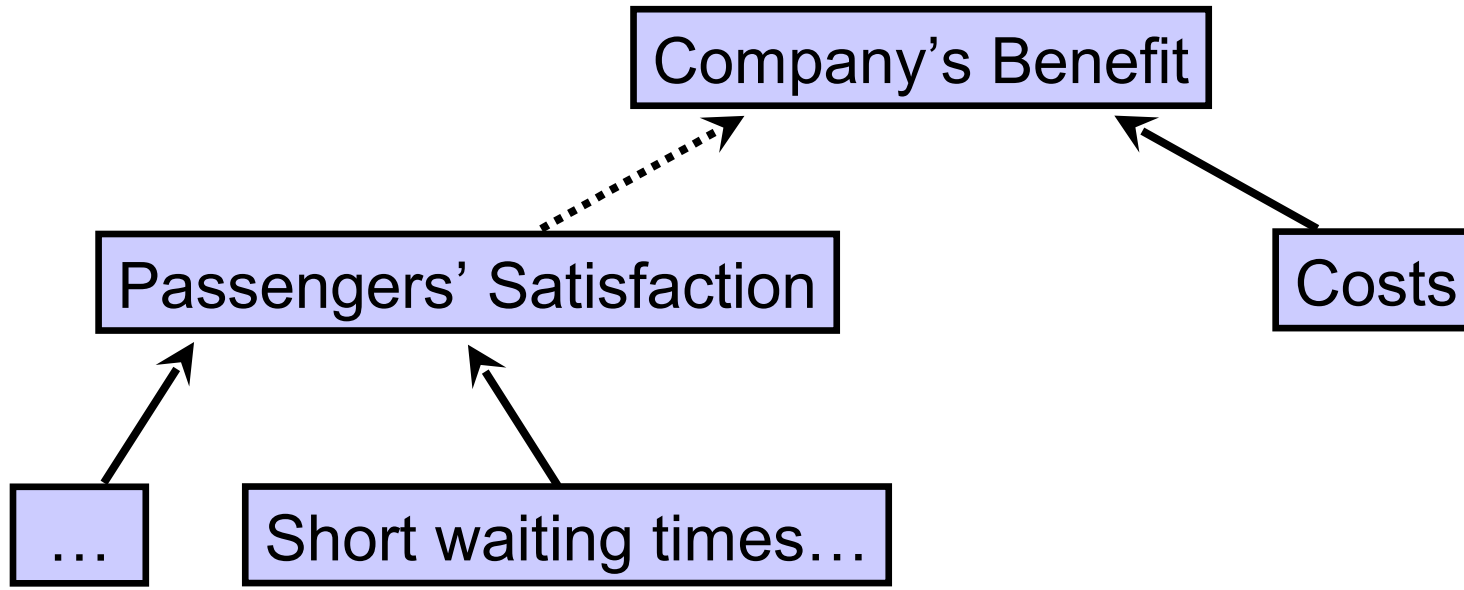


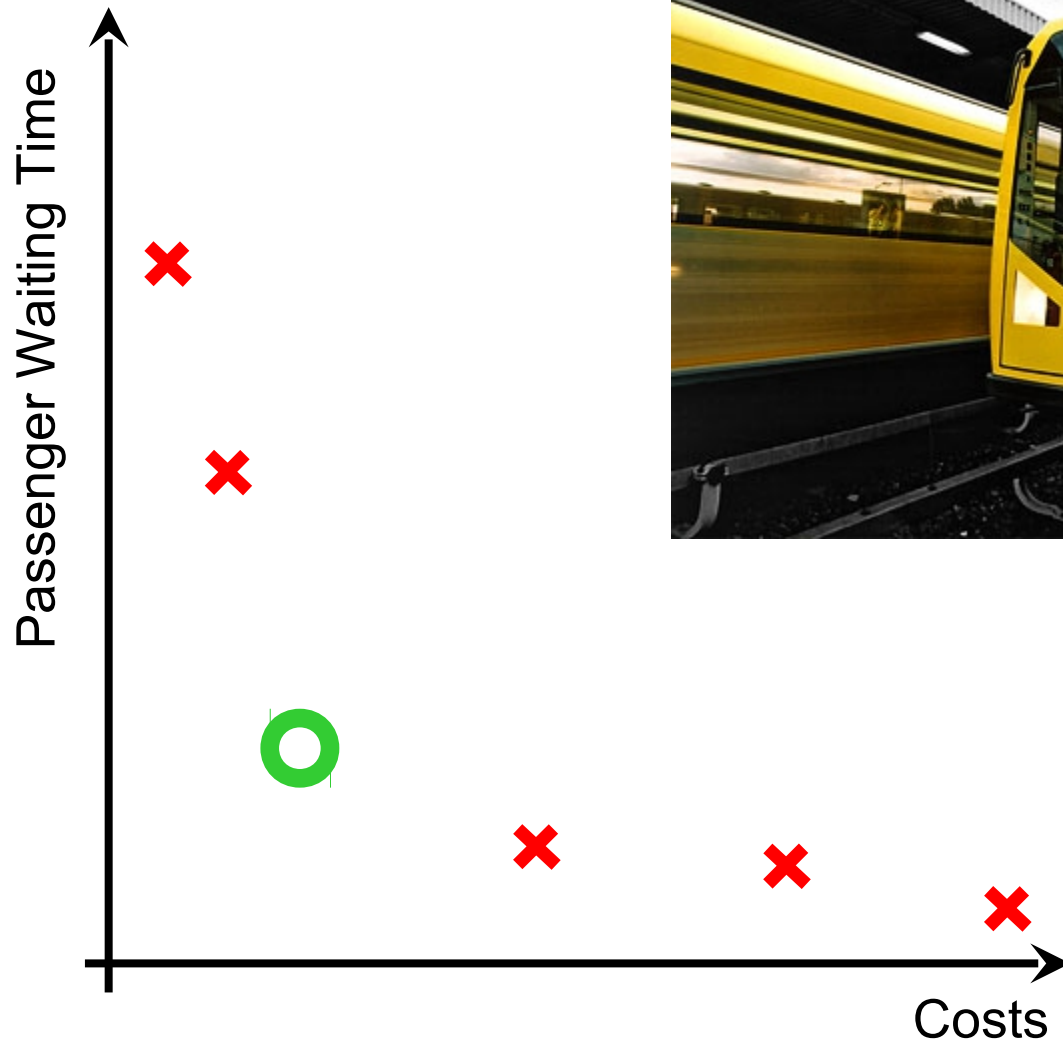
- **Minimize weighted sum of passenger waiting time and number of trains**

Real World

Mathematical World



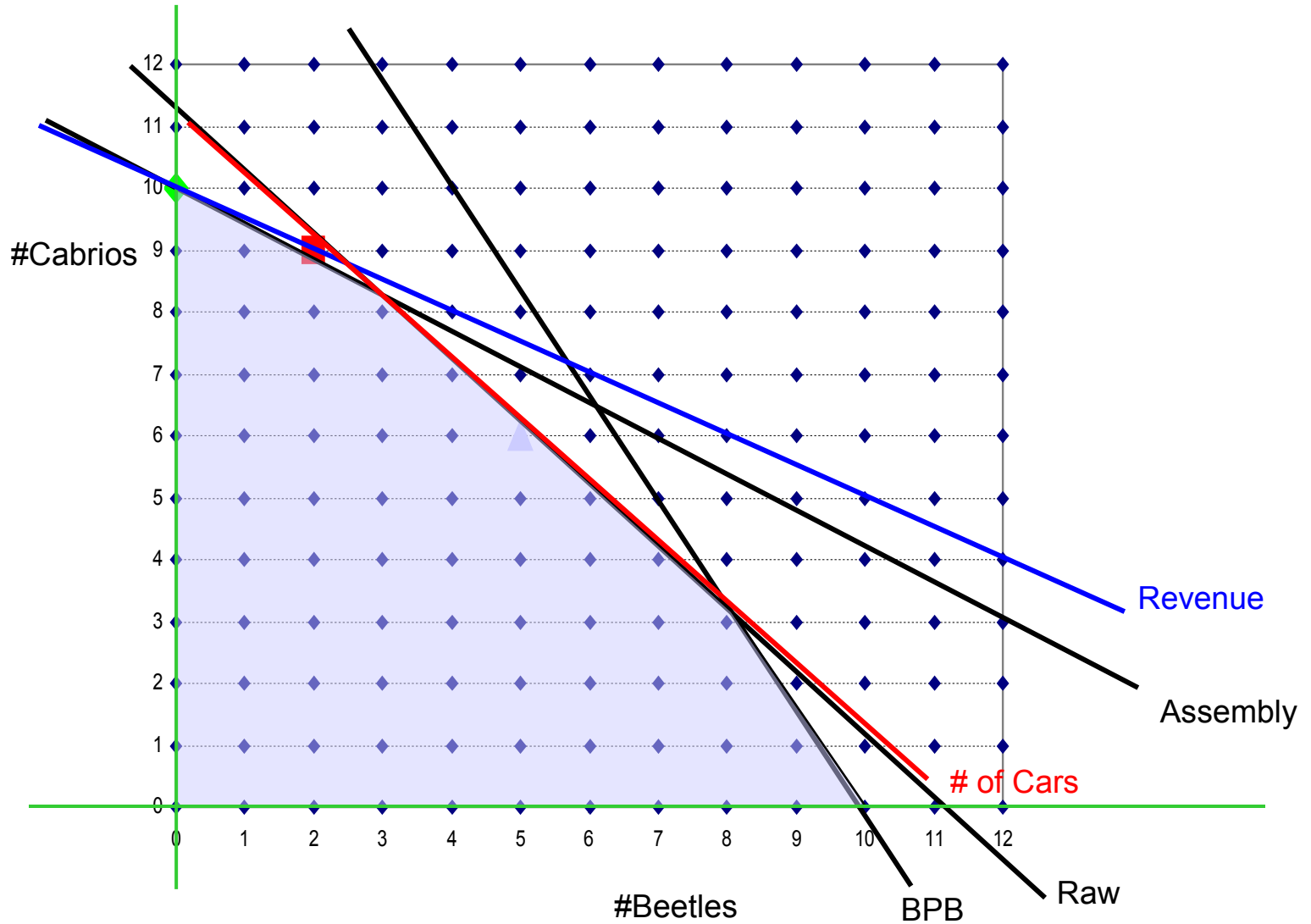






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- **Multi-criteria Optimization**
  - **Multi-criteria Linear Problem**
  - **Multi-criteria Integer Problem**
-

# Mathematical Tools for Engineering and Management



$$\max \sum_{j=1}^n c_j^1 x_j, \sum_{j=1}^n c_j^2 x_j, \dots, \sum_{j=1}^n c_j^q x_j$$

Multiple  
Objective  
functions

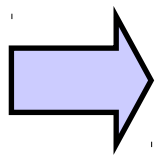
$$\text{s.t. } \sum_{j=1}^n a_{ij} x_j \leq b_i \quad i = 1, \dots, m$$
$$l_j \leq x_j \leq u_j \quad j = 1, \dots, n$$

A feasible solution  $\mathbf{x}$  is referred to as an **efficient (non-dominated) solution** if there is no feasible solution  $\mathbf{y}$  such that

$$\sum_{j=1}^n c_j^p y_j \geq \sum_{j=1}^n c_j^p x_j \quad p = 1, \dots, q$$

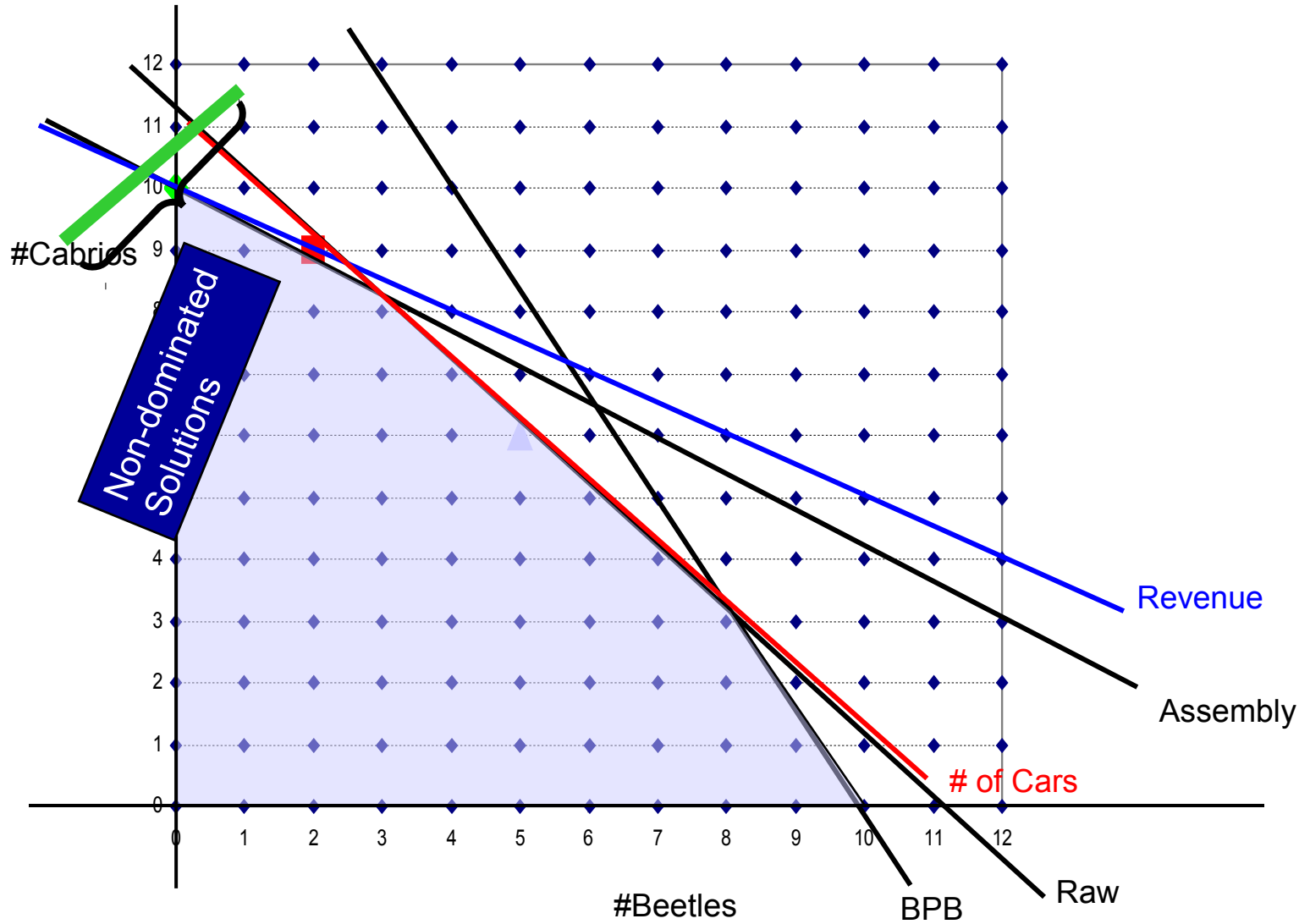
and

$$\sum_{j=1}^n c_j^r y_j > \sum_{j=1}^n c_j^r x_j \quad \text{for some } r, 1 \leq r \leq q$$



**No objective can be improved without reduction of one of the other objectives**

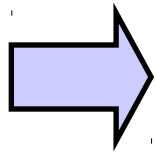
# Mathematical Tools for Engineering and Management



Combine all objectives into one objective by taking a linear combination

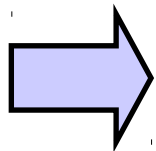
$$\max \sum_{p=1}^q \lambda^p \left[ \sum_{j=1}^n c_j^p x_j \right]$$

$$\lambda^1, \dots, \lambda^q > 0$$



**Single objective linear program**

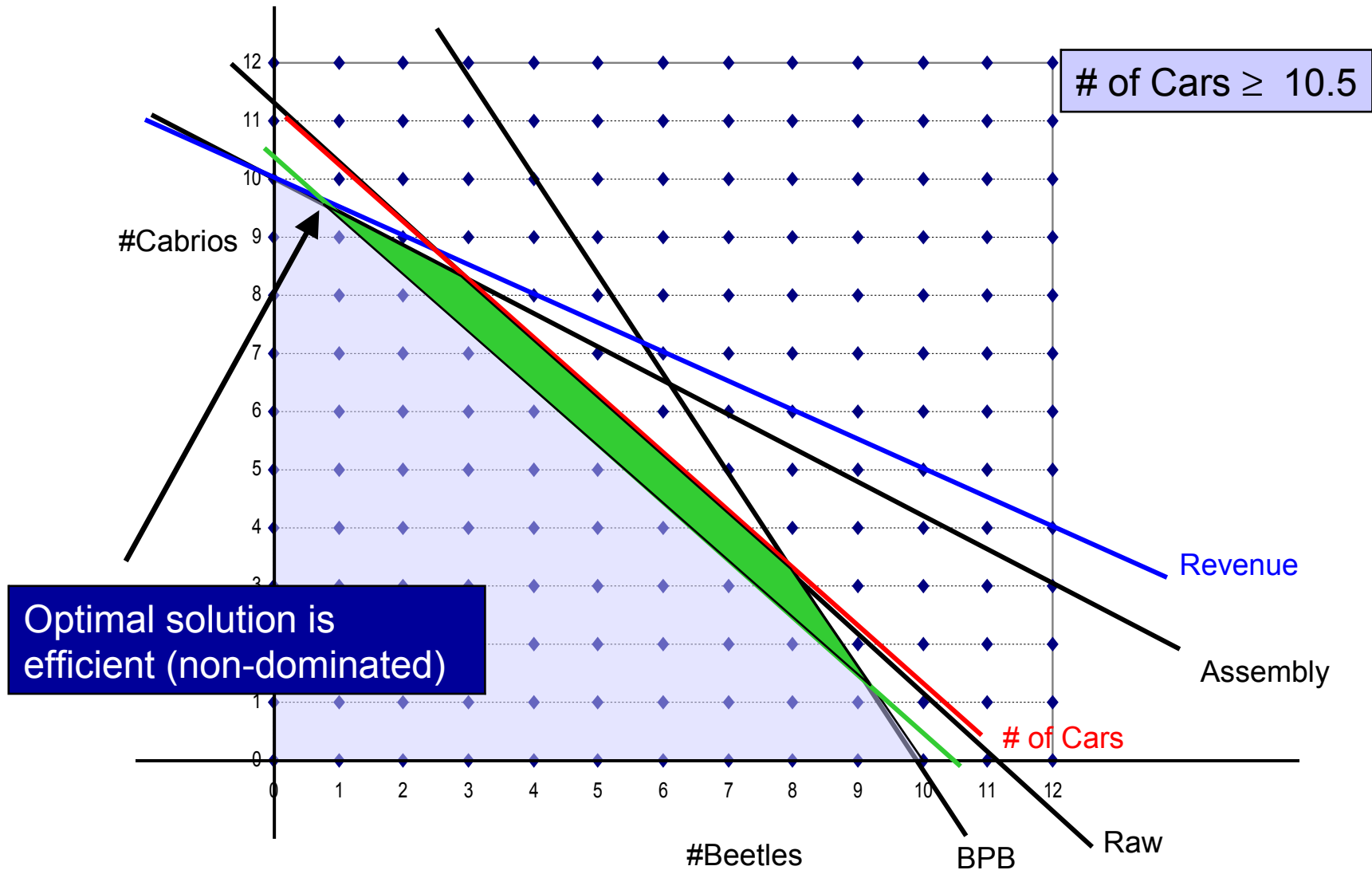
$$\max \sum_{j=1}^n \bar{c}_j x_j \quad \text{with} \quad \bar{c}_j = \sum_{p=1}^q \lambda^p c_j^p$$



**$x$  is efficient if and only if there exists  $\lambda_p$  such that  $x$  is optimal for single obj. LP**

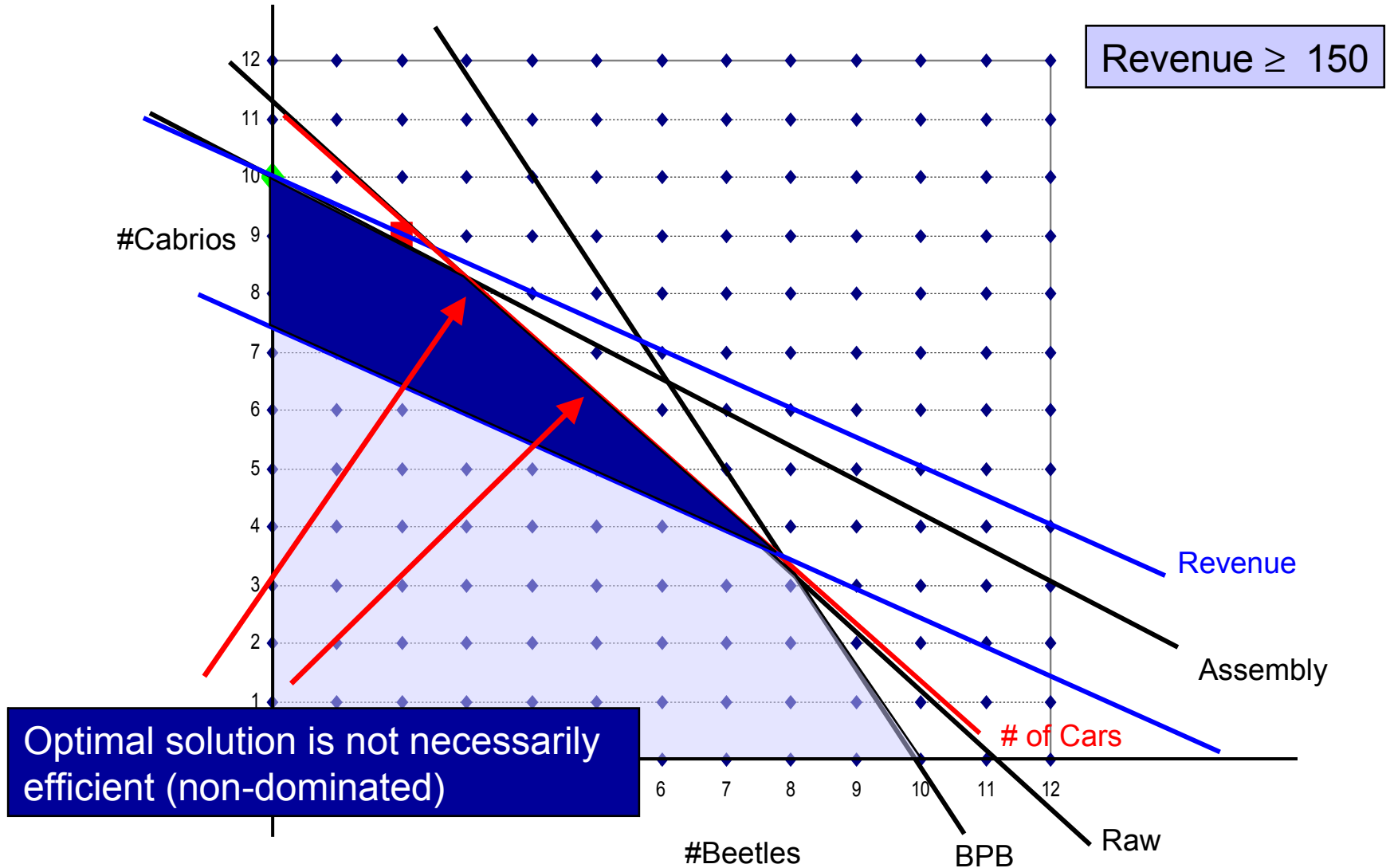
**Idea:** Maximize one objective subject to bounds on all other objectives

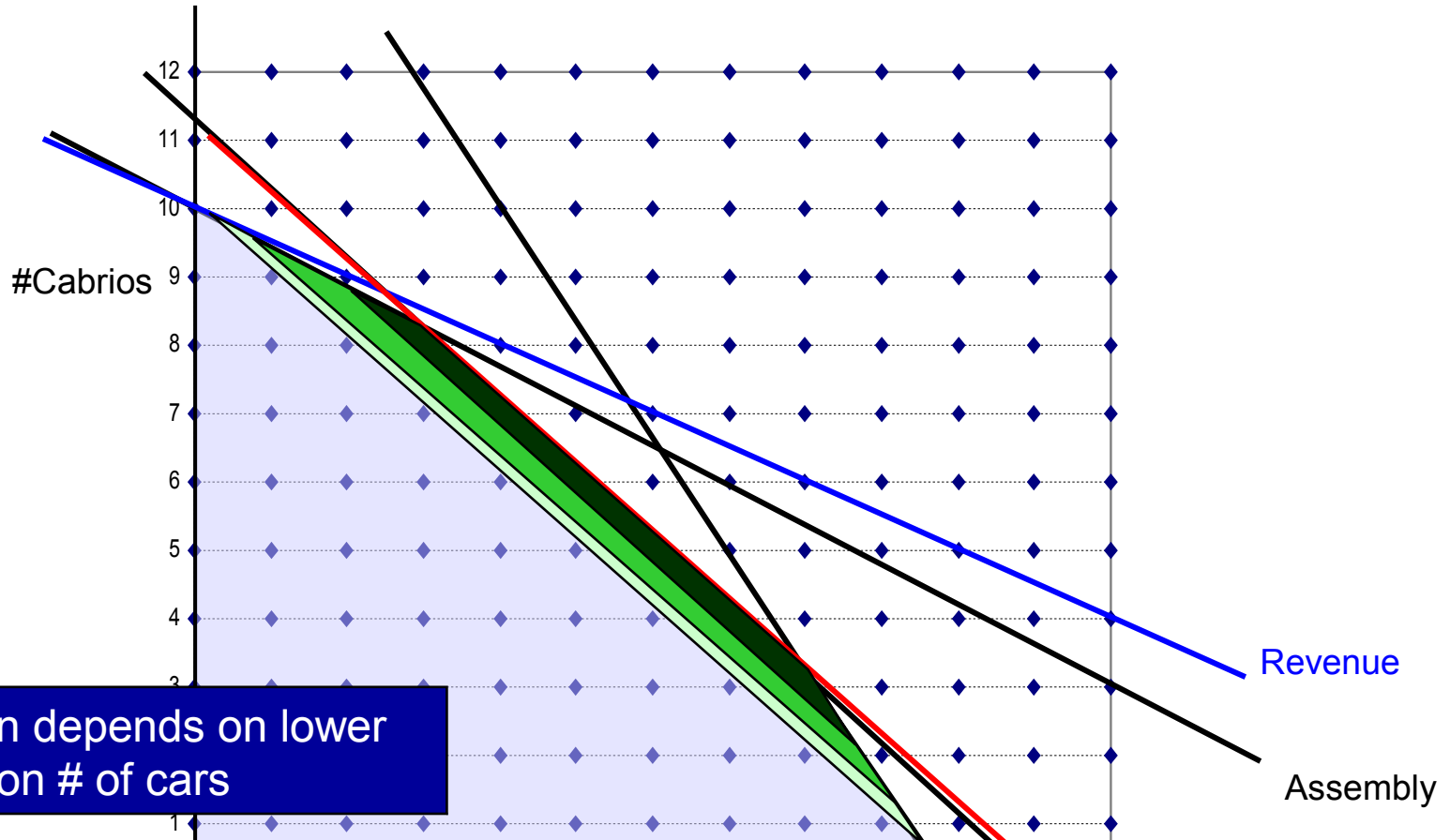
$$\begin{aligned} \max \quad & \sum_{j=1}^n c_j^r x_j && \text{r-th objective optimized} \\ \text{s.t.} \quad & \sum_{j=1}^n c_j^p x_j \geq L^p && p = 1, \dots, q, p \neq r \\ & && \text{Lower bound for p-th objective} \\ & \sum_{j=1}^n a_{ij} x_j \leq b_i && i = 1, \dots, m \\ & l_j \leq x_j \leq u_j && j = 1, \dots, n \end{aligned}$$





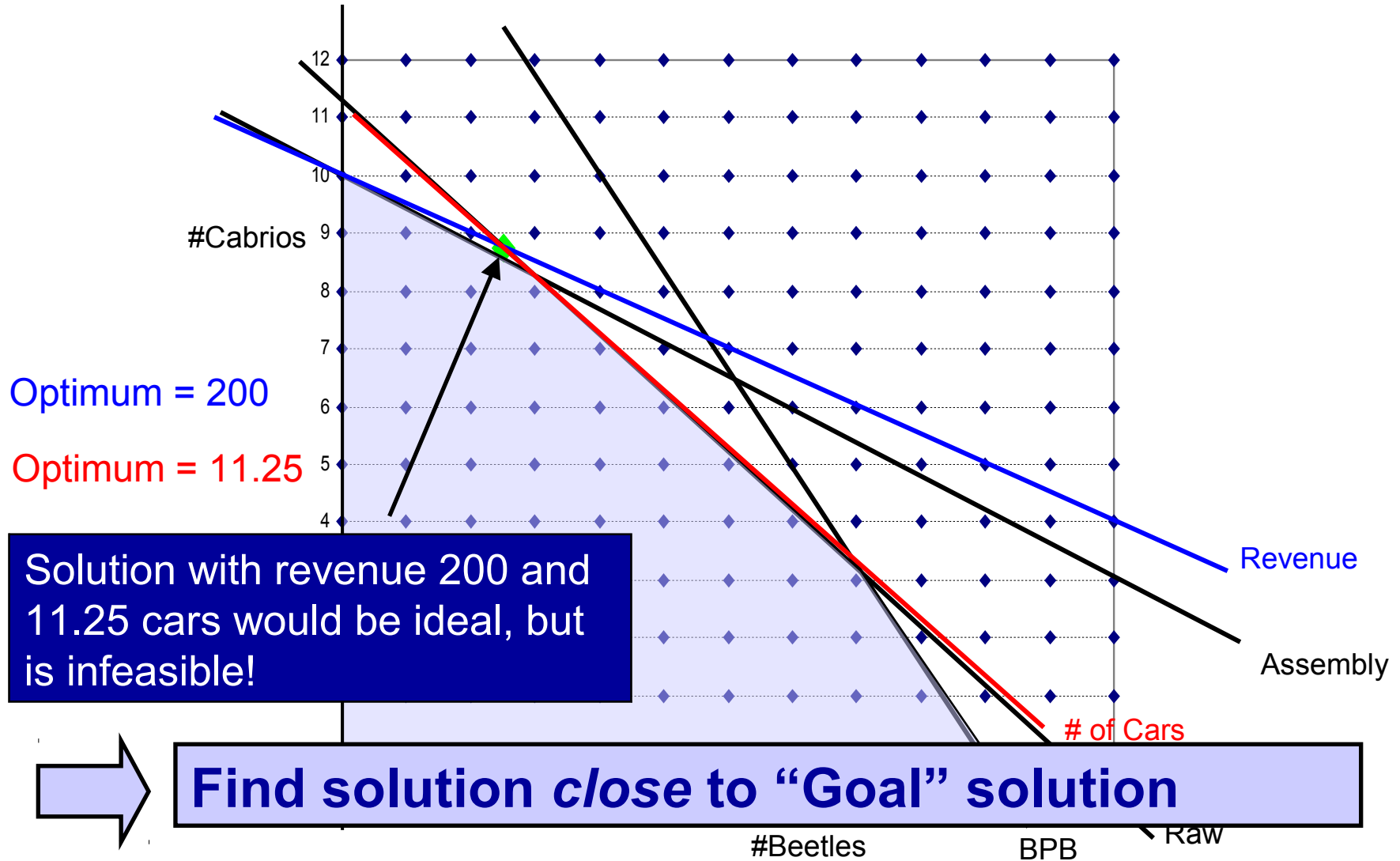
# Mathematical Tools for Engineering and Management

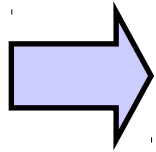




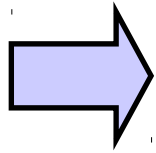
Solution depends on lower bound on # of cars

Trade-off between two/more objectives: decision support tool

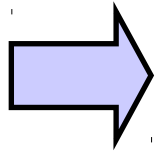




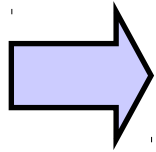
**Efficient (non-dominated) solutions**



**Method 1: Linear Combination of Objectives**

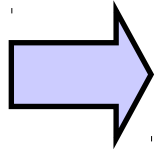


**Method 2: Single Objective with Constraints for other objectives**

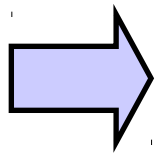


**Method 3: Goal Programming**

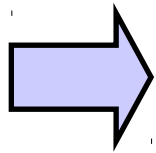
- 
- **Multi-criteria Optimization**
  - **Multi-criteria Linear Problem**
  - **Multi-criteria Integer Problem**
-



**Method 1: Linear Combination of Objectives**

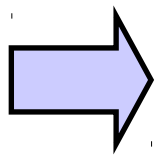


**Method 2: Single Objective with Constraints for other objectives**



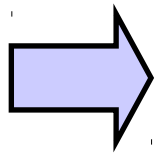
**Method 3: Goal Programming**

## Linear Programming



**x is efficient if and only if there exists  $\lambda_p$  such that x is optimal for single obj. LP**

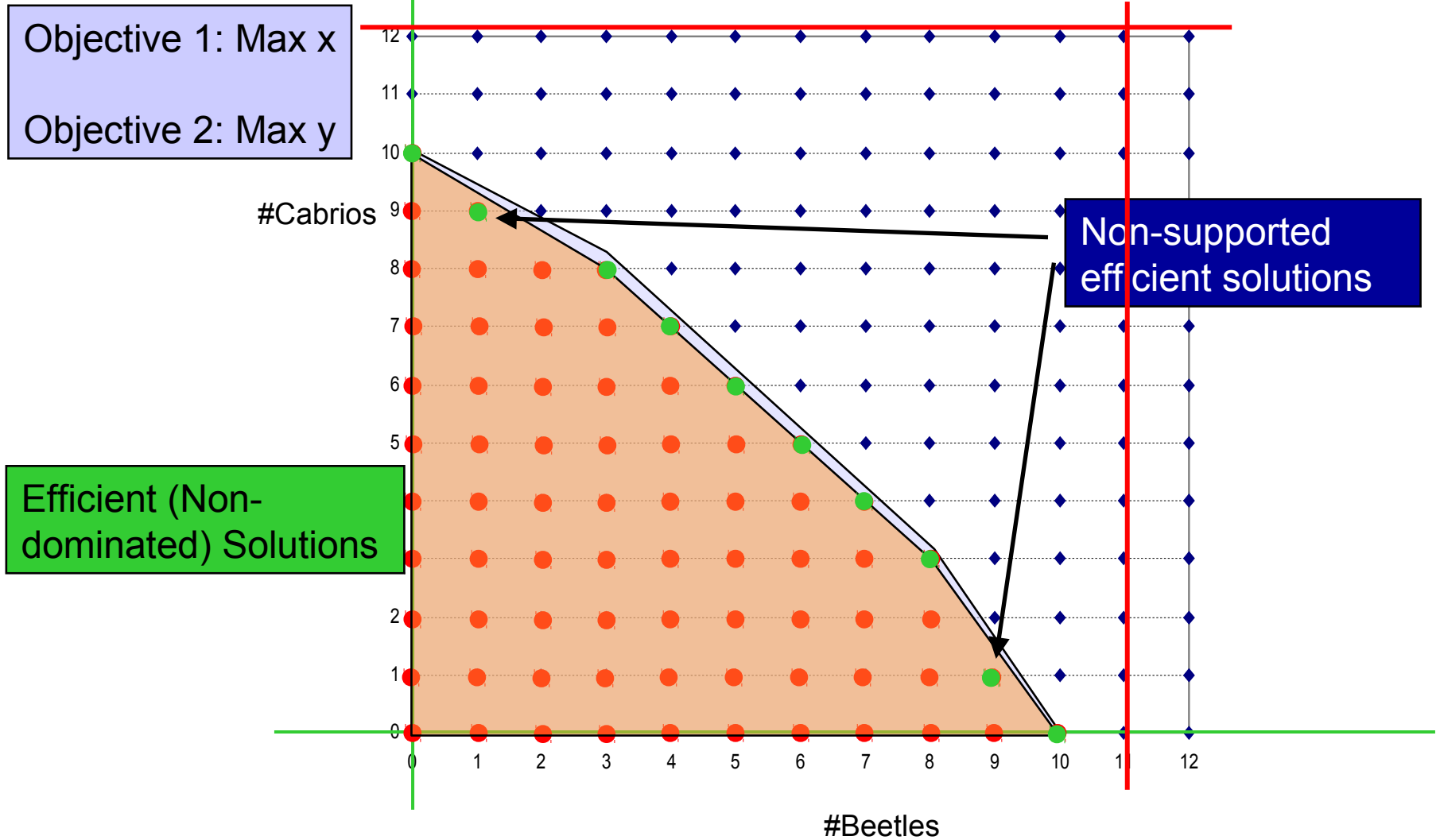
## Integer Programming



**There exist efficient solutions that are not optimal for any linear combination**

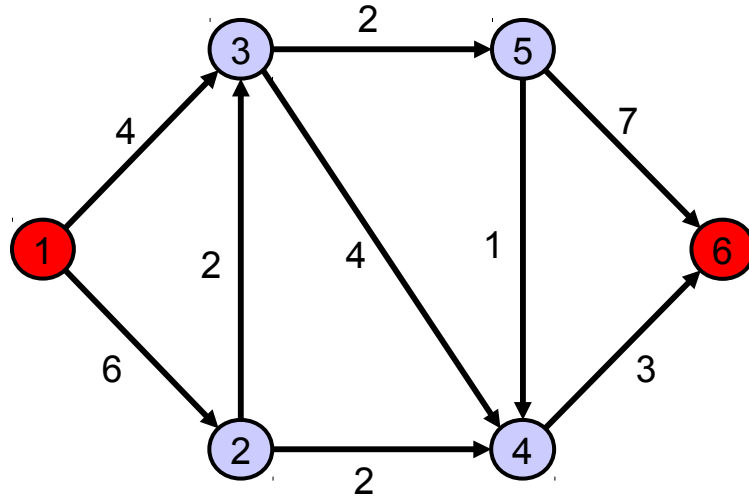


- **Supported efficient (SE)** solutions: efficient solutions that are optimal for a linear combination of objectives
- **Non-supported efficient (NE)** solutions: efficient solutions that are not optimal for any linear combination of objectives



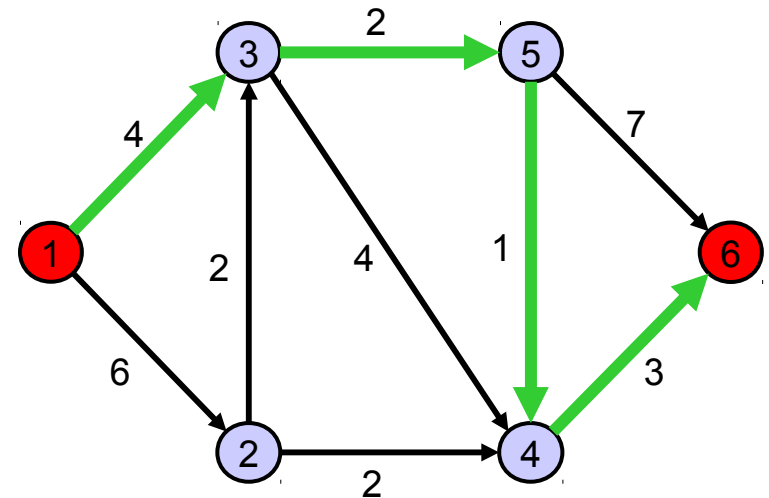


Shortest path from 1 to 6 ?

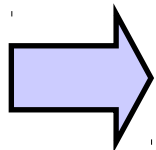


- Minimize Length of path from 1 to 6
- Minimize # of hops (= # of nodes on path)

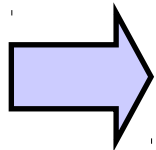
Solution:



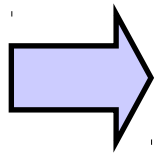
- Min Length = 10
- Min Hops = 4



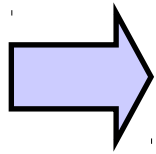
**Constrained Shortest Path Problem**



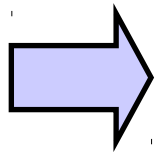
**NP-hard in general; polynomial for #hops**



**Existence of non-supporting efficient solutions**



**Extra Constraint(s) make(s) easy combinatorial problems often NP-hard**



**Many more techniques, in particular heuristics**