

Lamé coefficients for 3D confocal quadrics
(and 1st and 2nd fundamental forms)

$$H_1^2 = \langle \partial_1 \mathbf{x}, \partial_1 \mathbf{x} \rangle = (\partial_1 x)^2 + (\partial_1 y)^2 + (\partial_1 z)^2$$

$$= \frac{1}{4} \left(\frac{x^2}{(u_1+a)^2} + \frac{y^2}{(u_1+b)^2} + \frac{z^2}{(u_1+c)^2} \right) = Z.$$

$$x^2 = \frac{(u_1+a)(u_2+a)(u_3+a)}{(a-b)(a-c)} \Rightarrow 2x \partial_1 x = \partial_1(x^2) = \frac{x^2}{u_1+a} \Rightarrow \partial_1 x = \frac{x}{2(u_1+a)}$$

Lemma: For $-a < u_1 < -b < u_2 < -c < u_3$ and $\mathbf{x}(u_1, u_2, u_3) = \begin{pmatrix} x(u_1, u_2, u_3) \\ y(u_1, u_2, u_3) \\ z(u_1, u_2, u_3) \end{pmatrix}$

with $\frac{x^2}{u_i+a} + \frac{y^2}{u_i+b} + \frac{z^2}{u_i+c} = 1$, $i=1,2,3$.

Then $\left\{ \begin{array}{l} \frac{x^2}{(u_1+a)^2} + \frac{y^2}{(u_1+b)^2} + \frac{z^2}{(u_1+c)^2} = \frac{(u_1-u_2)(u_1-u_3)}{(u_1+a)(u_1+b)(u_1+c)} \\ \frac{x^2}{(u_2+a)^2} + \frac{y^2}{(u_2+b)^2} + \frac{z^2}{(u_2+c)^2} = \frac{(u_2-u_1)(u_2-u_3)}{(u_2+a)(u_2+b)(u_2+c)} \\ \frac{x^2}{(u_3+a)^2} + \frac{y^2}{(u_3+b)^2} + \frac{z^2}{(u_3+c)^2} = \frac{(u_3-u_1)(u_3-u_2)}{(u_3+a)(u_3+b)(u_3+c)} \end{array} \right.$

Proof:

• u_1, u_2, u_3 are the roots of $f(\lambda) = \frac{x^2}{\lambda+a} + \frac{y^2}{\lambda+b} + \frac{z^2}{\lambda+c} - 1$

$\hookrightarrow f(\lambda) = -\frac{(\lambda-u_1)(\lambda-u_2)(\lambda-u_3)}{(\lambda+a)(\lambda+b)(\lambda+c)}$

• differentiate both expressions for f w.r.t. u_i :

$$\frac{\partial_1(x^2)}{\lambda+a} + \frac{\partial_1(y^2)}{\lambda+b} + \frac{\partial_1(z^2)}{\lambda+c} = \frac{(\lambda-u_2)(\lambda-u_3)}{(\lambda+a)(\lambda+b)(\lambda+c)}$$

$$\Leftrightarrow \frac{x^2}{(u_1+a)(\lambda+a)} + \frac{y^2}{(u_1+b)(\lambda+b)} + \frac{z^2}{(u_1+c)(\lambda+c)} = \dots$$

$$\partial_1(x^2) = \frac{x^2}{u_1+a}$$

$$\Rightarrow \frac{x^2}{(u_1+a)^2} + \frac{y^2}{(u_1+b)^2} + \frac{z^2}{(u_1+c)^2} = \frac{(u_1-u_2)(u_1-u_3)}{(u_1+a)(u_1+b)(u_1+c)}$$

$$\lambda = u_1$$

□

More generally: for $-a_1 < u_1 < -a_2 < u_2 < \dots < -a_N < u_N$ and $\{u_1, \dots, u_N\}$

$$\text{with } \sum_{k=1}^N \frac{x_k^2}{u_i + a_k} = 1, \quad i = 1, \dots, N$$

$$\text{Then } \sum_{k=1}^N \frac{x_k^2}{(u_i + a_k)^2} = \frac{\prod_{m \neq i} (u_i - u_m)}{\prod_{m=1}^N (u_i + a_m)}, \quad i = 1, \dots, N$$

Thus, the Lamé coefficients are given by:

$$H_1^2 = \frac{1}{4} \frac{(u_1-u_2)(u_1-u_3)}{(u_1+a)(u_1+b)(u_1+c)}, \quad H_2^2 = \frac{1}{4} \frac{(u_2-u_1)(u_2-u_3)}{(u_2+a)(u_2+b)(u_2+c)}$$

$$H_3^2 = \frac{1}{4} \frac{(u_3-u_1)(u_3-u_2)}{(u_3+a)(u_3+b)(u_3+c)}$$

In particular,

$$\frac{E_{12}}{G_{12}} = \frac{H_1^2}{H_2^2} = - \frac{u_1-u_3}{(u_1+a)(u_1+b)(u_1+c)} \cdot \frac{(u_2+a)(u_2+b)(u_2+c)}{u_2-u_3}$$

$$I_{12} = \begin{pmatrix} E_{12} & 0 \\ 0 & G_{12} \end{pmatrix}$$

Generally,

$$\frac{E_{ij}}{G_{ij}} = \frac{H_i^2}{H_j^2} = - \frac{\alpha_{jk}(u_j, u_k)}{\alpha_{ik}(u_j, u_k)} \quad \text{with } \alpha_{lm}(u_l, u_m) = \frac{(u_l+a)(u_l+b)(u_l+c)}{u_l-u_m}$$

and thus, all coordinate surfaces (i.e. quadrics) are isothermic surfaces (but we can't reparametrize the entire confocal system in such a way that all

coordinate surfaces are parametrized isothermally at the same time)

Let us now compute the 2nd fundamental forms of the coordinate surfaces:

$$e_{12} = \frac{\partial_3(H_1^2)}{H_3} = -\frac{1}{4H_3} \cdot \frac{u_1 - u_2}{(u_1+a)(u_1+b)(u_1+c)}$$

$$g_{12} = \frac{\partial_3(H_2^2)}{H_3} = -\frac{1}{4H_3} \cdot \frac{u_2 - u_1}{(u_2+a)(u_2+b)(u_2+c)}$$

$$\mathbb{II}_{12} = \begin{pmatrix} e_{12} & 0 \\ 0 & g_{12} \end{pmatrix}$$

Where are the umbilic points on the quadrics (coordinate surfaces)?

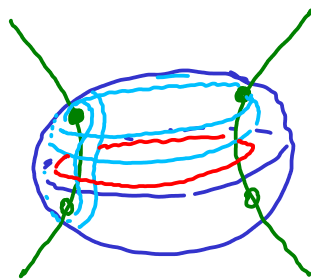
$$K_1 = \frac{e_{12}}{E_{12}} = -\frac{1}{4H_3} \cdot \frac{u_1 - u_2}{(u_1+a)(u_1+b)(u_1+c)} \cdot \frac{4(u_1+a)(u_1+b)(u_1+c)}{(u_1-u_2)(u_1-u_3)} = \frac{-1}{H_3(u_1-u_3)}$$

$$K_2 = \frac{g_{12}}{G_{12}} = -\frac{1}{4H_3} \cdot \frac{u_2 - u_1}{(u_2+a)(u_2+b)(u_2+c)} \cdot \frac{4(u_2+a)(u_2+b)(u_2+c)}{(u_2-u_1)(u_2-u_3)} = \frac{-1}{H_3(u_2-u_3)}$$

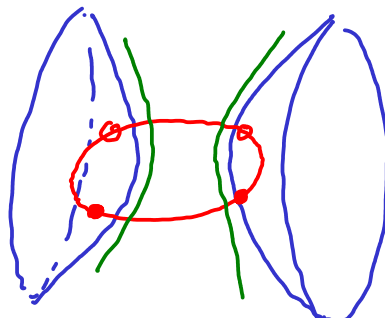
$$K_1 = K_2 \iff \frac{-1}{H_3(u_1-u_3)} = \frac{-1}{H_3(u_2-u_3)} \iff u_1 = u_2 \iff u_1 = u_2 = -b$$

(point on the focal hyperbola)

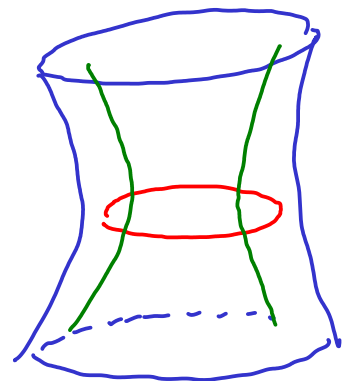
Generally: The umbilic points are the intersection points of the quadric with its focal conics.



4 umbilic points



4 umbilic points



Let us now have a look at the quotients of the coefficients of the 2nd fundamental form:

$$\frac{e_{12}}{g_{12}} = -\frac{(u_2+a)(u_2+b)(u_2+c)}{(u_1+a)(u_1+b)(u_1+c)}$$

Generally,

$$\frac{e_{ij}}{g_{ij}} = - \frac{\beta_j(u_j)}{\beta_i(u_i)}, \quad \beta_i(u_i) = (u_i+a)(u_i+b)(u_i+c).$$

How do the coefficients of the 2nd fundamental form change under reparametrization along the coordinate lines $u_i \rightarrow u_i(s_i)$

$$\begin{aligned} \tilde{e}_{12}(s_1, s_2) &= \left\langle \frac{\partial \mathcal{P}}{\partial s_1}, \frac{\partial \mathcal{X}}{\partial s_1} \right\rangle = \left\langle \frac{du_1}{ds_1} \frac{\partial \mathcal{P}}{\partial u_1}, \frac{du_1}{ds_1} \frac{\partial \mathcal{X}}{\partial u_1} \right\rangle = u_1'(s_1)^2 \left\langle \frac{\partial \mathcal{P}}{\partial u_1}, \frac{\partial \mathcal{X}}{\partial u_1} \right\rangle \\ &= u_1'(s_1)^2 e_{12}(u_1(s_1), u_2(s_2)) \end{aligned}$$

Thus, the quotient changes by $\underbrace{>0}_{>0} \underbrace{>0}_{>0} \underbrace{<0}_{<0}$

$$\frac{\tilde{e}_{12}}{\tilde{g}_{12}} = \frac{(u_1')^2 e_{12}}{(u_2')^2 g_{12}} = - \frac{(u_1')^2 \underbrace{(u_2+a)(u_2+b)(u_2+c)}_{>0}}{(u_2')^2 \underbrace{(u_1+a)(u_1+b)(u_1+c)}_{<0}}$$

$$[-a < u_1 < -b < u_2 < -c < u_3]$$

If we choose

$$\begin{aligned} (u_1')^2 &= (u_1+a)(u_1+b)(u_1+c) > 0 \\ (u_2')^2 &= -(u_2+a)(u_2+b)(u_2+c) > 0 \\ (u_3')^2 &= (u_3+a)(u_3+b)(u_3+c) > 0 \end{aligned}$$

differential equations for Weierstrass- p -function (in particular they can be solved by elliptic functions)

we obtain

$$\frac{\tilde{e}_{12}}{\tilde{g}_{12}} = 1, \quad \frac{\tilde{e}_{13}}{\tilde{g}_{13}} = -1, \quad \frac{\tilde{e}_{23}}{\tilde{g}_{23}} = 1,$$

thus up to sign we can make all 2nd fundamental forms of the coordinate surfaces "conformal". (the parametrization we derived using Jacobi elliptic functions has exactly this property)