

DIFFERENTIAL GEOMETRY II: ANALYSIS AND GEOMETRY ON MANIFOLDS

Exercise Sheet 9

(Levi-Civita connection, geodesics)

due 8.1.2015

Exercise 1

5 points

Let (M, g) be a Riemannian manifold and $\tilde{g} = e^{2u}g$ for some smooth function $u: M \rightarrow \mathbb{R}$. Show that between the corresponding Riemannian connections the following relation holds:

$$\tilde{\nabla}_X Y = \nabla_X Y + du(X)Y + du(Y)X - g(X, Y)\text{grad } u.$$

Here $\text{grad } u \in \Gamma(\text{TM})$ is the vector field uniquely determined by the condition $du(X) = g(\text{grad } u, X)$ for all $X \in \Gamma(\text{TM})$.

Exercise 2

5 points

Let M be a Riemannian manifold, $\gamma: I \rightarrow M$ a curve, which is parametrized with constant speed, and $f: M \rightarrow M$ an isometry, which fixes γ , i.e. $f \circ \gamma = \gamma$. Further, let

$$\ker(\text{Id} - d_{\gamma(t)}f) = \mathbb{R}\dot{\gamma}(t), \text{ for all } t.$$

Then γ is a geodesic.

Exercise 3

5 points

The Poincaré half-plane model of the n -dimensional hyperbolic space is the half-plane $\mathbb{H}_+^n = \mathbb{R}^{n-1} \times \mathbb{R}_{>0}$ equipped with the metric $\frac{1}{x_n^2} \langle \cdot, \cdot \rangle$, where $\langle \cdot, \cdot \rangle$ denotes the Euclidean metric of \mathbb{R}^n .

- Show that $B \rightarrow \mathbb{H}_+^n$, $(\tilde{x}, x_n) \mapsto 2 \frac{(\tilde{x}, 1-x_n)}{(|\tilde{x}, 1-x_n|^2)} - e_n$ is an isometry, where $B = \{x \in \mathbb{R}^n \mid |x| < 1\}$ is equipped with the metric g of the Poincaré ball-model, i.e. $g_x(\cdot, \cdot) = \frac{4\langle \cdot, \cdot \rangle}{(1-|x|^2)^2}$.
- Show that the maps $z \mapsto \frac{az+b}{cz+d}$ for all $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(2, \mathbb{R})$ define orientation preserving isometries of $\mathbb{H}_+^2 \subset \mathbb{C}$, and that this defines a group isomorphism between the isometries of \mathbb{H}_+^2 and $\text{SL}(2, \mathbb{R})/\{\pm 1\}$.
- Show that all geodesics of \mathbb{H}_+^2 are either rays or semi-circular arcs, which are perpendicular to the real axis $\mathbb{R} \times \{0\}$.