

Discrete Conformal Maps

Linear and Non-Linear

Christian MERCAT

Montpellier II

Oberwolfach Discrete Differential Geometry '06

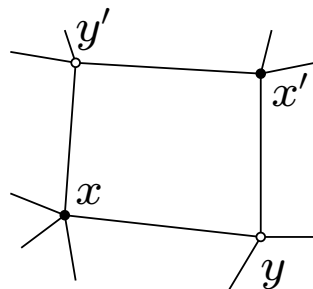
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$$f \text{ is holomorphic} \Rightarrow f(z) = \begin{cases} az + b + o(z), \\ \frac{az + b}{cz + d} + o(z^2). \end{cases}$$

Leads to two different notions of discrete conformality on a quad-graph :

- Preserving diagonal ratio (linear),
- or preserving cross-ratio (Moebius invariant).



Diagonals ratio :

$$\frac{y' - y}{x' - x} = i \rho$$

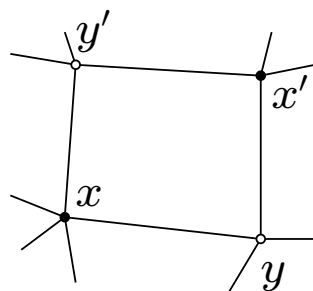
Crossratio :

$$\frac{y' - x'}{x' - y} \frac{y - x}{x - y'} = q$$

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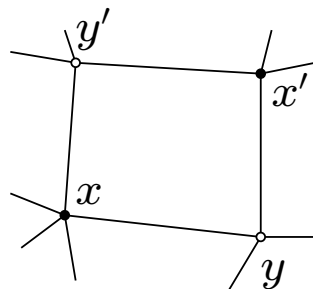
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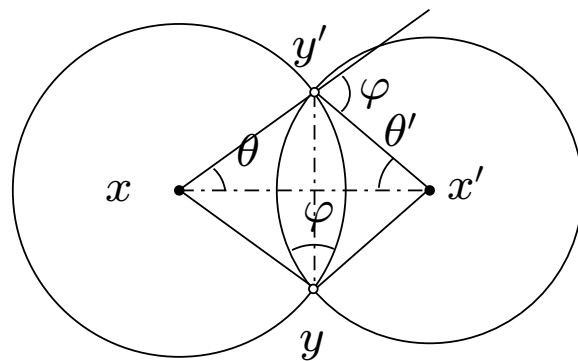
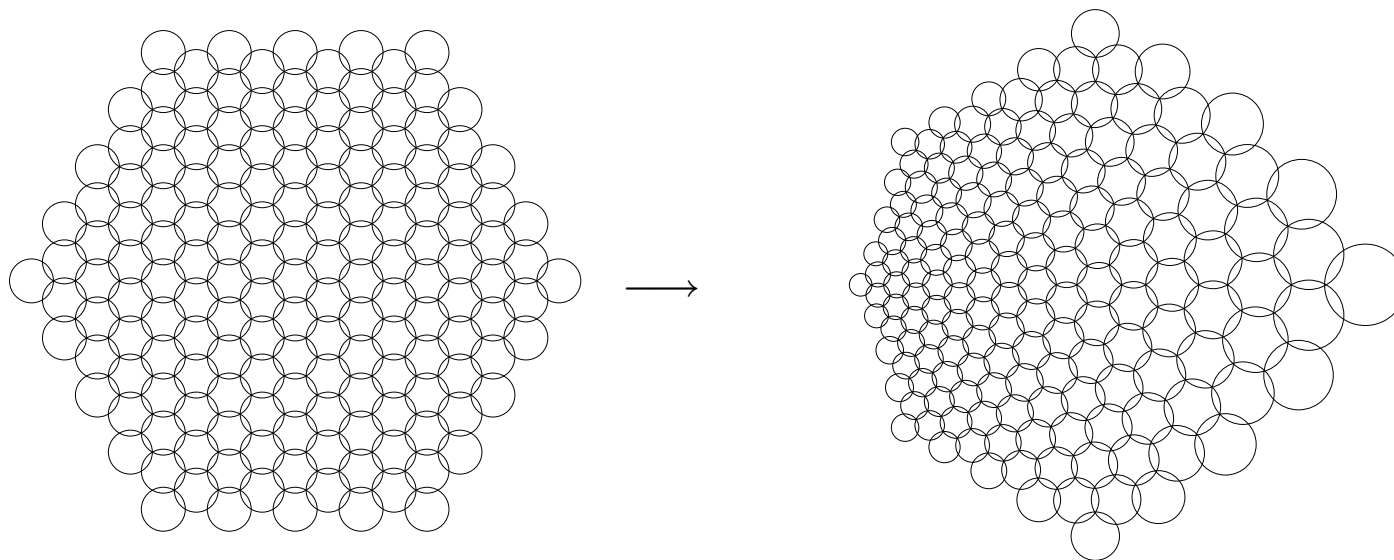
Diagonals ratio :

$$\frac{y' - y}{x' - x} = i \rho$$

Crossratio :

$$\begin{aligned} \frac{y' - x'}{x' - y} \frac{y - x}{x - y'} &= q \\ &= \frac{f(y') - f(x')}{f(x') - f(y)} \frac{f(y) - f(x)}{f(x) - f(y')} \end{aligned}$$

Circles patterns are a particular case :



$$q = e^{-2(\theta+\theta')}$$

$$= e^{-2\varphi}$$

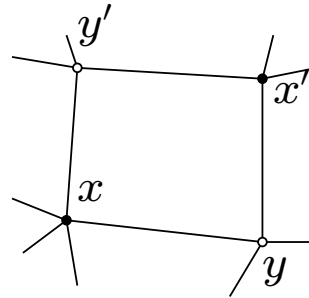
$$\rho = \frac{\cos(\theta-\theta')-\cos(\varphi)}{\sin(\varphi)}$$

Hirota system

For every **cross-ratio preserving** function F , there exists a function f with

$$F(y) - F(x) = f(x) f(y) (y - x) = "F'(z) dz".$$

This imposes on a face (x, y, x', y') ,



$$f(x) f(y) (y - x) + f(y) f(x') (x' - y) + f(x') f(y') (y' - x') + f(y') f(x) (x - y') = 0$$

to be understood as a Morera equation $\oint F'(z) dz = 0$.

Circles pattern case : f is real at the centers and unitary at the intersections :

$$F(y) - F(x) = r(x) e^{i\theta(y)} (y - x).$$

Both definitions can be understood as a Morera equation $\oint F'(z) dz = 0$. with discrete integration of functions whether

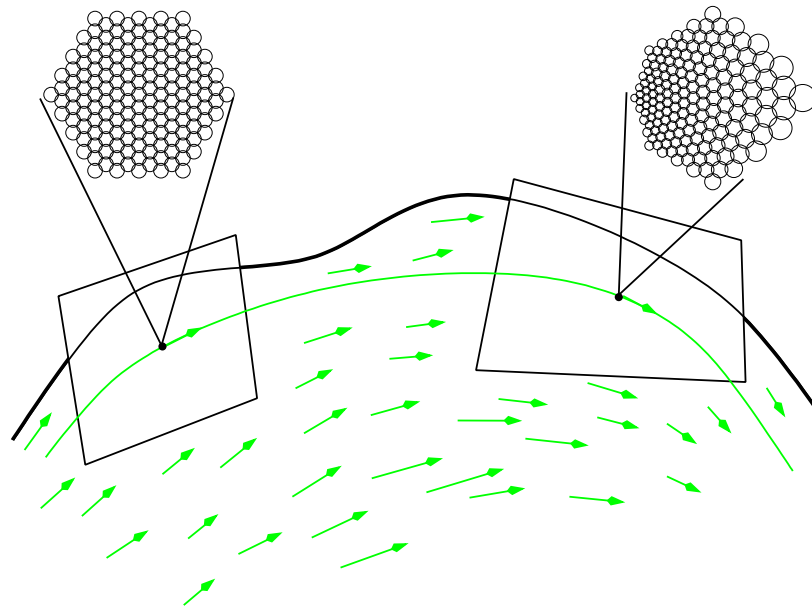
- by the *geometric* mean for the **diagonals ratio preserving** maps

$$\int_{(x,y)} g dZ := \sqrt{g(x)g(y)} (y - x).$$

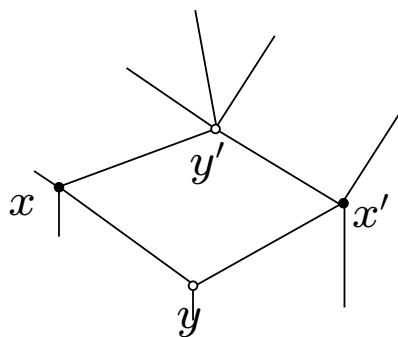
- or by the *arithmetic* mean for the **diagonals ratio preserving** maps

$$\int_{(x,y)} g dZ := \frac{g(x) + g(y)}{2} (y - x).$$

The linear case is a linearization of the quadratic one :

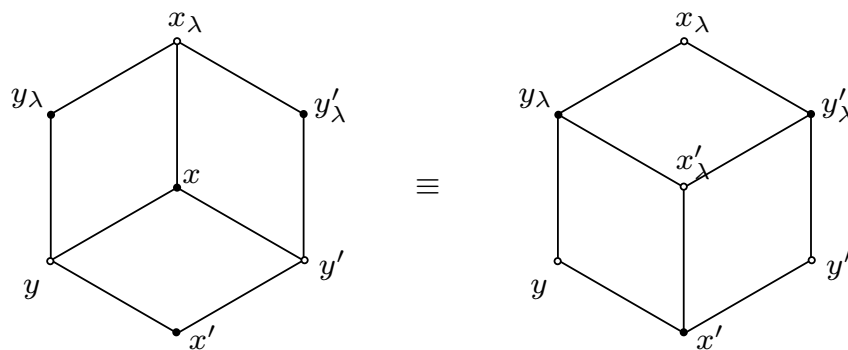


Bäcklund transformation

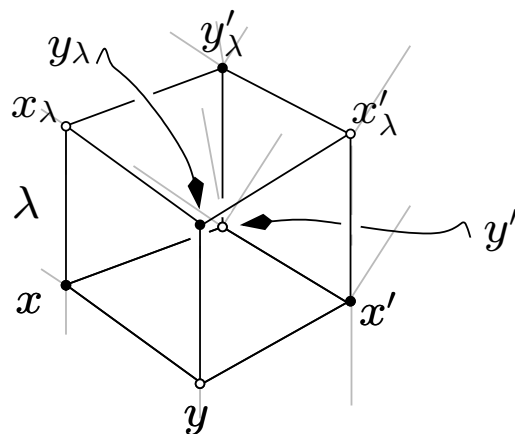


We impose “vertically” the same equation as “horizontally”.

The 3D consistency or **Yang-Baxter** equation yields integrability for rhombic quad-graphs :

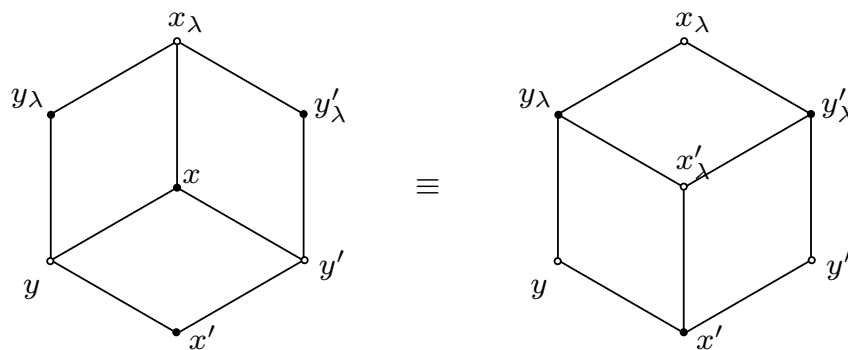


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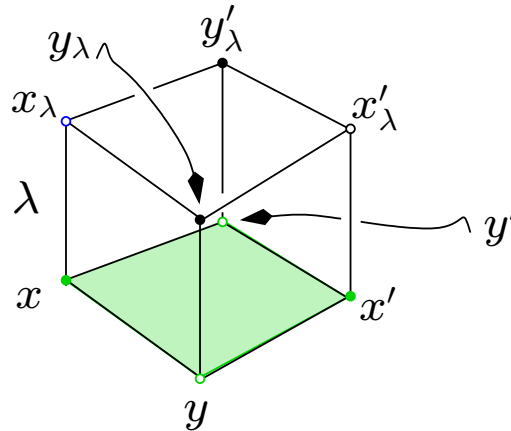
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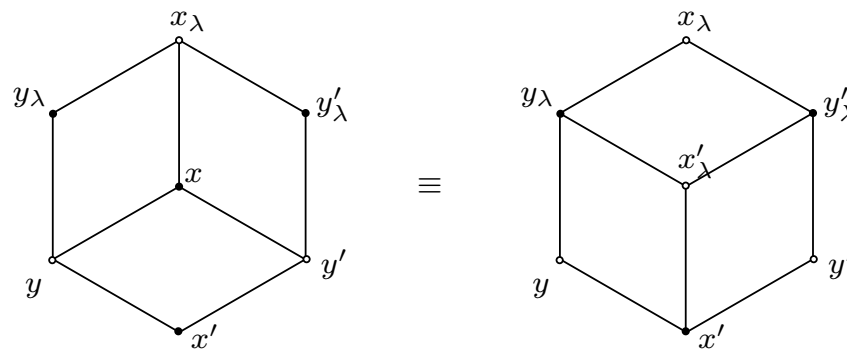
$$i\rho = \frac{y-y'}{x-x'}$$

$$q = \frac{(y-x)^2}{(y'-x')^2}$$



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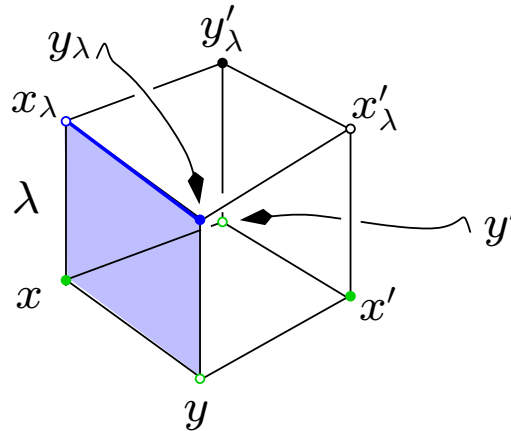
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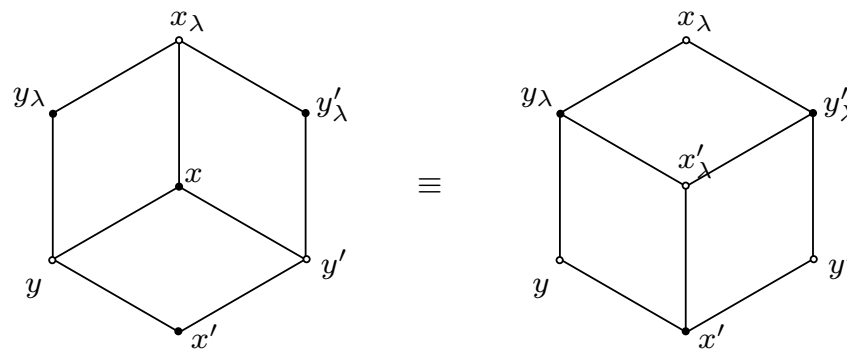
$$i\rho = \frac{y-x+\lambda}{x-y+\lambda}$$

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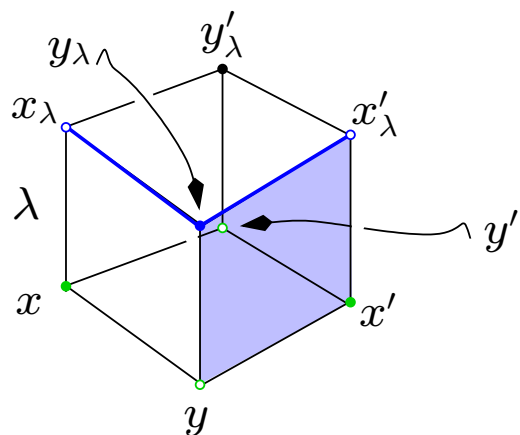


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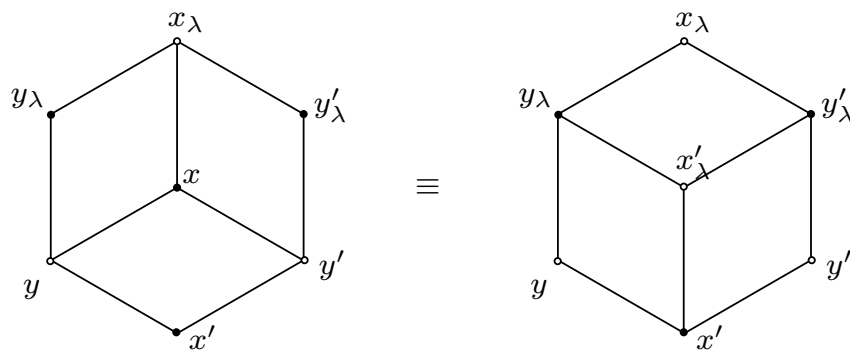


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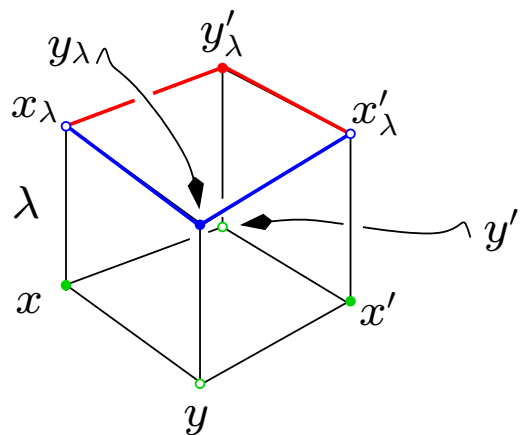


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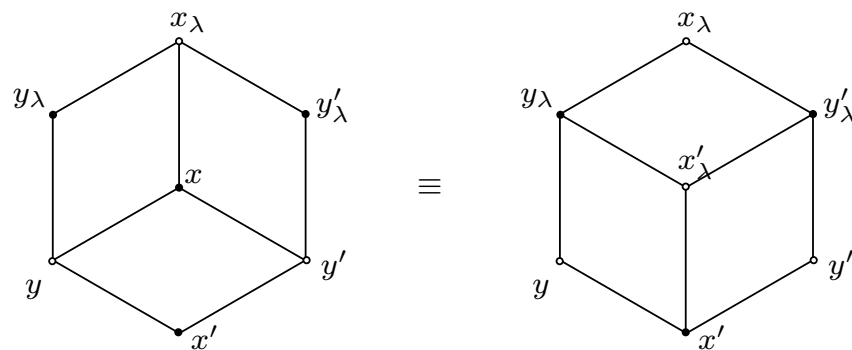


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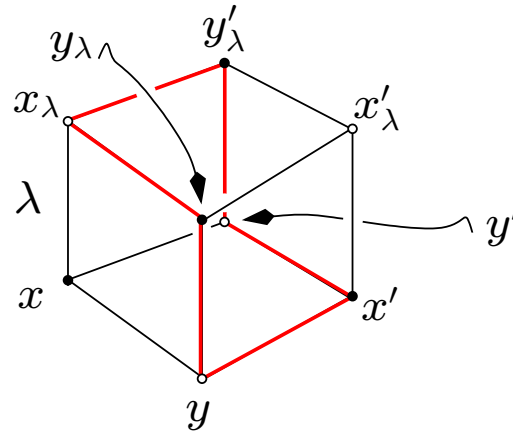


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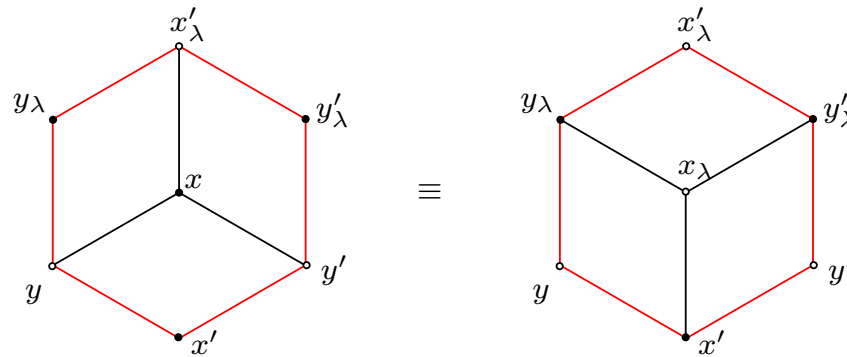


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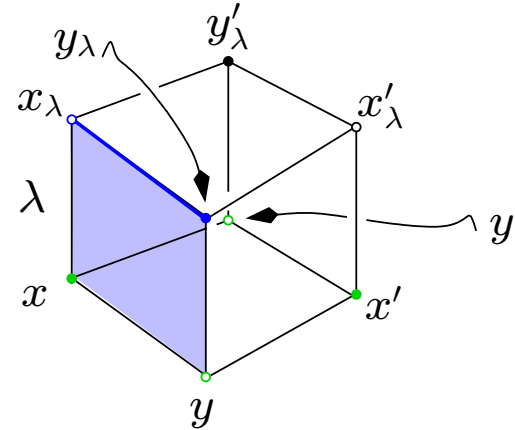


Solitons

The vertical equation is

$$i \rho = \frac{y-x+\lambda}{x-y+\lambda}$$

$$\frac{(f_\lambda(y) - f_\lambda(x))(f(y) - f(x))}{(f_\lambda(y) - f(y))(f_\lambda(x) - f(x))} = q = \frac{(y-x)^2}{\lambda^2}$$



With the change of variables $g = \ln f$, the continuous limit ($y = x + \epsilon$) is :

$$\sqrt{g'_\lambda \times g'} = \frac{2}{\lambda} \sinh \frac{g_\lambda - g}{2}.$$

Isomonodromic solutions, moving frame

The Bäcklund transformation allows to define a notion of discrete holomorphy in \mathbb{Z}^d , for $d > 1$ finite, equipped with rapidities $(\alpha_i)_{1 \leq i \leq d}$.

$$\rho = \frac{\alpha_i + \alpha_j}{\alpha_i - \alpha_j}$$

$$q = \frac{\alpha_i^2}{\alpha_j^2}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} z = \frac{az+b}{cz+d}$$

$$f(x + e_i + e_j) = L_i(x + e_j)f(x + e_j), \quad L_i(x + e_j) \in \mathbb{P}GL_2(\mathbb{C})$$

$$L_i(x; \lambda) = \begin{pmatrix} \lambda + \alpha_i & -2\alpha_i(f(x + e_i) + f(x)) \\ 0 & \lambda - \alpha_i \end{pmatrix}$$

The *moving frame* $\Psi(\cdot, \lambda) : \mathbb{Z}^d \rightarrow GL_2(\mathbb{C})[\lambda]$ for a prescribed $\Psi(0; \lambda) :$

$$\Psi(x + e_i; \lambda) = L_i(x; \lambda)\Psi(x; \lambda).$$

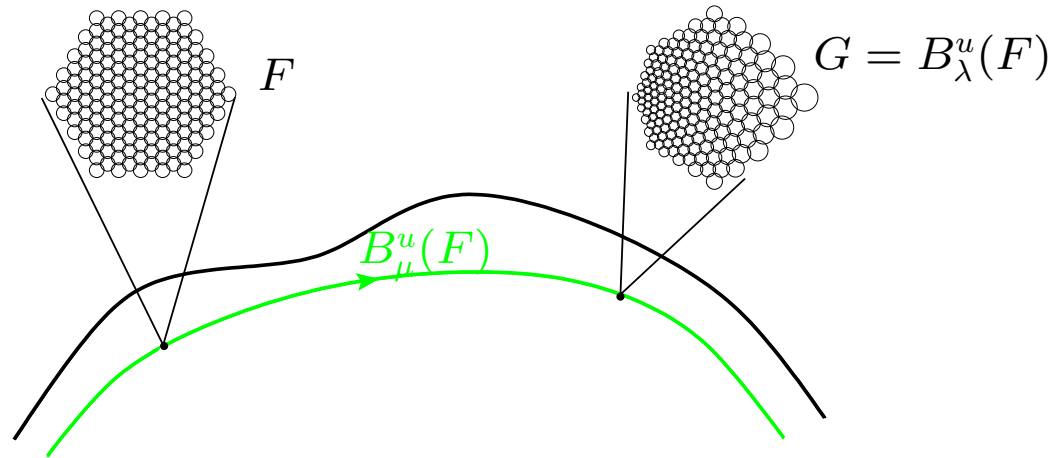
Define $A(\cdot; \lambda) : \mathbb{Z}^d \rightarrow GL_2(\mathbb{C})[\lambda]$ by $A(x; \lambda) = \frac{d\Psi(x; \lambda)}{d\lambda} \Psi^{-1}(x; \lambda).$

They satisfy the recurrent relation

$$A(x + e_k; \lambda) = \frac{dL_k(x; \lambda)}{d\lambda} L_k^{-1}(x; \lambda) + L_k(x; \lambda)A(x; \lambda)L_k^{-1}(x; \lambda).$$

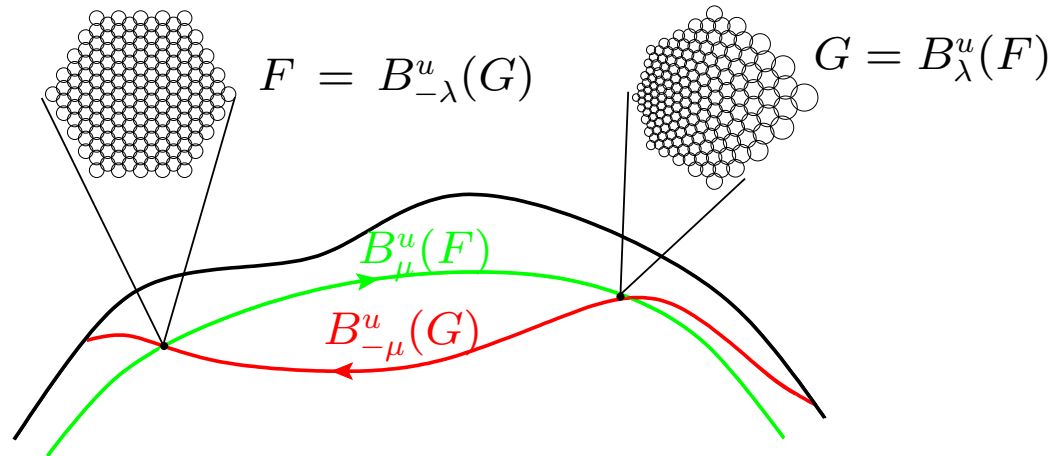
A discrete holomorphic function $f : \mathbb{Z}^d \rightarrow \mathbb{C}$ is called **isomonodromic**, if, for some choice of $A(0; \lambda)$, the matrices $A(x; \lambda)$ are meromorphic in λ , with poles whose positions and orders do not depend on $x \in \mathbb{Z}^d$. Isomonodromic solutions can be constructed with prescribed boundary conditions. Example : the **Green function**.

The exponential



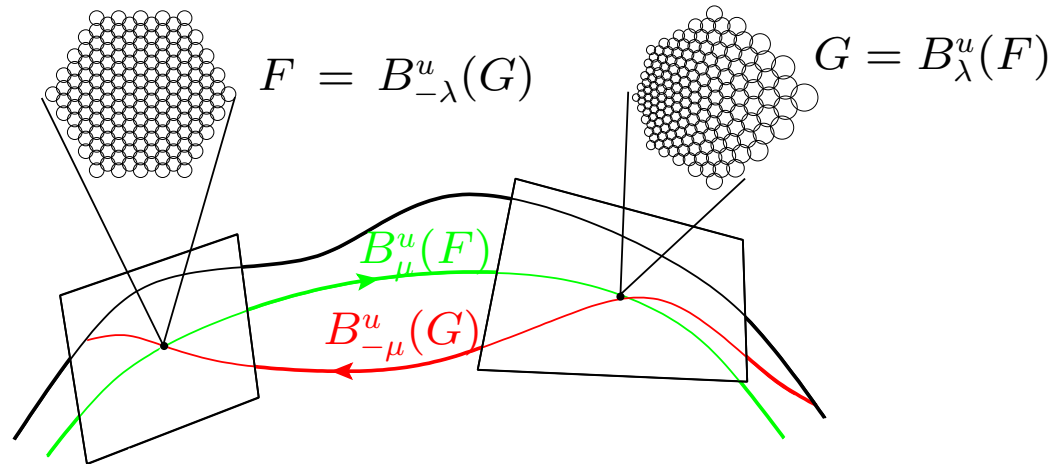
Two-parameter analytic family of CR-preserving maps, the initial condition u at a given origin, and the parameter λ of the Bäcklund transformation. It induces a linear map between the tangent spaces. It is not injective, its kernel is named the **discrete exponential** $\exp(\cdot:\lambda:F)$. Varying the parameter, they form a **basis** of the tangent space, the space of linear discrete holomorphic functions.

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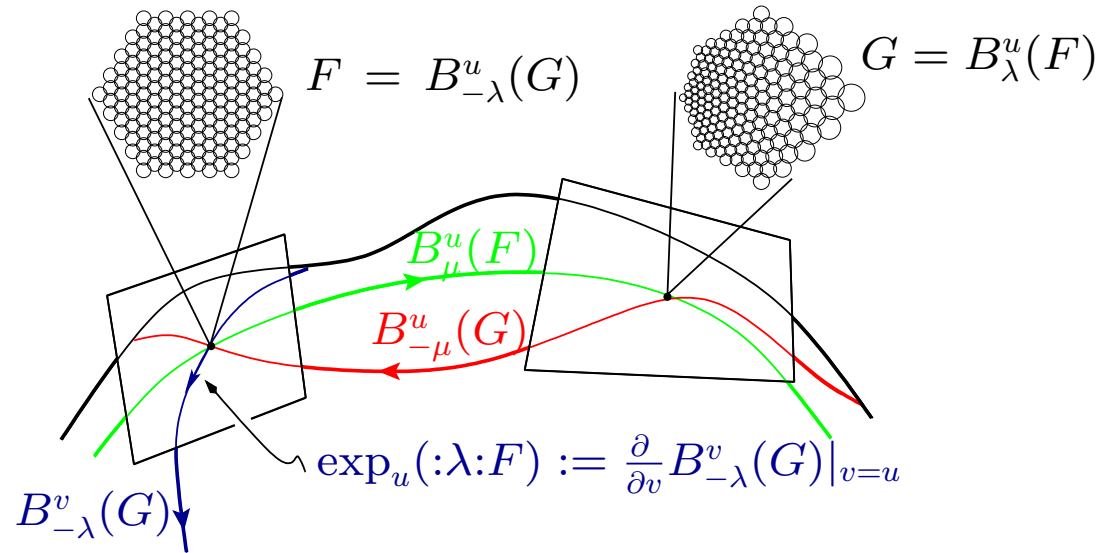
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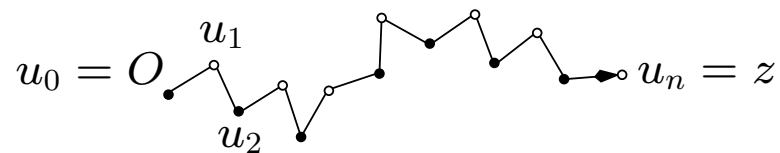
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Example : The lozenges.



$$\exp(:\lambda: z) = \prod_k \frac{1 + \frac{\lambda}{2}(u_k - u_{k-1})}{1 - \frac{\lambda}{2}(u_k - u_{k-1})}.$$

It is a generalization of the formula

$$\exp(\lambda z) = \left(1 + \frac{\lambda z}{n}\right)^n + O\left(\frac{z^2}{n}\right) = \left(\frac{1 + \frac{\lambda z}{2n}}{1 - \frac{\lambda z}{2n}}\right)^n + O\left(\frac{z^3}{n^2}\right).$$

The Green function on any rhombic map is

Theorem 1 (Richard Kenyon)

$$G(O, x) = -\frac{1}{8\pi^2 i} \oint_C \exp(:\lambda: x) \frac{\log \frac{\delta}{2} \lambda}{\lambda} d\lambda$$

$$\Delta G(O, x) = \delta_{O,x}, \quad G(O, x) \sim_{x \rightarrow \infty} \begin{cases} \log |x| & \text{for black vertices,} \\ i \arg(x) & \text{for white vertices.} \end{cases}$$

The derivative of the exponential with respect to the parameter λ yield

$$\frac{\partial^k}{\partial \lambda^k} \exp(:\lambda: z) =: Z^{:k:} \exp(:\lambda: z)$$

and $\lambda = 0$ defines the discrete polynomials $Z^{:k:}$ which in turn give $\exp(:\lambda: z) = \sum \frac{Z^{:k:}}{k!}$, absolutely convergent for $\lambda \cdot \delta < 1$.

In this case, the primitive of a holomorphic function is itself holomorphic :

$$\int_{(x,y)} f dZ := \frac{f(x) + f(y)}{2} (y - x).$$

We can solve some “differential equations”, for example the polynomials fulfill

$$Z^{:k+1:} = (k + 1) \int Z^{:k:} dZ,$$

and the exponential

$$\exp(:\lambda: z) = \frac{1}{\lambda} \int \exp(:\lambda: z) dZ.$$

There is a duality : with $\varepsilon = \pm 1$ on black and whites, $f^\dagger = \varepsilon \bar{f}$ is again holomorphic.

We define the derivative f' of a holomorphic function f as

$$f'(z) := \frac{4}{\delta^2} \left(\int_O^z f^\dagger dZ \right)^\dagger + \lambda \varepsilon,$$

it verifies $f = \int f' dZ$.

Most of the tools of the continuous theory are recovered in the discrete linear case, harmonicity, Hodge decomposition, poles, Riemann-Roch theorem, period matrix, Cauchy integral formulae, Abel’s map in the Jacobian, Riemann bilinear relations and a continuous limit theorem.

Discrete hamonicity

– Hodge star : $* : C^k \rightarrow C^{2-k}$,

– Discrete Laplacian :

$$d^* := - * d *, \quad \Delta := d d^* + d^* d,$$

– Hodge decomposition :

$$C^k = \text{Im} d \oplus^\perp \text{Im} d^* \oplus^\perp \text{Ker } \Delta,$$

– Weyl's lemma :

$$\Delta f = 0 \iff \iint f * \Delta g = 0, \quad \forall g \text{ compact.}$$

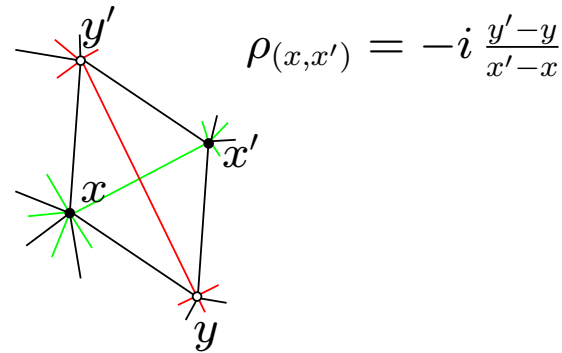
– Green's identity :

$$\iint_D (f * \Delta g - g * \Delta f) = \oint_{\partial D} (f * dg - g * df).$$

$$\int_{(y,y')} * \alpha := \rho_{(x,x')} \int_{(x,x')} \alpha.$$

$$\Delta f(x) = \sum \rho_{(x,x_k)} (f(x) - f(x_k)).$$

$$\text{Ker } \Delta_1 = C^{(1,0)} \oplus^\perp C^{(0,1)}.$$



cf Wardetzky, Polthier, Glickenstein, Novikov, Wilson

Meromorphic forms

$$\alpha \in C^1 \text{ is holomorphic} \iff \begin{cases} * \alpha = -i \alpha & \text{of type (1,0)} \\ d\alpha = 0 & \text{closed.} \end{cases} \quad \text{i.e. } \int_{(y,y')} \alpha = i \rho_{(x,x')} \int_{(x,x')} \alpha$$

- α of type (1,0) has a pole of order 1 at v if its residue $\text{Res}_v \alpha := \frac{1}{2i\pi} \oint_{\partial v^*} \alpha \neq 0$.
- If α is not of type (1,0) on (x, y, x', y') it has there a pole of order > 1 .
- Discrete Riemann-Roch theorem : Existence of forms with prescribed poles and holonomies.
- Green function and potential, Cauchy integral formula : $\oint_{\partial D} f \cdot \nu_{x,y} = 2i\pi \frac{f(x)+f(y)}{2}$.
- Period matrix, Jacobian, Abel's map, Riemann's bilinear relations.
- In the rhombic case : integration of functions, derivation, explicit basis (exponentials and polynomials), continuous limit theorem.

The L^2 norm of the 1-form df is called the **Dirichlet** energy

$$\begin{aligned} E_D(f) &:= \|df\|^2 = (df, df) = \frac{1}{2} \sum_{(x,x') \in \Lambda_1} \rho(x, x') |f(x') - f(x)|^2 \\ &= \frac{E_D(f|_\Gamma) + E_D(f|_{\Gamma^*})}{2}. \end{aligned}$$

The **conformal energy** of a map measures its conformality defect

$$E_C(f) := \frac{1}{2} \|df - i * df\|^2.$$

They are related through

$$\begin{aligned} E_C(f) &= \frac{1}{2} (df - i * df, df - i * df) \\ &= \frac{1}{2} \|df\|^2 + \frac{1}{2} \|-i * df\|^2 + \operatorname{Re}(df, -i * df) \\ &= \|df\|^2 + \operatorname{Im} \iint_{\diamond_2} df \wedge \overline{df} \\ &= E_D(f) - 2\mathcal{A}(f) \end{aligned}$$

where the algebraic area covered by the function is

$$\mathcal{A}(f) := \frac{i}{2} \iint_{\diamond_2} df \wedge \overline{df}$$

For a face $(x, y, x', y') \in \diamond_2$, the algebraic area of the oriented quadrilateral $(f(x), f(x'), f(y), f(y'))$ is

$$\begin{aligned} \iint_{(x,y,x',y')} df \wedge \bar{d}f &= i \operatorname{Im} \left((f(x') - f(x)) \overline{(f(y') - f(y))} \right) \\ &= -2i \mathcal{A}(f(x), f(x'), f(y), f(y')) \end{aligned}$$

In the continuous,

$$\text{for } f(z + z_0) = f(z_0) + z \times (\partial f)(z_0) + \bar{z} \times (\bar{\partial} f)(z_0) + o(|z|),$$

$$(\partial f)(z_0) = \lim_{\gamma \rightarrow z_0} \frac{i}{2\mathcal{A}(\gamma)} \oint_{\gamma} f d\bar{z}, \quad (\bar{\partial} f)(z_0) = - \lim_{\gamma \rightarrow z_0} \frac{i}{2\mathcal{A}(\gamma)} \oint_{\gamma} f dZ,$$

over a small loop γ around z_0 .

It leads to the following definitions in the discrete setup :

$$\begin{aligned} \partial : C^0(\diamond) &\rightarrow C^2(\diamond) \\ f &\mapsto \partial f = [(x, y, x', y') \mapsto -\frac{i}{2\mathcal{A}(x,y,x',y')} \oint_{(x,y,x',y')} f d\bar{Z}] \\ &= \frac{(f(x') - f(x))(\bar{y}' - \bar{y}) - (\bar{x}' - \bar{x})(f(y') - f(y))}{(x' - x)(\bar{y}' - \bar{y}) - (\bar{x}' - \bar{x})(y' - y)}, \end{aligned}$$

$$\begin{aligned} \bar{\partial} : C^0(\diamond) &\rightarrow C^2(\diamond) \\ f &\mapsto \bar{\partial} f = [(x, y, x', y') \mapsto -\frac{i}{2\mathcal{A}(x,y,x',y')} \oint_{(x,y,x',y')} f dZ] \\ &= \frac{(f(x') - f(x))(y' - y) - (x' - x)(f(y') - f(y))}{(x' - x)(\bar{y}' - \bar{y}) - (\bar{x}' - \bar{x})(y' - y)}. \end{aligned}$$

A holomorphic function f verifies $\bar{\partial}f \equiv 0$ and (with $Z(u)$ noted simply u)

$$\partial f(x, y, x', y') = \frac{f(y') - f(y)}{y' - y} = \frac{f(x') - f(x)}{x' - x}.$$

The Jacobian $J = |\partial f|^2 - |\bar{\partial}f|^2$ relates the area :

$$\iint_{(x,y,x',y')} df \wedge \bar{d}f = J \iint_{(x,y,x',y')} dZ \wedge \bar{d}Z.$$

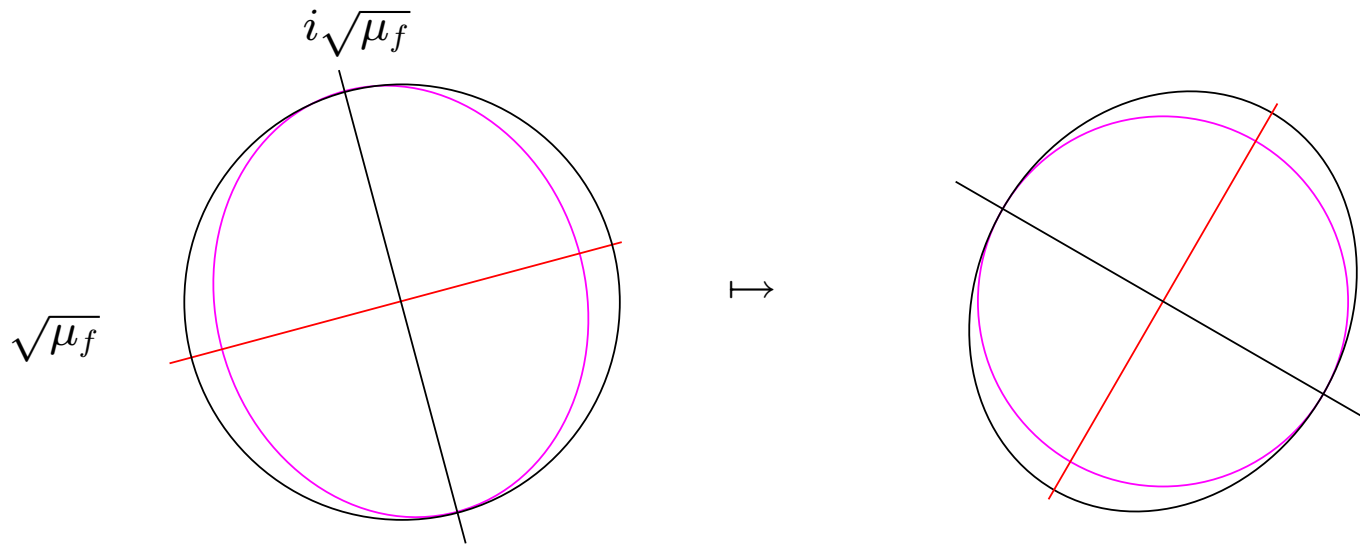
Quasi-conformal maps

For a general function, define the *dilatation* coefficient

$$D_f := \frac{|f_z| + |f_{\bar{z}}|}{|f_z| - |f_{\bar{z}}|}$$

$D_f \geq 1$ for $|f_{\bar{z}}| \leq |f_z|$ (quasi-conformal). Can be written in term of the *complex dilatation* :

$$\mu_f = \frac{f_{\bar{z}}}{f_z}$$



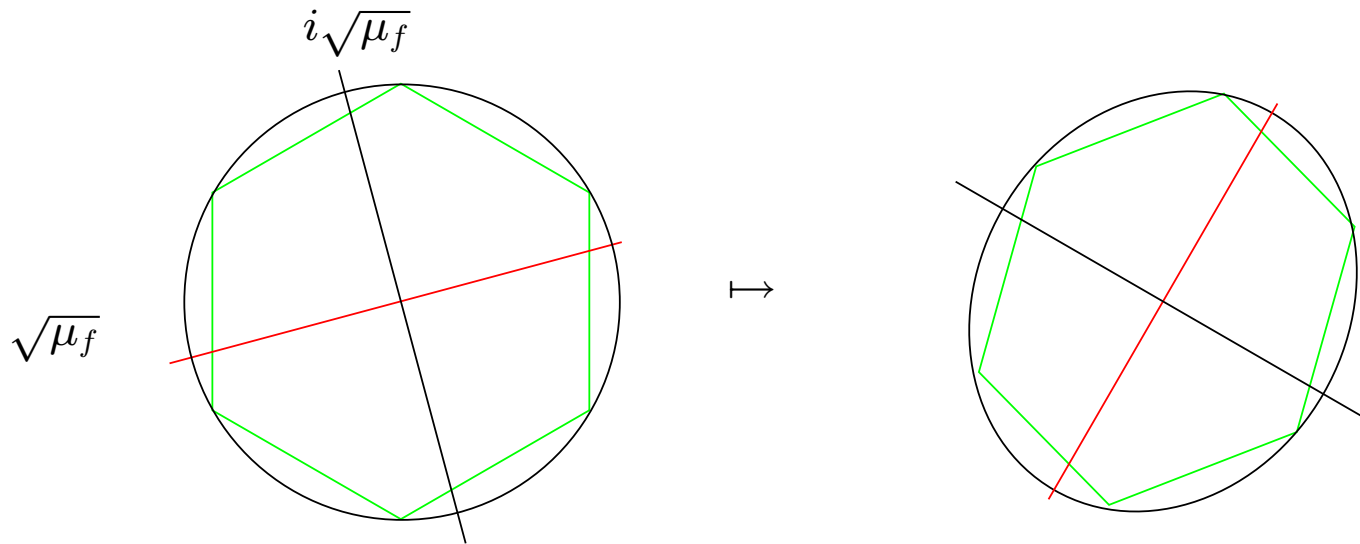
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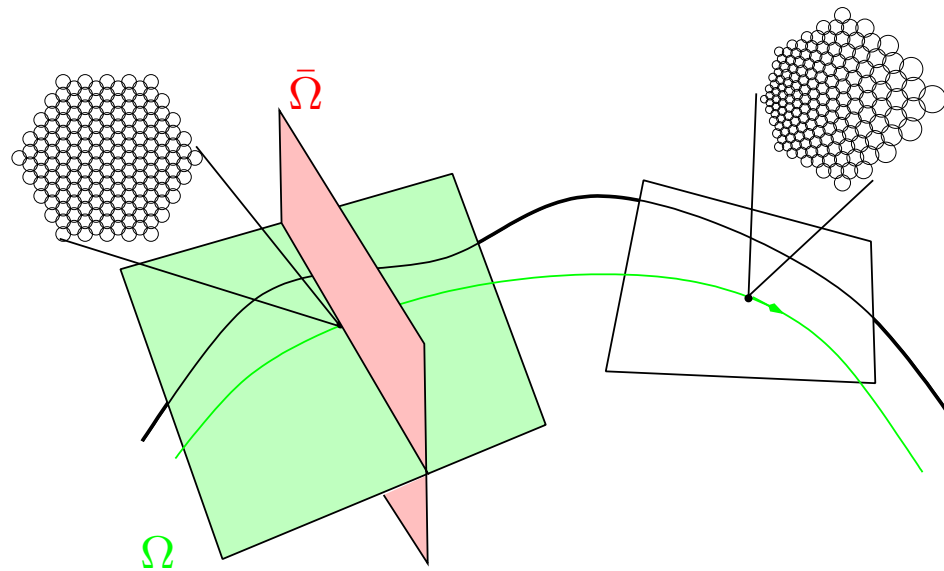
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$$\mu_f = \frac{f_{\bar{z}}}{f_z} = \frac{(f(x') - f(x))(y' - y) - (x' - x)(f(y') - f(y))}{(f(x') - f(x))(\bar{y}' - \bar{y}) - (\bar{x}' - \bar{x})(f(y') - f(y))}$$



Teichmüller space?

For a given combinatorics the fixed cross-ratio subspaces foliate the space of maps. Ω stays on the same discrete Riemann surface, $\bar{\Omega}$ changes the discrete conformal structure.



Apply Ahlfors-Bers



Before



After

Christian Mercat, Arnaud Chéritat, Xavier Buff

Thank you.