

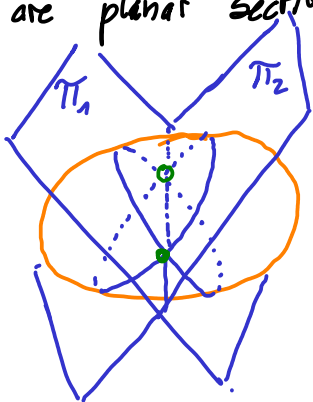
circles and spheres

- $Q \subset \mathbb{RP}^3 \subset \mathbb{CP}^3$ quadric.

Q sphere $\Leftrightarrow Z \subset Q$ where $Z: x_1^2 + x_2^2 + x_3^2 = 0, x_4 = 0$

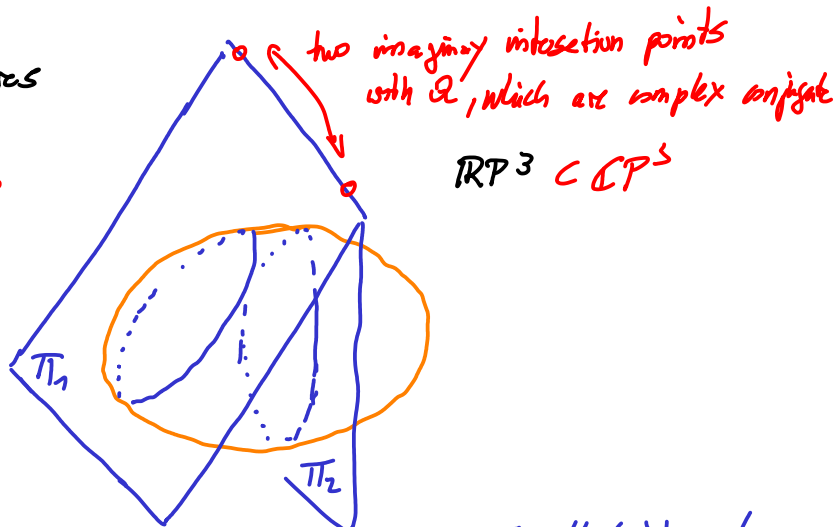
- circles are planar sections of spheres

- generally



$\mathbb{RP}^3 \subset \mathbb{CP}^3$

two planes π_1, π_2 that intersect in a line, which intersects Q in 2 points



$\mathbb{RP}^3 \subset \mathbb{CP}^3$

two planes π_1, π_2 that intersect in a line, which doesn't intersect Q

in \mathbb{CP}^3 these two cases coincide:

- a line always has two intersection points (or one double intersection point) with a quadric
- if the intersection points are not real, they must be complex conjugate (and this case there are always two intersection points)

- thus, for a sphere, a planar section must intersect Z in two complex conjugate points

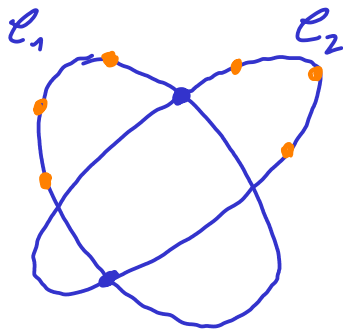
this gives us: C conic in some plane in \mathbb{RP}^3

" \Rightarrow " C circle $\Rightarrow C$ contains two points of Z

- " \Leftarrow " if C contains two points of Z ,

we need to show that there exists a quadric that contains C and Z

for two conics that intersect in two points there always exists a pencil of quadrics containing the two conics:



CP²

choose 3 points on each conic
 \hookrightarrow 6 points determine a pencil of quadrics, each quadric containing C_1 and C_2

- alternative approach by normalizing the plane of the circle
 $C \subset \mathbb{P}^2$ conic in $\mathbb{R}P^3$

apply a similarity transformation (projective transformation that preserves \mathcal{Z})
 to normalize \mathbb{P}^2 , e.g. $\mathbb{P}^2: x_3 = 0$

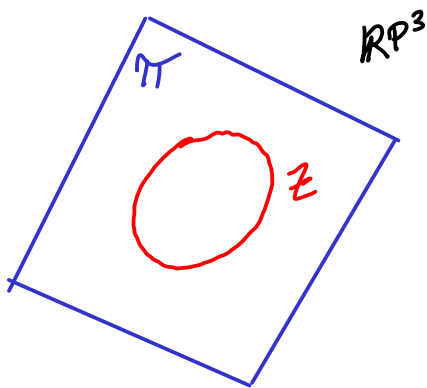
restrict the problem to the plane \mathbb{P}^2 :

C : quadratic equation in 3 variables x_1, x_2, x_4

\mathcal{Z} : $x_1^2 + x_2^2 = 0, x_4 = 0$ (two imaginary points at infinity)

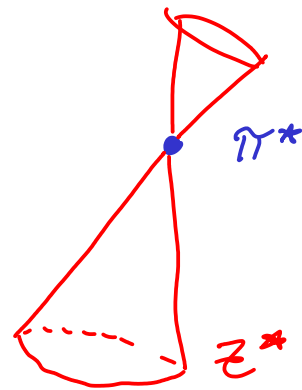
show C is a circle if and only if it contains the 2 points on \mathcal{Z}

dualizing the conic at infinity



$C: x_1^2 + x_2^2 + x_3^2 = 0, x_4 = 0$

dualize \longleftrightarrow



$C^*: x_1^2 + x_2^2 + x_3^2 = 0$

Gram matrix: $Z = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 0 \end{pmatrix}$

Circular sections of ellipsoids

$$Q: \frac{x^2}{a} + \frac{y^2}{b} + \frac{z^2}{c} = 1, \quad a > b > c > 0 \quad \text{ellipsoid}$$

Circular sections lie in the planes:

$$(1) \quad \Pi_{\pm}(\lambda_{\pm}): \sqrt{\frac{1}{b} - \frac{1}{a}} x \pm \sqrt{\frac{1}{c} - \frac{1}{b}} z = \lambda_{\pm}, \quad \lambda_{\pm} \in \left[-\sqrt{\frac{a-c}{b}}, \sqrt{\frac{a-c}{b}} \right]$$

curvature line parametrization of Q :

$$(2) \quad \begin{cases} x(s_1, s_2) = \sqrt{\frac{a}{(a-b)(a-c)}} f_1(s_1) f_2(s_2) \\ y(s_1, s_2) = \sqrt{\frac{b}{(a-b)(b-c)}} g_1(s_1) g_2(s_2) \\ z(s_1, s_2) = \sqrt{\frac{c}{(a-c)(b-c)}} h_1(s_1) h_2(s_2) \end{cases}$$

plus some quadratic equations for $f_1, f_2, g_1, g_2, h_1, h_2$

substitute (2) into (1):

$$\sqrt{\frac{a}{(a-b)(a-c)}} \cdot \frac{a-b}{ab} f_1(s_1) f_2(s_2) \pm \sqrt{\frac{c}{(a-c)(b-c)}} \frac{b-c}{bc} h_1(s_1) h_2(s_2) = \lambda_{\pm}$$

$$\Leftrightarrow f_1(s_1) f_2(s_2) \pm h_1(s_1) h_2(s_2) = \sqrt{b(a-c)} \lambda_{\pm}$$

Thus, f_1, f_2, h_1, h_2 need to satisfy

$$(I) \quad f_1(s_1)^2 + h_1(s_1)^2 = a - c$$

$$(II) \quad f_2(s_2)^2 + h_2(s_2)^2 = a - c$$

$$(III_{\pm}) \quad f_1(s_1) f_2(s_2) \pm h_1(s_1) h_2(s_2) = \sqrt{b(a-c)} \lambda_{\pm}(s_1 \pm s_2)$$

for some functions
 $\lambda_{\pm}(s_{\pm})$

Check that $f_1(s_1) = \sqrt{a-c} \sin s_1$ $f_2(s_2) = \sqrt{a-c} \cos s_2$
 $h_1(s_1) = \sqrt{a-c} \cos s_1$ $h_2(s_2) = \sqrt{a-c} \sin s_2$

satisfy (I), (II), (III $_{\pm}$):

(I) $(a-c) \sin^2 s_1 + (a-c) \cos^2 s_1 = a-c$ ✓

(II) $(a-c) \cos^2 s_2 + (a-c) \sin^2 s_2 = a-c$ ✓

(III $_{\pm}$) $(a-c) \sin s_1 \cos s_2 \pm (a-c) \cos s_1 \sin s_2$
 $= (a-c) \left(\underbrace{\sin s_1 \cos s_2 \pm \cos s_1 \sin s_2}_{\sin(s_1 \pm s_2)} \right)$
 $= \sqrt{b(a-c)} \cdot \underbrace{\sqrt{\frac{a-c}{b}} \sin(s_1 \pm s_2)}_{=\lambda_{\pm}(s_1 \pm s_2)}$ ✓

in the discrete case:

- the planes are given by (1)
- the curvature line parametrization is given (2) with $s_1 \rightarrow u_1$, $s_2 \rightarrow u_2$
with different quadratic eq. for $f_1, f_2, g_1, g_2, h_1, h_2$

In particular, f_1, f_2, h_1, h_2 must satisfy:

(I) $f_1(u_1) f_1(u_1 + \frac{\pi}{2}) + h_1(u_1) h_1(u_1 + \frac{\pi}{2}) = a-c$

(II) $f_2(u_2) f_2(u_2 + \frac{\pi}{2}) + h_2(u_2) h_2(u_2 + \frac{\pi}{2}) = a-c$

(III $_{\pm}$) $f_1(u_1) f_2(u_2) + h_1(u_1) h_2(u_2) = \sqrt{b(a-c)} \lambda_{\pm} \left(\frac{u_1 + u_2}{2} \right)$

Check that $f_1(u_1) = \varepsilon \sqrt{a-c} \sin \delta u_1$, $f_2(u_2) = \varepsilon \sqrt{a-c} \cos \delta u_2$
 $h_1(u_1) = \varepsilon \sqrt{a-c} \cos \delta u_1$, $h_2(u_2) = \varepsilon \sqrt{a-c} \sin \delta u_2$

for $0 < \delta < \pi$ and $\varepsilon = \frac{1}{\sqrt{\cos \frac{\delta}{2}}}$

satisfy (I), (II), (III $_{\pm}$):

$$\begin{aligned}
 \text{(I)} \quad & \varepsilon^2(a-c) \sin \delta u_1 \sin\left(\delta u_1 + \frac{\delta}{2}\right) + \varepsilon^2(a-c) \cos \delta u_1 \cos\left(\delta u_1 + \frac{\delta}{2}\right) \\
 & = \varepsilon^2(a-c) \left(\underbrace{\sin \delta u_1 \sin\left(\delta u_1 + \frac{\delta}{2}\right) + \cos \delta u_1 \cos\left(\delta u_1 + \frac{\delta}{2}\right)}_{= \cos\left(\delta u_1 - \left(\delta u_1 + \frac{\delta}{2}\right)\right)} \right) \\
 & = \varepsilon^2(a-c) \cos \frac{\delta}{2} = a-c \quad \checkmark
 \end{aligned}$$

(II) similar to (I) \checkmark

$$\begin{aligned}
 \text{(III)} \quad & \varepsilon^2(a-c) \sin \delta u_1 \cos \delta u_2 \pm \varepsilon^2(a-c) \cos \delta u_1 \sin \delta u_2 \\
 & = \varepsilon^2(a-c) \sin(\delta(u_1 \pm u_2)) \\
 & = \underbrace{\sqrt{b(a-c)} \sqrt{\frac{a-c}{b}} \cdot \varepsilon^2 \sin(\delta(u_1 \pm u_2))}_{= \lambda \pm \left(\frac{u_1 \pm u_2}{2}\right)} \quad \checkmark
 \end{aligned}$$