

minor divisors and invariant factors

$A \in F[\lambda]^{n \times n}$, $D_k =$ monic greatest common divisor of all $k \times k$ minors of A

Lemma: D_k invariant under elementary operations

1) $A = \begin{pmatrix} \vdots \\ p \\ \vdots \end{pmatrix}$, $p \in F[\lambda]^{1 \times n}$

$\xrightarrow[\text{of 1st type}]{\text{elem. op.}}$ $\begin{pmatrix} \vdots \\ \alpha p \\ \vdots \end{pmatrix}$ with $\alpha \in F \setminus \{0\}$

m some minor of A

case 1: the row p is not contained in the minor m

$$m = \det \begin{pmatrix} \vdots \\ p \\ \vdots \end{pmatrix} \xrightarrow{\text{det. op.}} m$$

case 2: the row p is contained in the minor

$$m = \det \begin{pmatrix} \vdots \\ p \\ \vdots \end{pmatrix} \longrightarrow \det \begin{pmatrix} \vdots \\ \alpha p \\ \vdots \end{pmatrix} = \alpha m$$

2) $A = \begin{pmatrix} \vdots \\ p \\ q \\ \vdots \end{pmatrix}$, $p, q \in F[\lambda]^{1 \times n}$

$\xrightarrow[\text{of 2nd type}]{\text{det. op.}}$ $\begin{pmatrix} \vdots \\ p \\ q + \alpha p \\ \vdots \end{pmatrix}$ with some $\alpha \in F[\lambda]$

case 1: the row q is not contained in the minor

$$m = \det \begin{pmatrix} p \\ q \end{pmatrix} \longrightarrow \det \begin{pmatrix} p \\ q + \alpha p \end{pmatrix} = m$$

case 2: the row p and q are contained in the minor

$$m = \det \begin{pmatrix} | & P & | \\ \hline & q & \\ \hline \end{pmatrix} \rightarrow \det \begin{pmatrix} | & P & | \\ \hline & q+ap & \\ \hline \end{pmatrix} = \det \begin{pmatrix} | & P & | \\ \hline & q & \\ \hline \end{pmatrix} + a \underbrace{\det \begin{pmatrix} | & P & | \\ \hline & & P \\ \hline \end{pmatrix}}_{=0}$$

case 3: the row q is contained, but not the row p

$$m = \det \begin{pmatrix} | & P & | \\ \hline & & \\ \hline & q & \\ \hline \end{pmatrix} \rightarrow \det \begin{pmatrix} | & P & | \\ \hline & & \\ \hline & q+ap & \\ \hline \end{pmatrix} = \underbrace{\det \begin{pmatrix} | & P & | \\ \hline & & q \\ \hline \end{pmatrix}}_{=m} + a \det \begin{pmatrix} | & P & | \\ \hline & & p \\ \hline & & \\ \hline \end{pmatrix}$$

// up to sign
 $\det \begin{pmatrix} | & P & | \\ \hline & & q \\ \hline & & \\ \hline \end{pmatrix}$
 = k x k minor of H
 =: \tilde{m}

$$= m + a \tilde{m}$$

Example

$$H = \begin{pmatrix} 0 & 0 & \lambda^2 - 1 \\ \lambda^2 + 1 & \lambda^2 - \lambda & 0 \\ \lambda^2 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & (\lambda-1)(\lambda+1) \\ \lambda(\lambda+1) & \lambda(\lambda-1) & 0 \\ \lambda^2 & 0 & 0 \end{pmatrix}_{D_0}$$

1x1 minors: $(\lambda-1)(\lambda+1), \lambda(\lambda+1), \lambda(\lambda-1), \lambda^2 \rightsquigarrow D_1 = 1$

2x2 minors: $-\lambda^3(\lambda-1), -\lambda^2(\lambda-1)(\lambda+1), -\lambda(\lambda-1)^2(\lambda+1) \rightsquigarrow D_2 = \lambda(\lambda-1) = \lambda^1(\lambda-1)^1(\lambda+1)^0$

3x3 minor: $-\lambda^3(\lambda-1)^2(\lambda+1) \rightsquigarrow D_3 = \lambda^3(\lambda-1)^2(\lambda+1) = \lambda^3(\lambda-1)^2(\lambda+1)^1$

invariant factors: $I_1 = \frac{D_1}{D_0} = 1 = \lambda^0(\lambda-1)^0(\lambda+1)^0$

$I_2 = \frac{D_2}{D_1} = \lambda(\lambda-1) = \lambda^1(\lambda-1)^1(\lambda+1)^0$

$I_3 = \frac{D_3}{D_2} = \lambda^2(\lambda-1)(\lambda+1) = \lambda^2(\lambda-1)^1(\lambda+1)^1$

Smith normal form: $\begin{pmatrix} 1 & & \\ & \lambda(\lambda-1) & \\ & & \lambda^2(\lambda-1)(\lambda+1) \end{pmatrix}$

Same as last time when computed by the algorithm

list of elementary divisors: $\lambda^2, \lambda, \lambda-1, \lambda-1, \lambda+1$ reconstruct invariant factors

Segre symbol: $[(0:2, 1), (1:1, 1), (-1:1)]$ factors

or abbreviated: $[(2, 1), (1, 1), 1]$
2 entries 2 entries 1 entry

$$I_3 = \lambda^2(\lambda-1)(\lambda+1)$$

all elementary divisors with largest exponent (and erase them from the list)

$$I_2 = \lambda(\lambda-1)$$

all elementary divisors with largest exponent that are still left

$$I_1 = 1$$

degenerate matrices in the family $A(\lambda)$

$$A(0) = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \text{rk } A(0) = 1 = 3 - 2$$

$$A(1) = \begin{pmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \text{rk } A(1) = 1 = 3 - 2$$

$$A(-1) = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \text{rk } A(-1) = 2 = 3 - 1$$