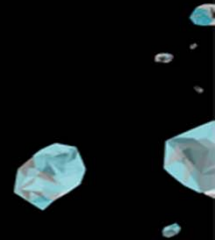
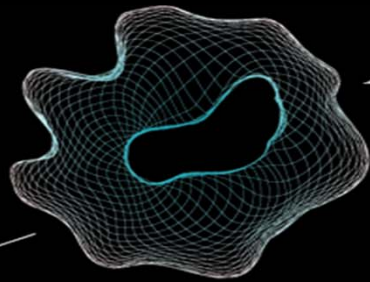
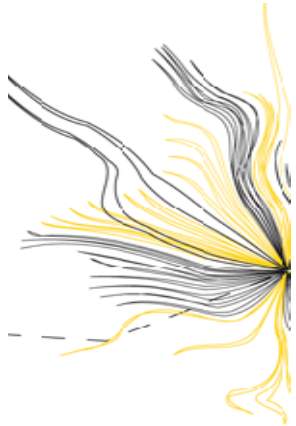


UNIVERSITY OF TWENTE.

## ON THE IMPORTANCE OF A PROPER USE OF ENERGY FUNCTIONS IN TRANSPORT MODELS

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Enschede  
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## SETTING THE STAGE... VIEWPOINT

- **Context of justification ('world of proofs'): *model manipulation* (mathematics, mathematical physics)**  
**versus**
- **Context of discovery/explanation: *modeling* as a decision process, abstraction (engineering physics)**





## SETTING THE STAGE... VIEWPOINT

- Herein focus on *reduction* by
  - making well-based *initial modeling decisions*
  - *structured* approach
  - variable *categorization* based on physical properties
  - *tools/notations* that support modeling decisions
  - *INSIGHT* in physical behavior
- **Mathematical *result* still open for further reduction!**



## SETTING THE STAGE... TERMINOLOGY

- **Ideal concepts ('storage', 'transformation', etc.): mental pictures**
- **Communication: depicting imaginary concepts into visible images – ideal 'elements'**
- **Potential confusion of**
  - **ideal elements with tangible components**
  - **topological structure with spatial (geometrical) structure**

(see Walter Lewin's lecture about Faraday versus Kirchhoff:  
part 1: <http://www.youtube.com/watch?v=eqjl-qRy71w&NR=1>,  
part 2: <http://www.youtube.com/watch?v=1bUWcy8HwpM&feature=related>)



## EXAMPLE: FARADAY'S LAW

$$\oint_C E \cdot dl = -\frac{d}{dt} \iint_S B \cdot dA$$

$$\oint_C E \cdot dl + \frac{d}{dt} \iint_S B \cdot dA = 0$$

- **Physicists:  $dB/dt = 0$  for Kirchhoff's voltage law to hold (*geometrical* interpretation)**
- **Electrical engineers, graph theoreticians:  $d\lambda/dt$  is a voltage (*topological* interpretation of the quasistationary situation)**

$$\frac{d\lambda}{dt} = n \frac{d\Phi}{dt} = n \frac{d}{dt} \iint_S B dA$$

- **i.o.w.: topological structure is NOT EQUAL TO geometrical structure (Lewin's confusion)**



## ‘LUMPED’ VERSUS ‘DISTRIBUTED’

- Ideal elements are *conceptual* ‘lumps’
- Distributed system models treat *configuration* space in a continuous way  
*but*  
still use *conceptually* ‘lumped’ concepts(!):
  - various balance equations (momentum, mass, etc.)
  - dissipation relations
  - etc.
- All conceptually separated...



## PREREQUISITES

- **Basic physical concepts: e.g. quantities for which a conservation principle holds (momentum, charge, etc.)**
- **Physical interaction implies energy exchange = = power ('through' *conceptual* ports)**
  - **even information exchange requires low power: back effect is (made) negligible (e.g. sensor & amplifier)**
- **Eulerian vs. Lagrangian coordinates ('view point')**
- **Legendre transforms**
- **Basics of (ir-)reversible thermodynamics**

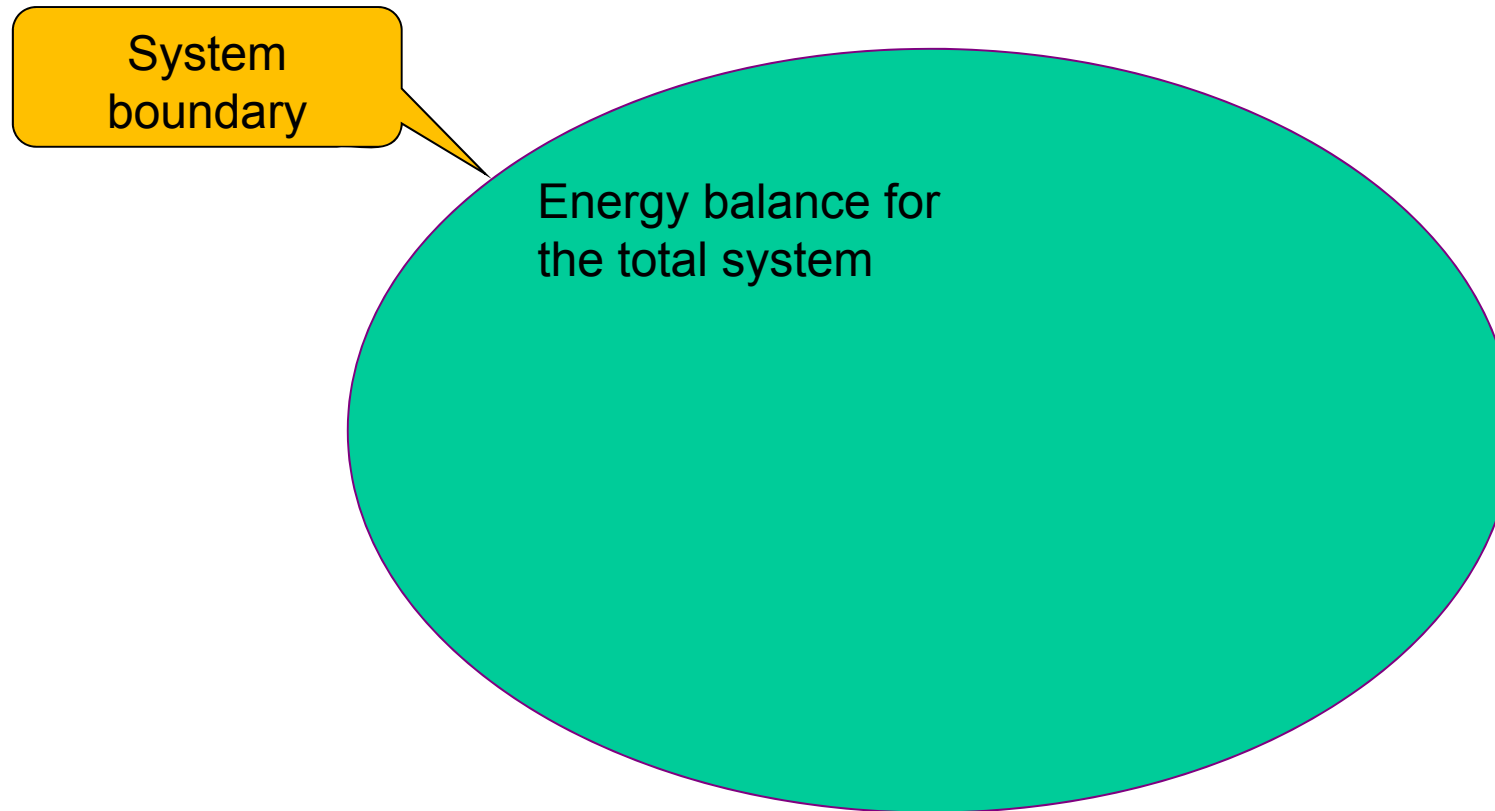


## 'PITCH' OF POINTS TO MAKE

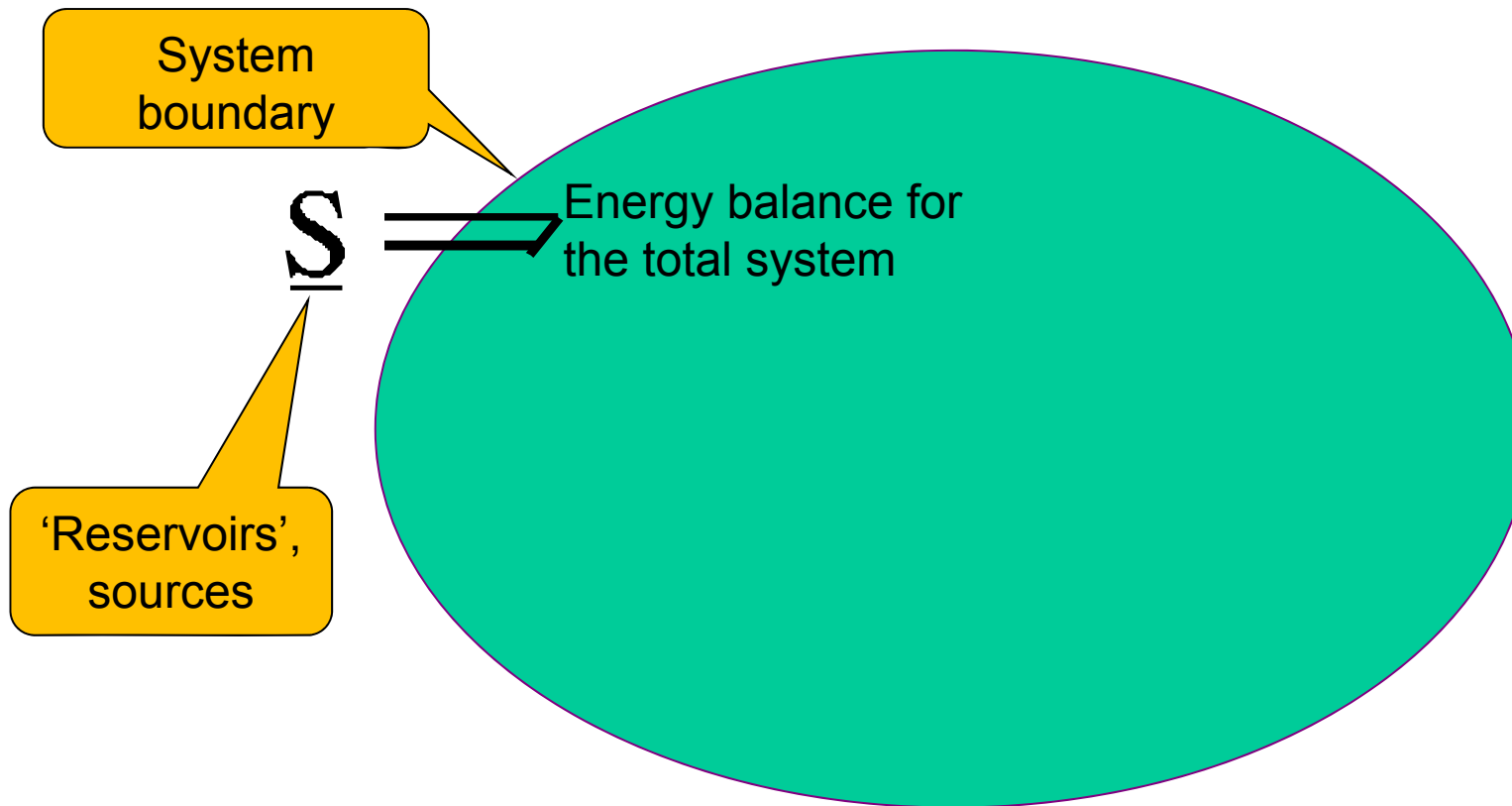
- separation between *configuration* and *energy* states: more insight
- system boundary definitions may be *mixed*: Eulerian vs Lagrangian
- concept of energy *density* (material of spatial) synonymous with first degree homogeneous energy function of all possible extensive states *in principle*
- energy-based modeling approach/notation:
  - automatically satisfies fundamental principles of physics when all grammar rules are obeyed
  - systematic approach to the dynamic behavior of all properties that may be *convected* in principle (e.g. momentum, electric charge, etc.);
- generalized thermodynamic framework of variables more general than Hamiltonian (generalized mechanical) framework:
  - some domains have no dual storage



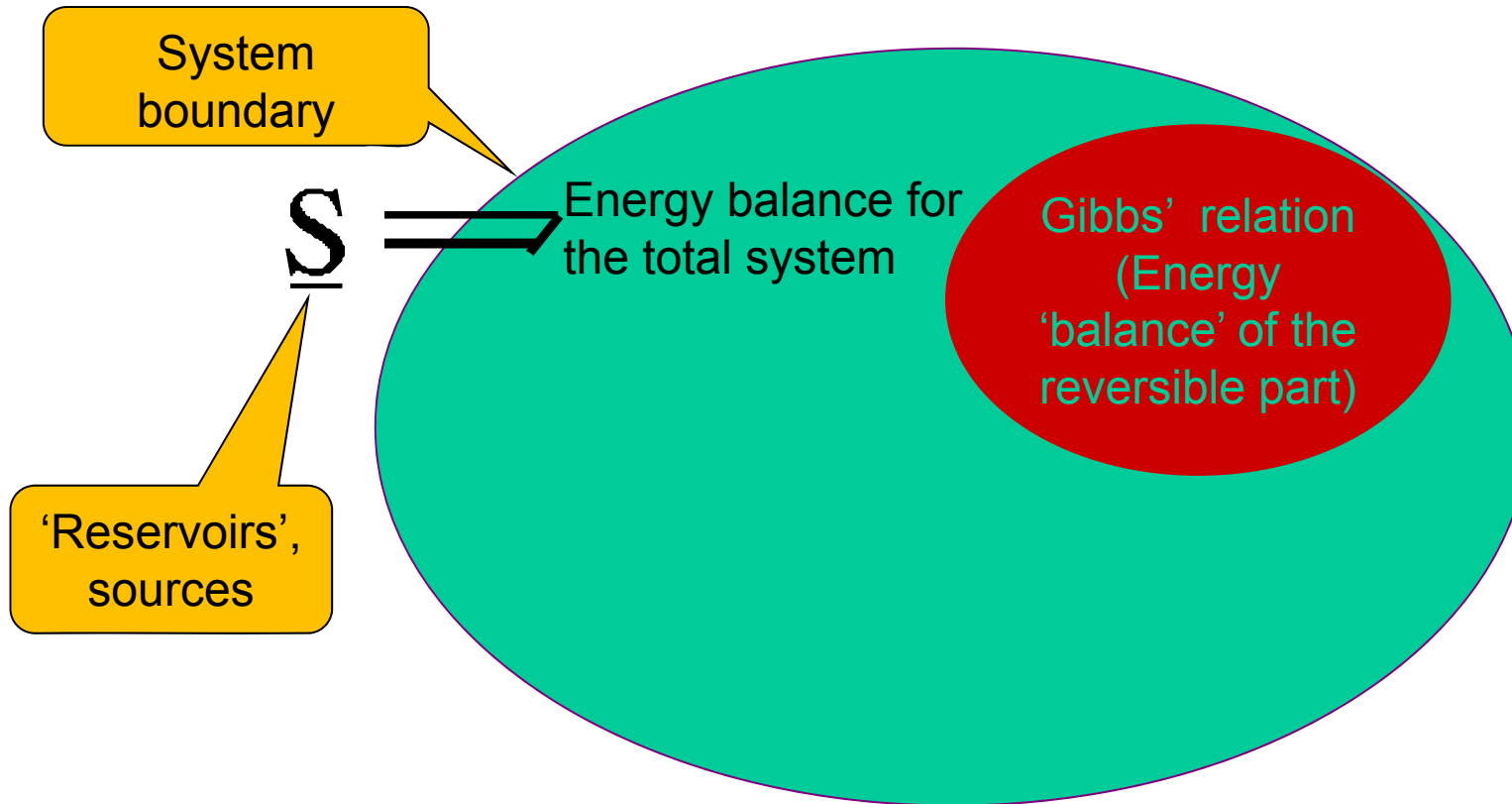
# THERMODYNAMIC APPROACH



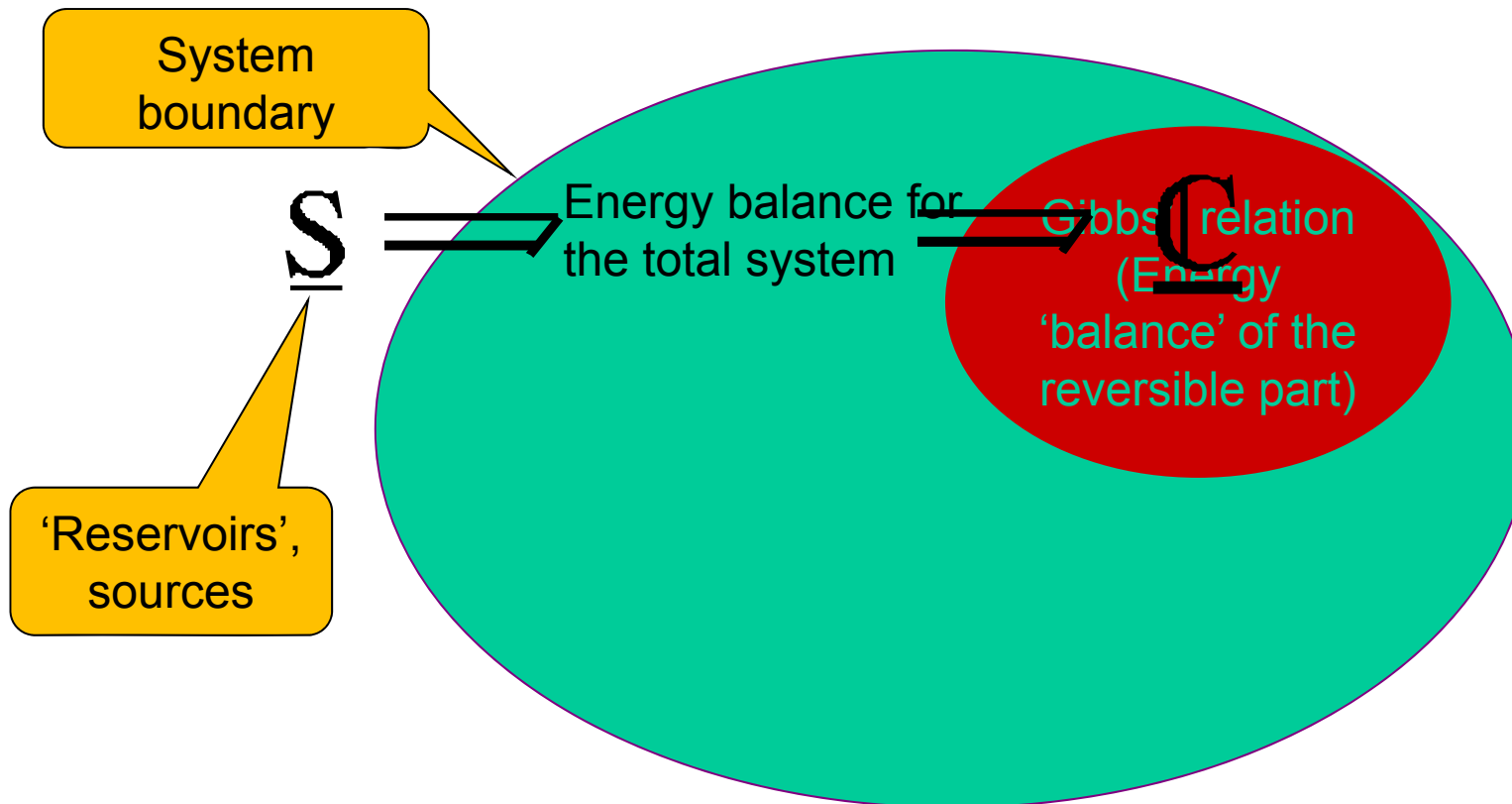
# THERMODYNAMIC APPROACH



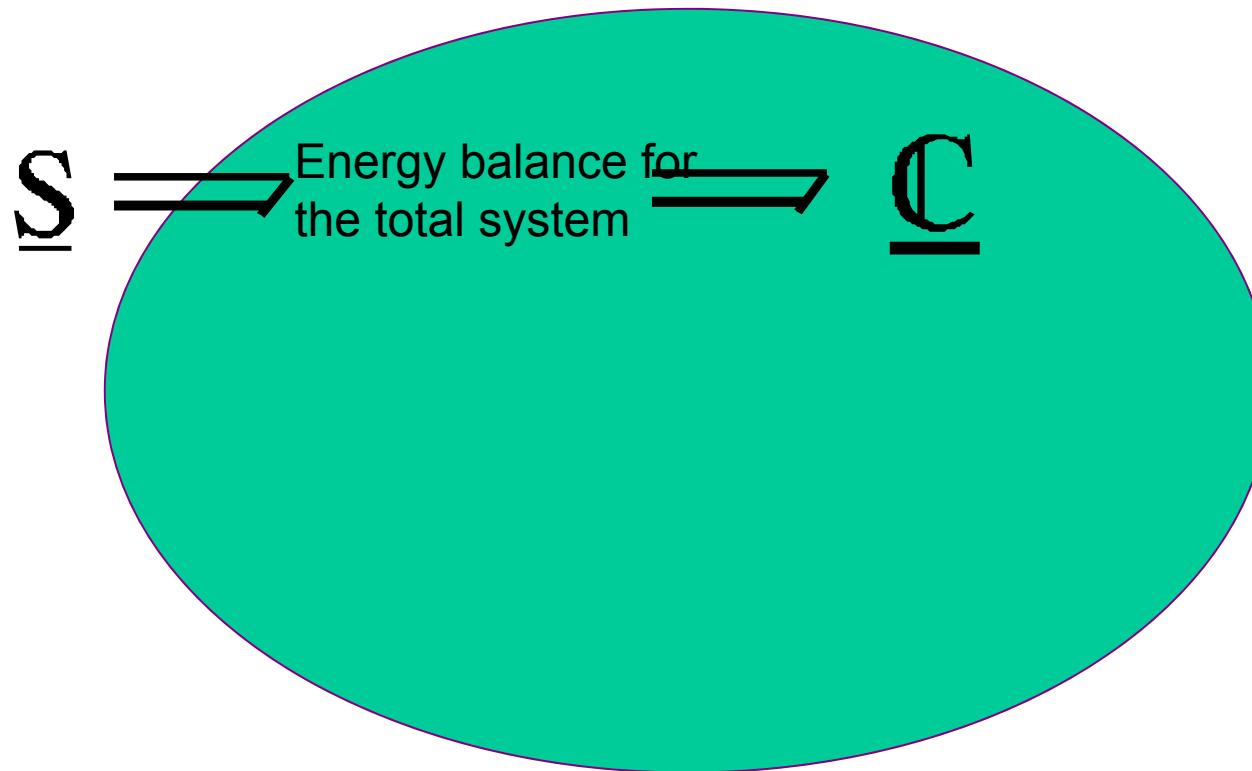
# THERMODYNAMIC APPROACH



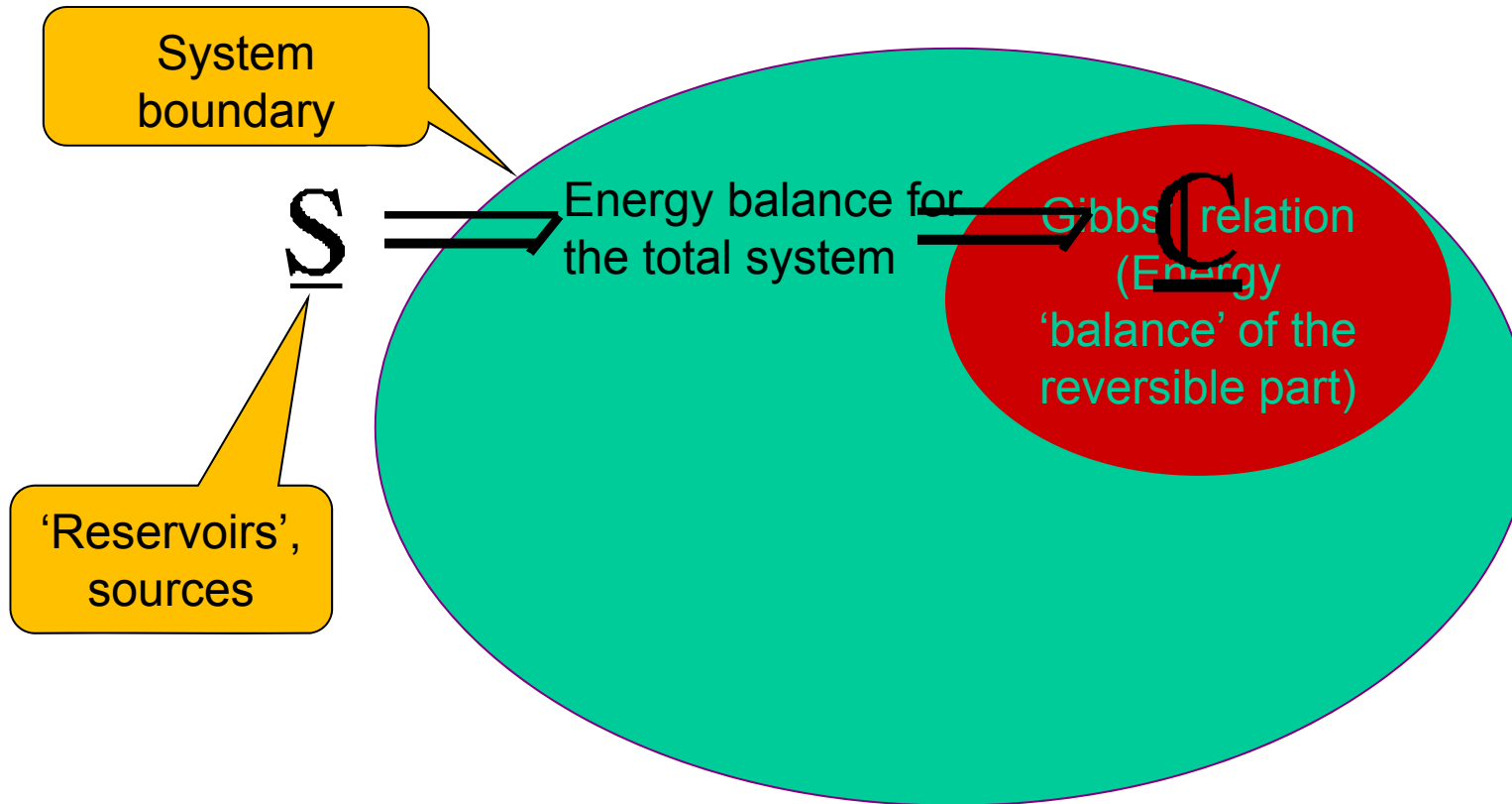
# THERMODYNAMIC APPROACH



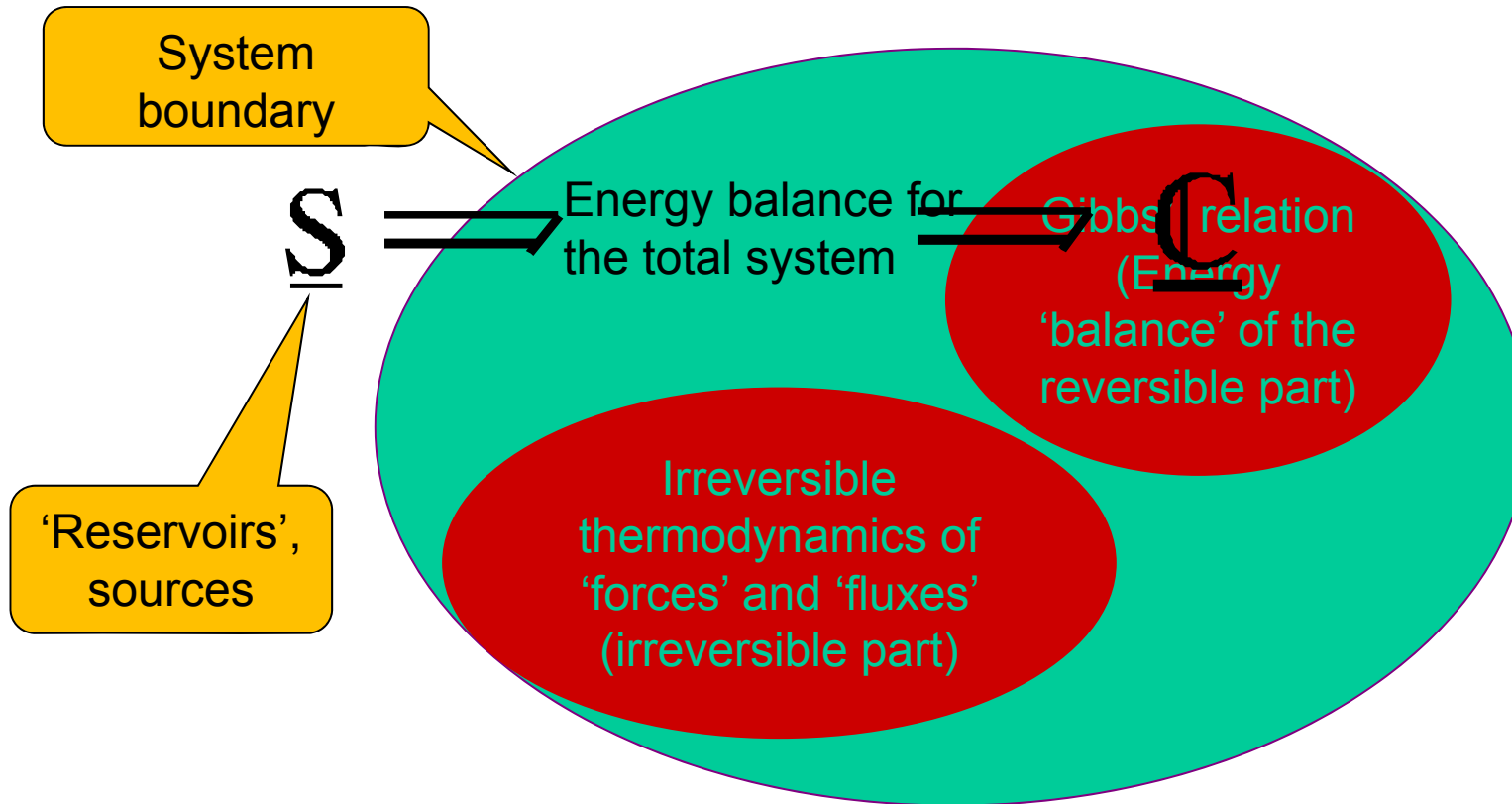
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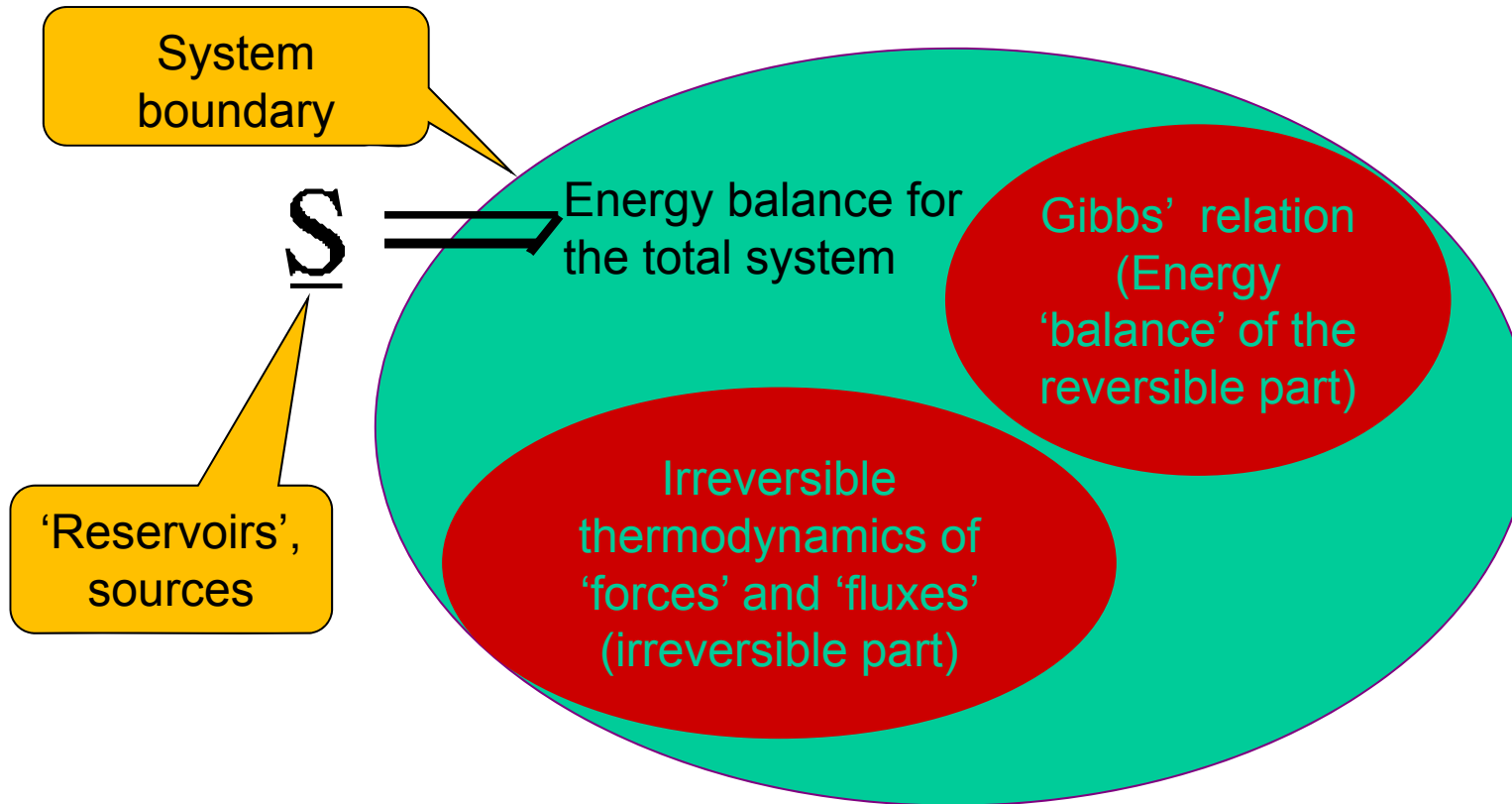
# THERMODYNAMIC APPROACH



# THERMODYNAMIC APPROACH

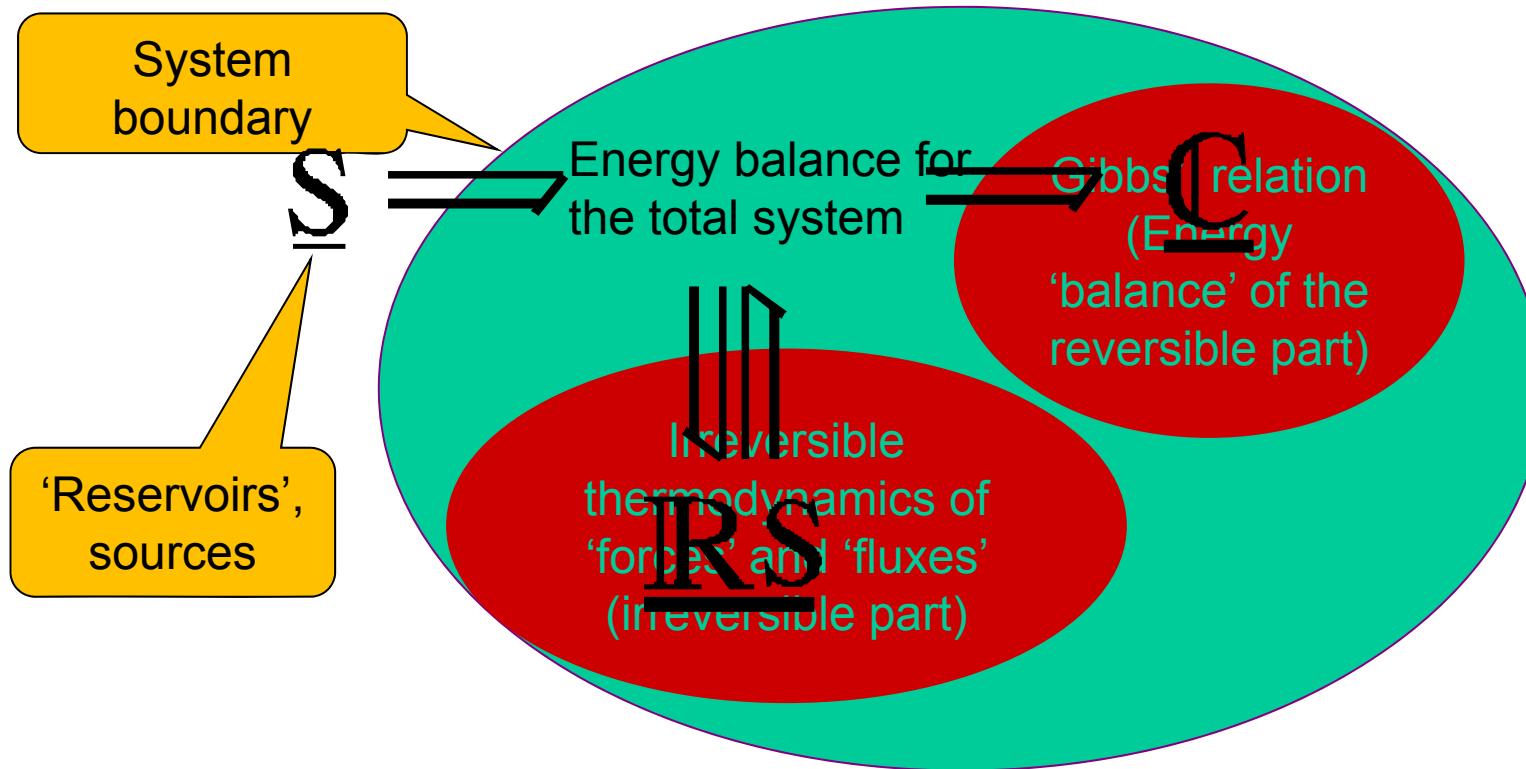


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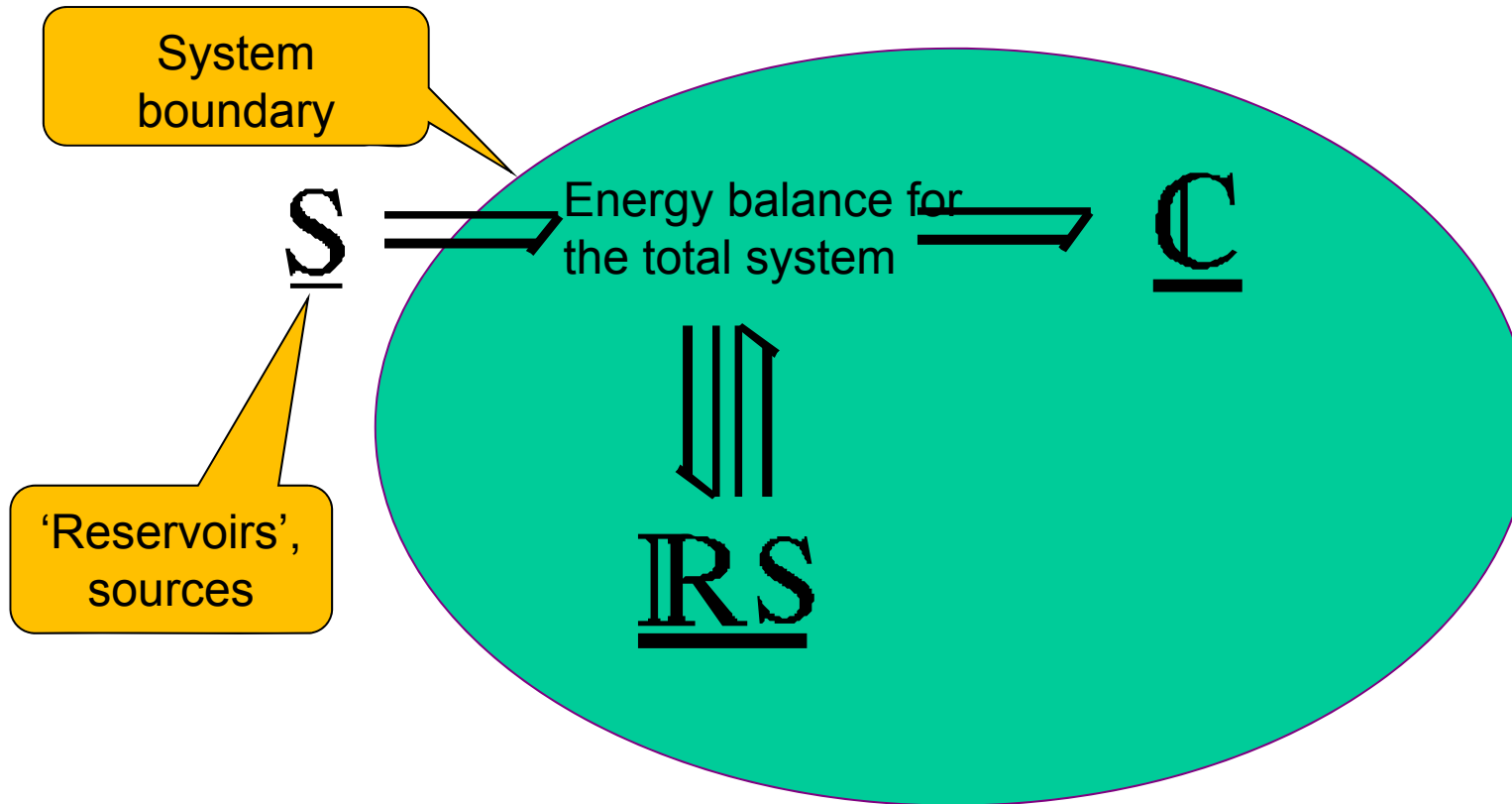




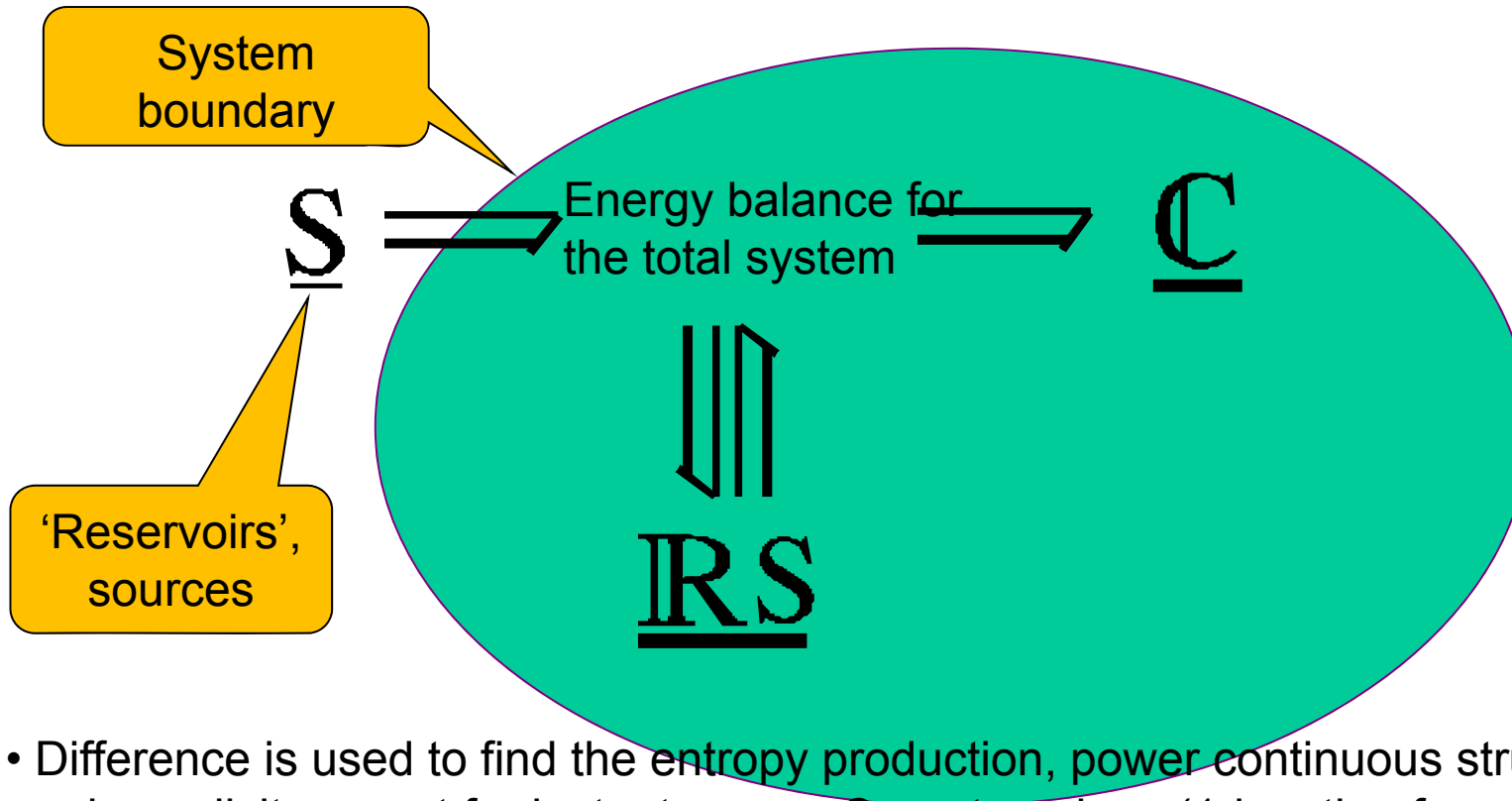
# THERMODYNAMIC APPROACH



# THERMODYNAMIC APPROACH

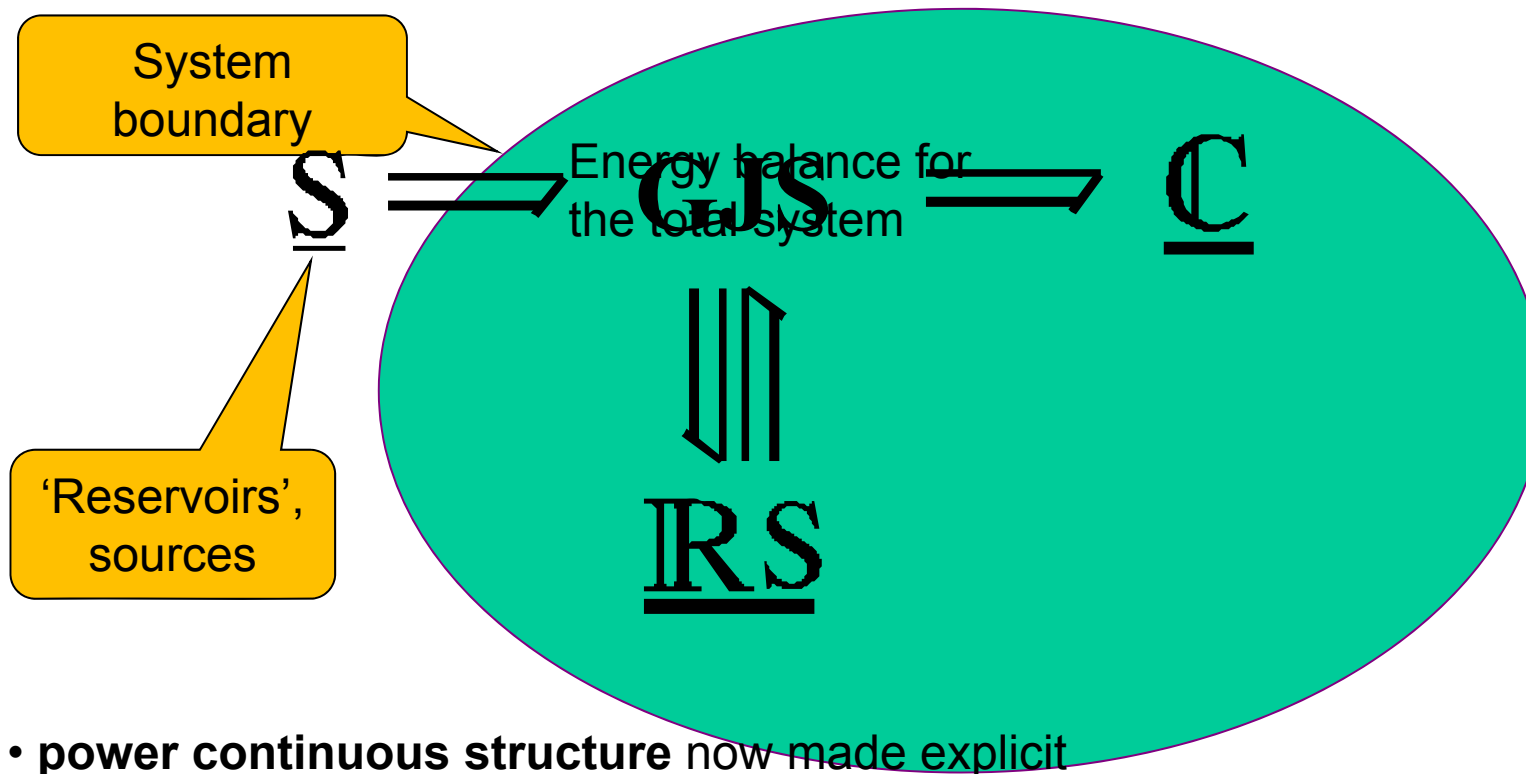


# THERMODYNAMIC APPROACH



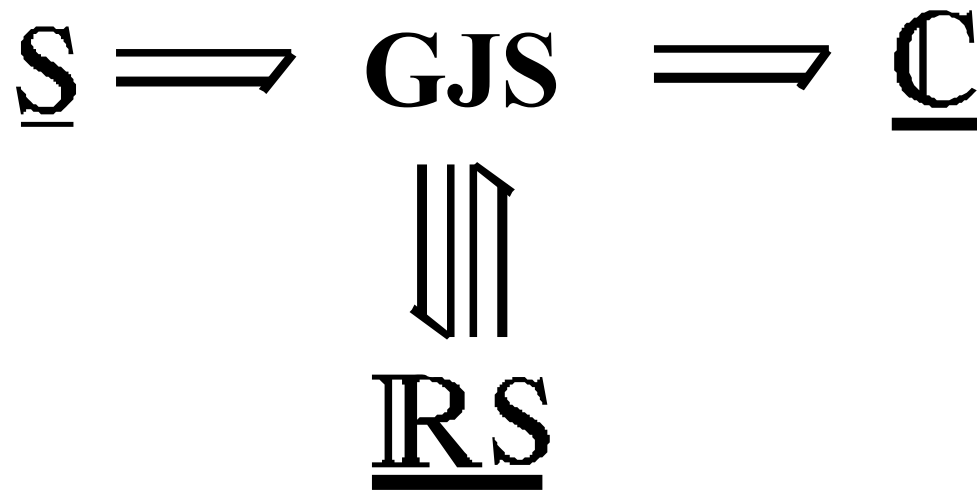
- Difference is used to find the entropy production, power continuous structure not made explicit, except for instantaneous Carnot engines (1-junction for entropy flow)

# NETWORK THERMODYNAMIC APPROACH



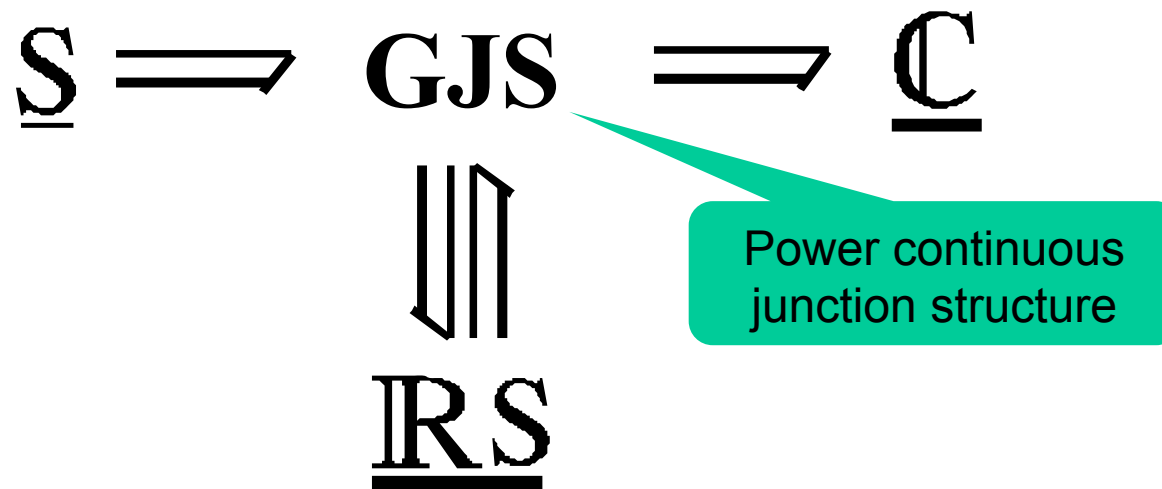
- **power continuous structure** now made explicit

## NETWORK THERMODYNAMIC APPROACH



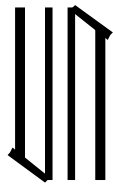
- simplified picture, containing the same information...

# NETWORK THERMODYNAMIC APPROACH



# NETWORK THERMODYNAMIC APPROACH

$$\underline{S} \Rightarrow \text{GJS} \Rightarrow \underline{C}$$

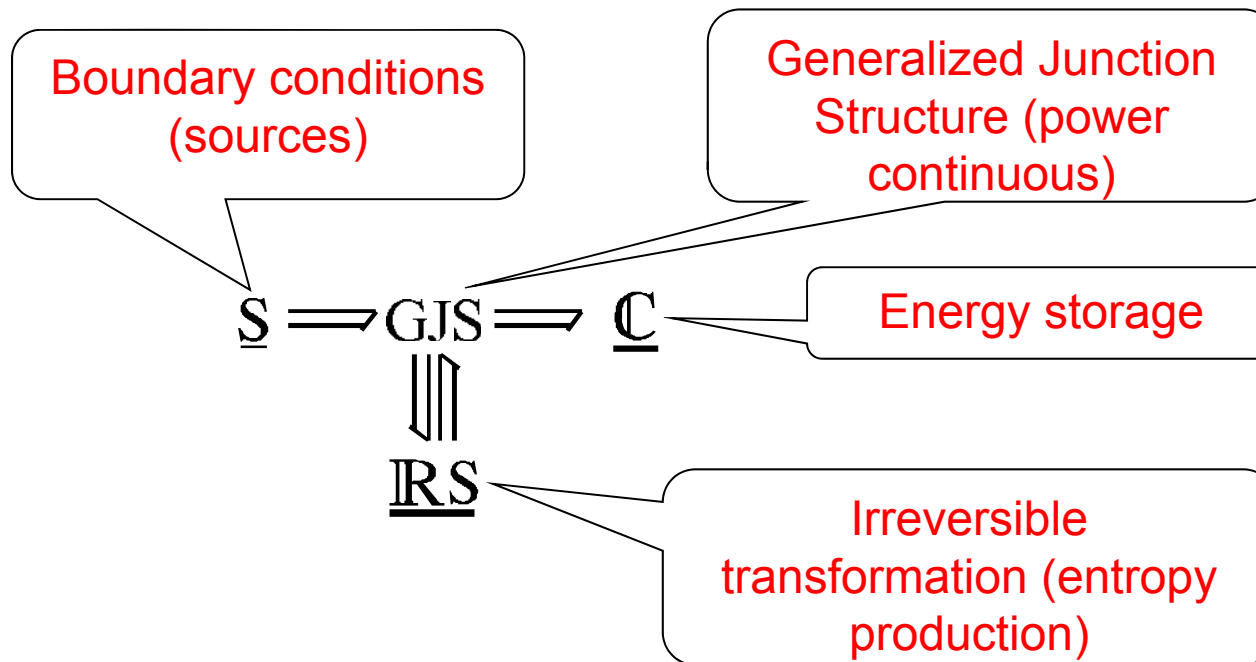


IRS

Power continuous  
junction structure

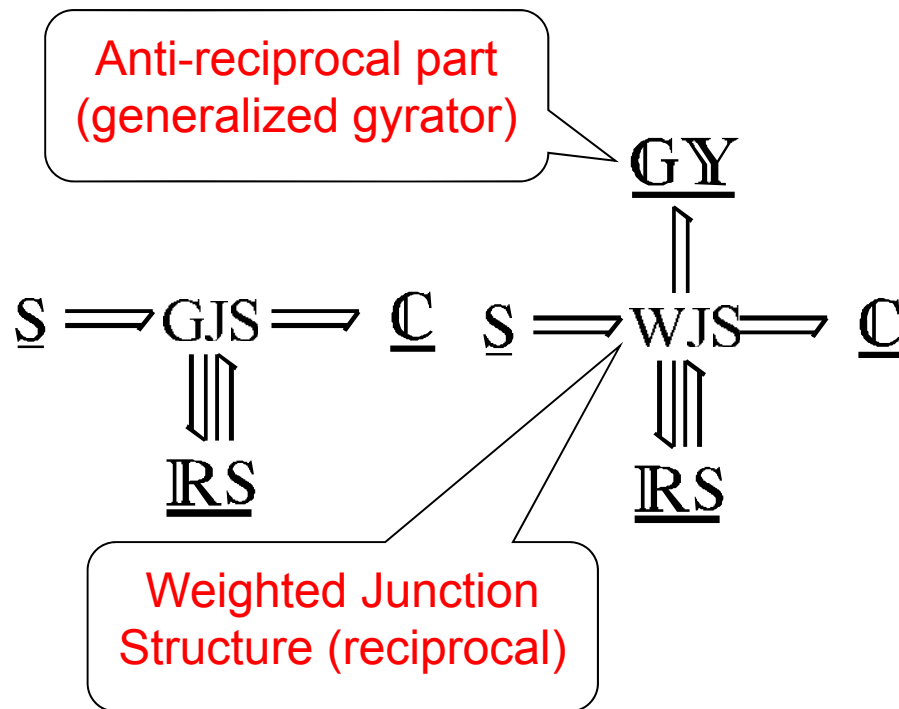
Structure is **conceptual** !

# BASIC MODEL STRUCTURE (GENERALIZED BOND GRAPH)

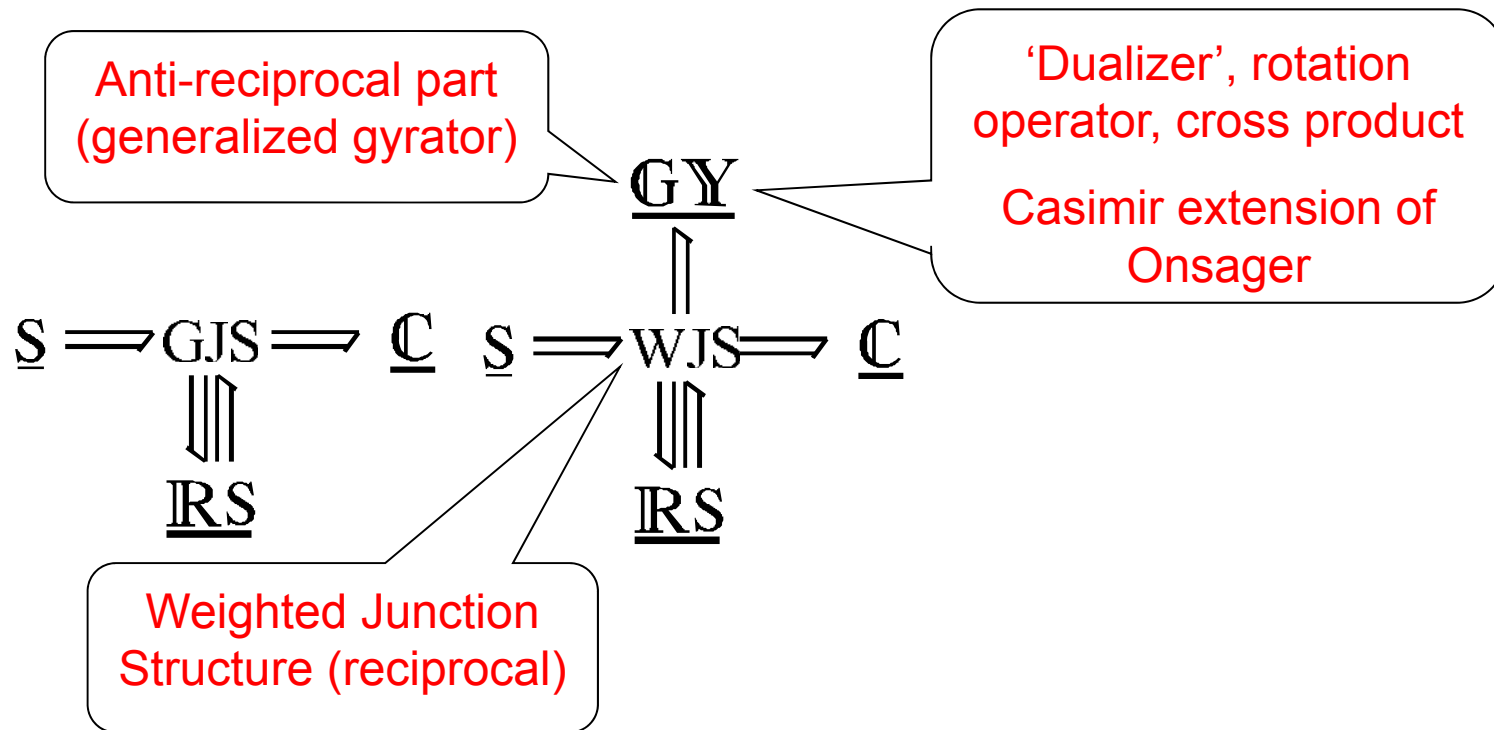




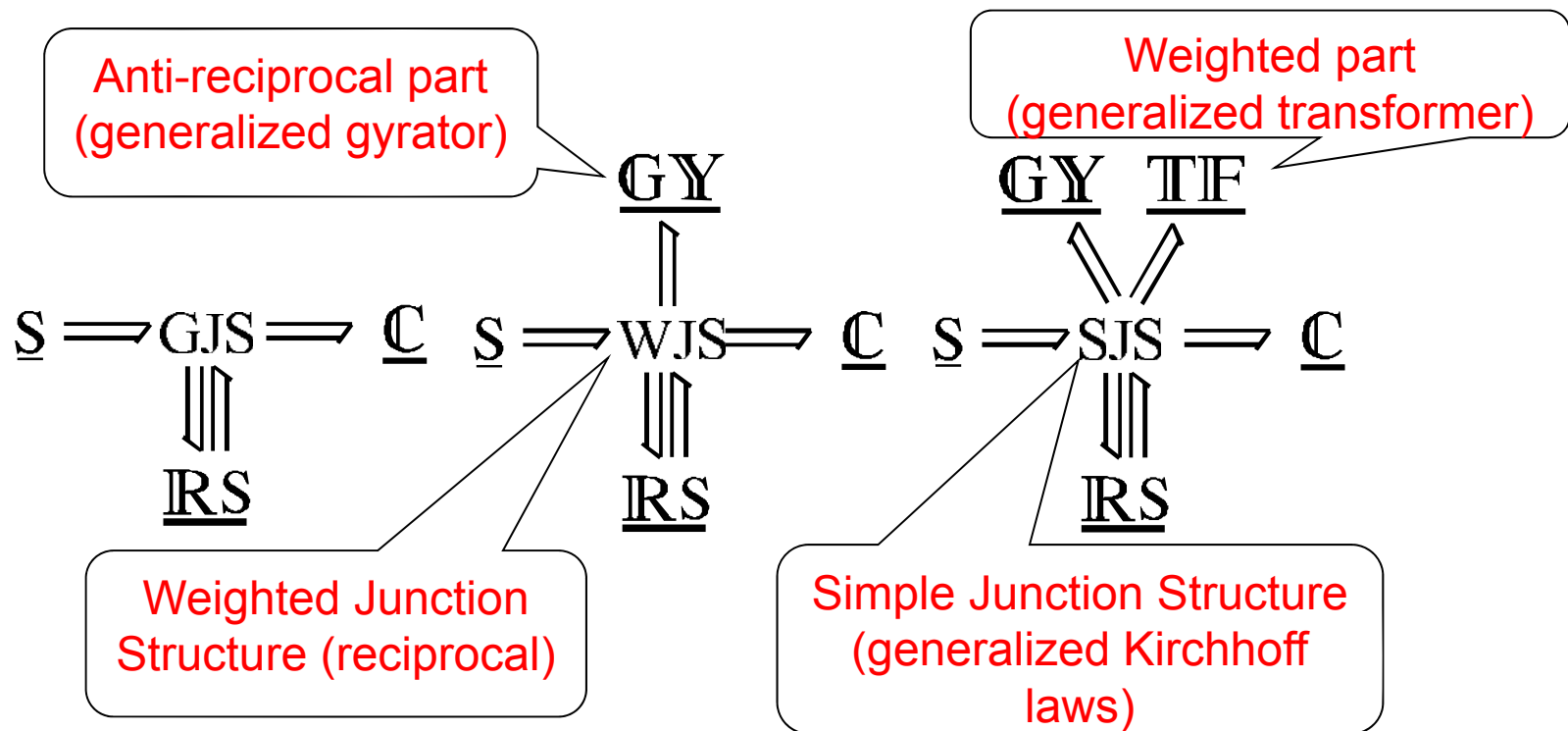
# BASIC MODEL STRUCTURE (GENERALIZED BOND GRAPH)



# BASIC MODEL STRUCTURE (GENERALIZED BOND GRAPH)



# BASIC MODEL STRUCTURE (GENERALIZED BOND GRAPH)



## CONFIGURATION INFLUENCE ON ENERGETIC STRUCTURE

- can ‘become’ an **additional energy state**: geometric parameter in storage relation results in a force

$$F(q, x) = \frac{\partial E(q, x)}{\partial x}$$

- examples: LVDT, electret microphone, relay, (ideal) gas etc. (MP C)
- *cycles allow transduction*
- changes of causality correspond to Legendre transforms!! (relation to dissipation)
- can **modulate** an energy relation
  - examples: crank-slider *mechanism*, etc. (MTF)
- can **switch** a contact (or behavior)

## ENERGY AS STARTING POINT

- **Energy**
  - $E = E(\underline{q}) = E(q_1, \dots, q_i, \dots, q_n)$
  - Homogeneous function of set of extensive state variables
- In ('generalized') *mechanics* : Hamiltonian
  - $E = H(\underline{q}, \underline{p}) = H(q_1, \dots, q_i, \dots, q_k, p_1, \dots, p_i, \dots, p_k)$
- In *thermodynamics* of 'simple' systems: internal energy
  - $E = U(\underline{q}) = U(V, S, N)$
  - more species:  $E = U(\underline{q}) = U(V, S, \underline{N}) =$   
 $= U(V, S, N_1, \dots, N_i, \dots, N_m) =$   
 $= U(V, S, N_1, \dots, N_i, \dots, N_{m-1}, N)$

## ENERGY-BASED MODEL FORMULATION

- Energy and power: domain independent concepts
- An energy function of a set of  $k$  conserved states  $q$ :  $E(q_1, \dots, q_i, \dots, q_k)$
- Result in a power:

$$P = \frac{dE(q_1, \dots, q_i, \dots, q_k)}{dt} = \sum_{i=1}^k \frac{\partial E(q_1, \dots, q_i, \dots, q_k)}{\partial q_i} \frac{dq_i}{dt} = \sum_{i=1}^k e_i f_i$$

- where  $f_i = \frac{dq_i}{dt}$  is an equilibrium-establishing variable or *flow*
- and  $e_i(q_1, \dots, q_i, \dots, q_k) = \frac{\partial E(q_1, \dots, q_i, \dots, q_k)}{\partial q_i}$  is an equilibrium-determining variable or *effort*
- ***This distinction is lost in a Hamiltonian framework!***



## ENERGY-BASED MODELING APPROACH

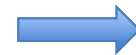
- **Note that a balance equation for a conserved, extensive state**

$$\frac{dq}{dt} = \sum \varepsilon f$$

with  $\varepsilon = \pm 1$  depending on direction w.r.t. positive orientation

- **May now be written as**

$$\sum \varepsilon f = 0$$



# GENERALIZED THERMODYNAMIC FRAMEWORK OF VARIABLES

	$f$ flow	$e$ effort	$q = \int f dt$ generalized state
<i>electric</i>	$i$ current	$u$ voltage	$q = \int i dt$ charge
<i>magnetic</i>	$u$ voltage	$i$ current	$\lambda = \int u dt$ magnetic flux linkage
<i>thermal</i>	$T$ temperature	$f_S$ entropy flow	$S = \int f_S dt$ entropy
<i>chemical</i>	$\mu$ chemical potential	$f_N$ molar flow	$N = \int f_N dt$ number of moles



## GENERALIZED THERMODYNAMIC FRAMEWORK OF VARIABLES

	$f$ flow	$e$ effort	$q = \int f dt$ generalized state
<i>elastic/potential translation</i>	$v$ velocity	$F$ force	$x = \int v dt$ displacement
<i>kinetic translation</i>	$F$ force	$v$ velocity	$p = \int F dt$ momentum
<i>elastic/potential rotation</i>	$\omega$ angular velocity	$T$ torque	$\theta = \int \omega dt$ angular displacement
<i>kinetic rotation</i>	$T$ torque	$\omega$ angular velocity	$b = \int T dt$ angular momentum
<i>elastic hydraulic</i>	$\varphi$ volume flow	$p$ pressure	$V = \int \varphi dt$ volume
<i>kinetic hydraulic</i>	$p$ pressure	$\varphi$ volume flow	$\Gamma = \int p dt$ momentum of a flow tube

## MECHANICAL FRAMEWORK OF VARIABLES

	$f$ flow	$e$ effort	$q = \int f dt$ generalized displacement	$p = \int e dt$ generalized momentum
<i>electromagnetic</i>	$i$ current	$u$ voltage	$q = \int i dt$ charge	$\lambda = \int u dt$ magnetic flux linkage
<i>mechanical translation</i>	$v$ velocity	$F$ force	$x = \int v dt$ displacement	$p = \int F dt$ momentum
<i>mechanical rotation</i>	$\omega$ angular velocity	$T$ torque	$\theta = \int \omega dt$ angular displacement	$b = \int T dt$ angular momentum
<i>hydraulic</i>	$\varphi$ volume flow	$p$ pressure	$V = \int \varphi dt$ volume	$\Gamma = \int p dt$ momentum of a flow tube

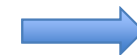
## SYNTHESIS OF MECHANICAL & THERMODYNAMIC FRAMEWORK

<u>Mechanics:</u>	<u>Thermodynamics:</u>
Two types of storage	One type of storage
Oscillatory behavior (damped): C-I(-R)	Only relaxation behavior: C-R
Split domains (therm.) and couple by <i>SGY</i> (mech.): $C-SGY-C$	

## GENERALIZED THERMODYNAMIC FRAMEWORK

## UNRESOLVED ISSUE?

- What is analog to what?
  - Mass and coil or mass and capacitor?  
or
  - Spring and capacitor or spring and coil?
- Long debates since mid thirties...



## PHYSICAL MEANING OF THE SYMPLECTIC GYRATOR

- Electrical network  $(q, \lambda)$ :
  - Only* if **quasi-stationary** (non-radiating),  
Maxwell's equations reduce to:

$$\begin{array}{c}
 \boxed{-\frac{d\lambda}{dt} = u} \quad \boxed{e_{mag} = i} \\
 \\
 \begin{array}{c}
 \mathbf{C} \leftarrow \begin{array}{l} e_{mag} = \frac{\partial E}{\partial \lambda} \\ f_{mag} = \frac{d\lambda}{dt} \end{array} \quad \begin{array}{l} e_{mag} = i \\ -\frac{d\lambda}{dt} = u \end{array} \quad \mathbf{SGY} \quad \begin{array}{l} e_{elec} = u \\ f_{elec} = i \end{array} \quad \begin{array}{l} e_{elec} = \frac{\partial E}{\partial q} \\ f_{elec} = \frac{dq}{dt} \end{array} \rightarrow \mathbf{C}
 \end{array}
 \end{array}$$

–Dualizing effect!

## PHYSICAL MEANING OF THE SYMPLECTIC GYRATOR

- Mechanical  $(x,p)$ 
  - *Only* when in **inertial** frames, i.e. when Newton's 2<sup>nd</sup> law holds:

$$\begin{array}{ccccccc}
 \mathbf{C} & \leftarrow & \begin{array}{c} e_{kin} = \frac{\partial E}{\partial p} \\ f_{kin} = \frac{dp}{dt} \end{array} & \begin{array}{c} e_{kin} = v \\ F = -\frac{dp}{dt} \end{array} & \rightarrow & \text{SGY} & \leftarrow & \begin{array}{c} e_{pot} = F \\ f_{pot} = v \end{array} & \begin{array}{c} e_{pot} = \frac{\partial E}{\partial x} \\ f_{pot} = \frac{dx}{dt} \end{array} & \rightarrow & \mathbf{C} \\
 & & \circ & \circ & & & \circ & \circ & & & \circ & \circ
 \end{array}$$

$$F = -\frac{dp}{dt}$$

# 'SPECIAL' STATES

## Position/displacement

- has a *dual* nature:
  - **energy** state (related to a conservation or symmetry principle like all other states)
  - **configuration** state

## Matter

- convects all matter-bound properties (not 'available volume'!)
- conjugate intensity depends on other intensities (Gibbs-Duhem)
- *boundary criterion*

## Volume

- *boundary criterion*

## Entropy

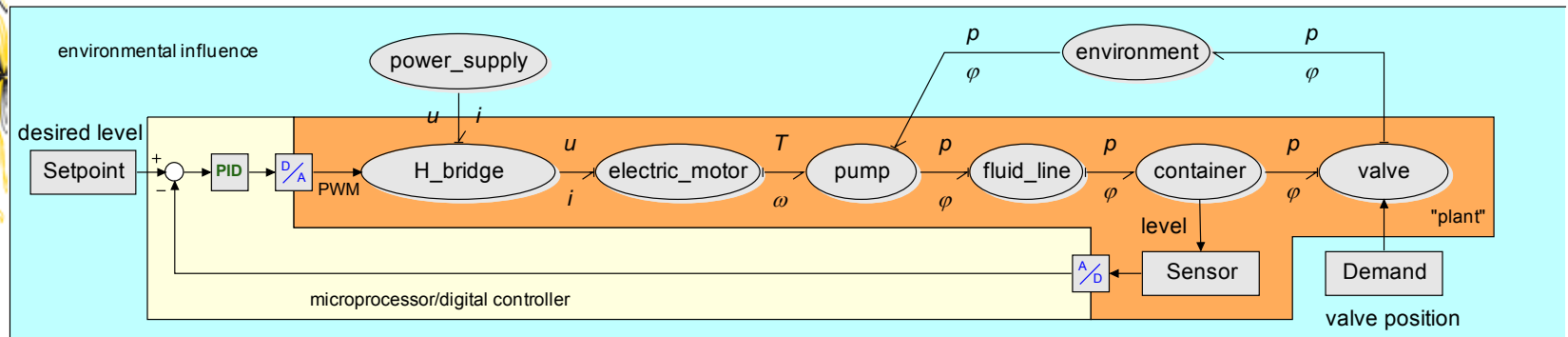
- can be 'locally' *produced* & is only 'locally' conserved (conceptual separation!)

## SYSTEM (BOUNDARY) DEFINITION

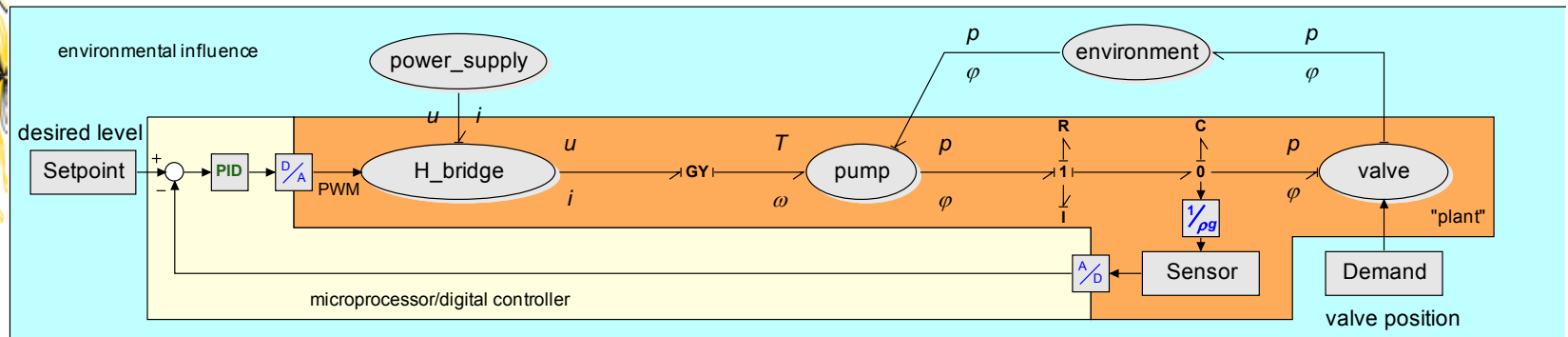
- Open (thermodynamic) systems
- $d\mathbf{N} = \mathbf{0}$  ( $dm=MdN=0$ ) : ‘Lagrangian coordinates’, material boundary criterion:
  - $\mathbf{N}$  not a state
- $d\mathbf{V} = \mathbf{0}$  ( $A dx=0$ ): ‘Eulerian coordinates’ (control volume, spatial boundary criterion):
  - $\mathbf{V}$  not a state
- Almost always **mixed** boundaries:
  - $\mathbf{N}$  and  $\mathbf{V}$  **remain states** for system under study!
- **Tangible system:** *globally Lagrangian, locally Eulerian*
- **Network of subsystems:** *globally Eulerian, locally Lagrangian* (e.g. network of elastic tubes)



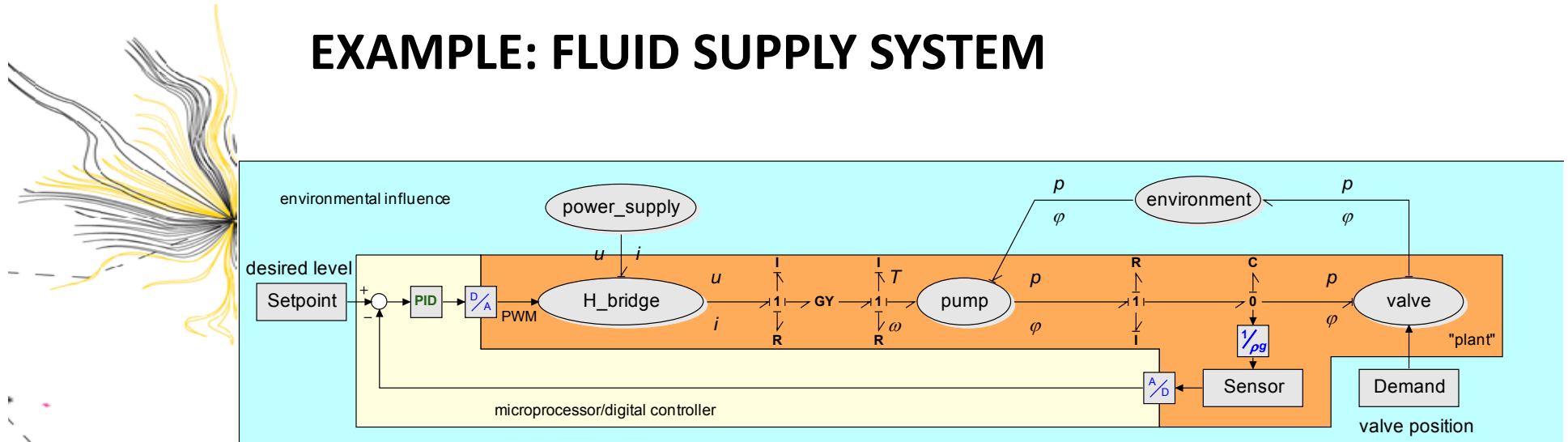
# EXAMPLE: FLUID SUPPLY SYSTEM COMPONENT LEVEL



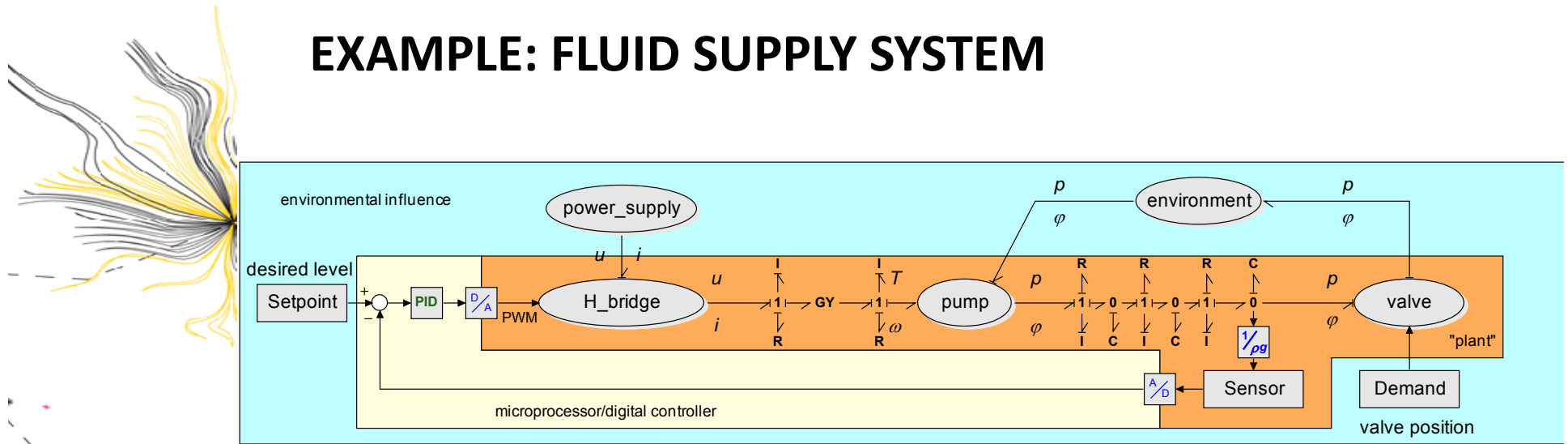
# EXAMPLE: FLUID SUPPLY SYSTEM CONCEPTUAL ELEMENTS



# EXAMPLE: FLUID SUPPLY SYSTEM



# EXAMPLE: FLUID SUPPLY SYSTEM





## EXAMPLE: ELECTRIC MOTOR

- **Most dominant: power transduction**
- **But also possible:**
  - **Multiport energy storage (magnetic, kinetic, thermal), necessarily reversible (cycle process is always required!), *linear* decomposition results in a transducer and 1-ports**
  - **Separate (conceptual!): irreversible transduction, electrical resistance and mechanical friction**
  - **etc.**



## EXAMPLE: FLUID LINE

- **Dominant: fluid resistance**
- **1) If relatively long and narrow: fluid inertia**
  - **Conceptual structure: common flow, summation of pressure drops, not separated in space!**
- **2) Compressibility:**
  - **Several segments (R,I,C)**
  - **Normal modes**
- **3) Compressible fluid, convecting momentum and entropy (also charge, flux,...): conceptual structure**
- **4) Elastic tube wall: mixed boundaries**



## TRANSPORT IN ENGINEERING SYSTEMS

- **System boundary: globally Lagrangian (commonly at rest), locally Eulerian (commonly closed)**
- **Tangible subsystem boundaries (components): globally Eulerian (network w.r.t. system boundary), locally Lagrangian (components have fixed neighbors, exceptions require bookkeeping, while major system structure is maintained)**
- ***Conceptual* (abstract) subsystem boundaries: structure is based on distinction between basic dynamic behaviors and not based on material or spatial criteria**



## 'ENERGY DENSITY' IMPLIES A FIRST DEGREE HOMOGENEOUS ENERGY

- **Conserved energy has to be a homogeneous function of conserved states:**

$$E(\mathbf{q}, m, V): \left(\frac{1}{m}\right)^n E\left(\frac{\mathbf{q}}{m}, 1, \frac{V}{m}\right) = \left(\frac{1}{m}\right)^{n=1} E\left(\frac{\mathbf{q}}{m}, 1, \frac{V}{m}\right) = \varepsilon_m\left(\frac{\mathbf{q}}{m}, v\right)$$

$$E(\mathbf{q}, m, V): \left(\frac{1}{V}\right)^n E\left(\frac{\mathbf{q}}{V}, \frac{m}{V}, 1\right) = \left(\frac{1}{V}\right)^{n=1} E\left(\frac{\mathbf{q}}{V}, \rho, 1\right) = \varepsilon_V\left(\frac{\mathbf{q}}{N}, \rho\right)$$

- **Convection requires that addition of subsystems means interaction-free addition of extensive states and addition of (extensive) energy:**
- **$n=1$  in principle (if all states are considered!)**





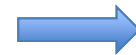
## FIRST DEGREE HOMOGENEOUS ENERGY

- **Generalized Gibbs' relation:**  $E(\mathbf{q}) = \frac{1}{n} \sum \frac{\partial E}{\partial q_i} q_i \stackrel{n=1}{=} \sum e_i q_i$
- **First degree homogeneous energy implies zero degree constitutive relations (intensity!):**

$$e_i(\alpha \mathbf{q}) = \frac{\partial E(\alpha \mathbf{q})}{\partial \alpha q_i} = \frac{\alpha \partial E(\mathbf{q})}{\alpha \partial q_i} = \frac{\partial E(\mathbf{q})}{\partial q_i} = \alpha^0 e_i(\mathbf{q})$$

$$\sum_{i=1}^k q_i d \frac{\partial E}{\partial q_i} = \sum_{i=1}^k q_i d e_i = 0 \quad k-1 \text{ independent intensities}$$

- **One-port storage cannot exist *in principle*, unless constant states are considered parameters**



## GENERALIZING GIBBS AND GIBBS-DUHEM

$$u = Ts - pv + \sum_{i=1}^{m-1} \mu_i \frac{N_i}{N} + \mu^{tot} \quad (\text{Gibbs})$$

$$0 = sdT - vdp + \sum_{i=1}^{m-1} \frac{N_i}{N} d\mu_i + d\mu^{tot} \quad (\text{Gibbs-Duhem})$$

$$u = Ts - pv + \sum_{i=1}^{m-1} \mu_i \frac{N_i}{N} + \mu^{tot} + v \frac{\bar{p}}{N} + e_i \frac{q_i}{N} \quad (\text{Generalized Gibbs})$$

$$0 = sdT - vdp + \sum_{i=1}^{m-1} \frac{N_i}{N} d\mu_i + d\mu^{tot} + \frac{\bar{p}}{N} dv + \frac{q_i}{N} de_i \quad (\text{Generalized Gibbs-Duhem})$$

Specific quantities are 'weighting factors'



## CONJUGATE FLOW RELATIONS

$$\left(\frac{dS}{dt}\right)_{convected} = \left(\frac{S}{N}\right) \frac{dN}{dt}; \quad \left(\frac{dN_i}{dt}\right)_{convected} = \left(\frac{N_i}{N}\right) \frac{dN}{dt}; \quad \left(\frac{dV}{dt}\right)_{convected} = 0!$$

$$\left(\frac{dq_i}{dt}\right)_{convected} = \left(\frac{q_i}{N}\right) \frac{dN}{dt}; \quad \left(\frac{d\bar{p}}{dt}\right)_{convected} = \left(\frac{\bar{p}}{N}\right) \frac{dN}{dt}; \quad \left(\frac{dN_i}{dt}\right)_{convected} = \left(\frac{N_i}{N}\right) \frac{dN}{dt}$$

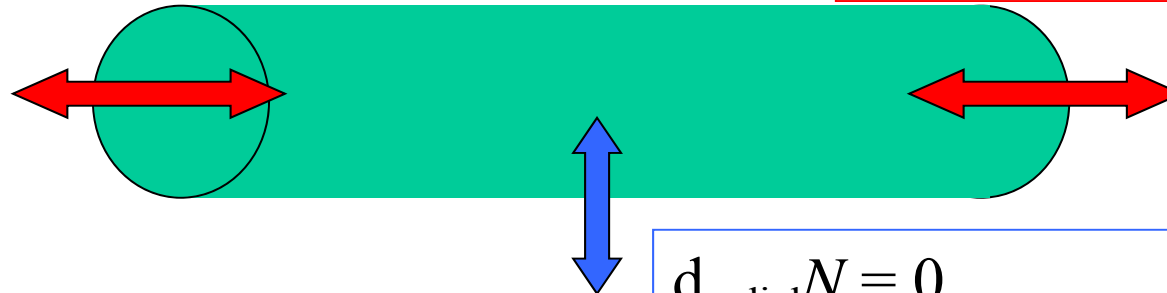
$$\left(\frac{dS}{dt}\right)_{convected} = \left(\frac{S}{N}\right) \frac{dN}{dt}; \quad \left(\frac{dV}{dt}\right)_{convected} = 0!$$

Same specific quantities are 'weighting factors'



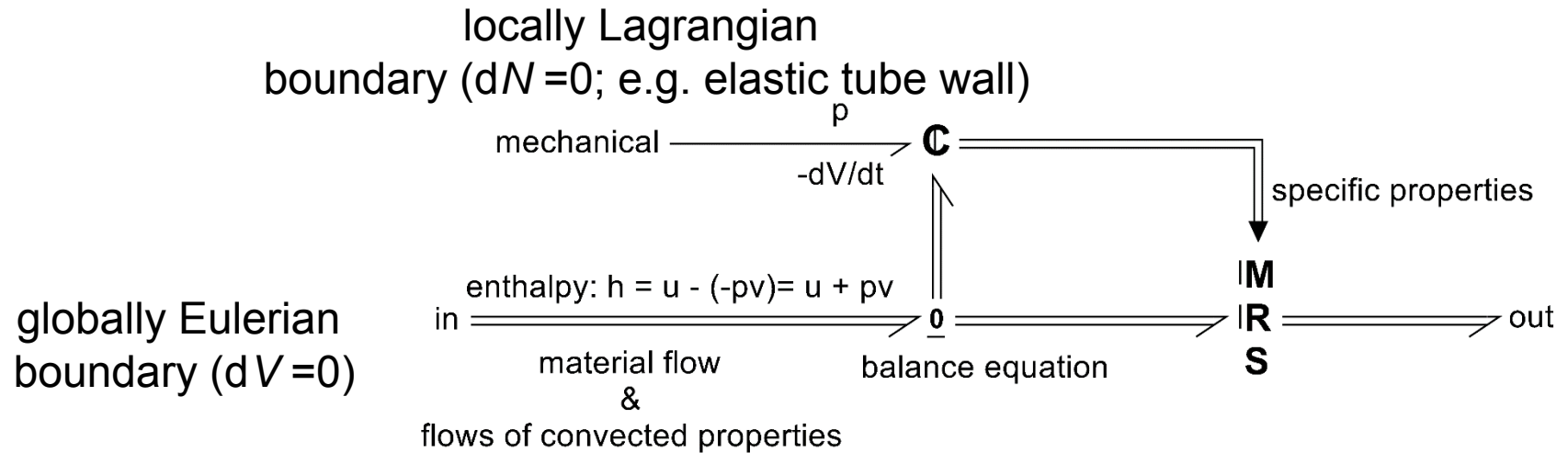
## PART OF A TUBE NETWORK

$$\begin{aligned}d_{\text{axial}} V &= 0 \\ & \text{(} V \text{ not a convected property)} \\ d_{\text{axial}} N &\neq 0\end{aligned}$$



$$\begin{aligned}d_{\text{radial}} N &= 0 \\ d_{\text{radial}} V &\neq 0 \\ & \text{(flexible tube, local changes)}\end{aligned}$$

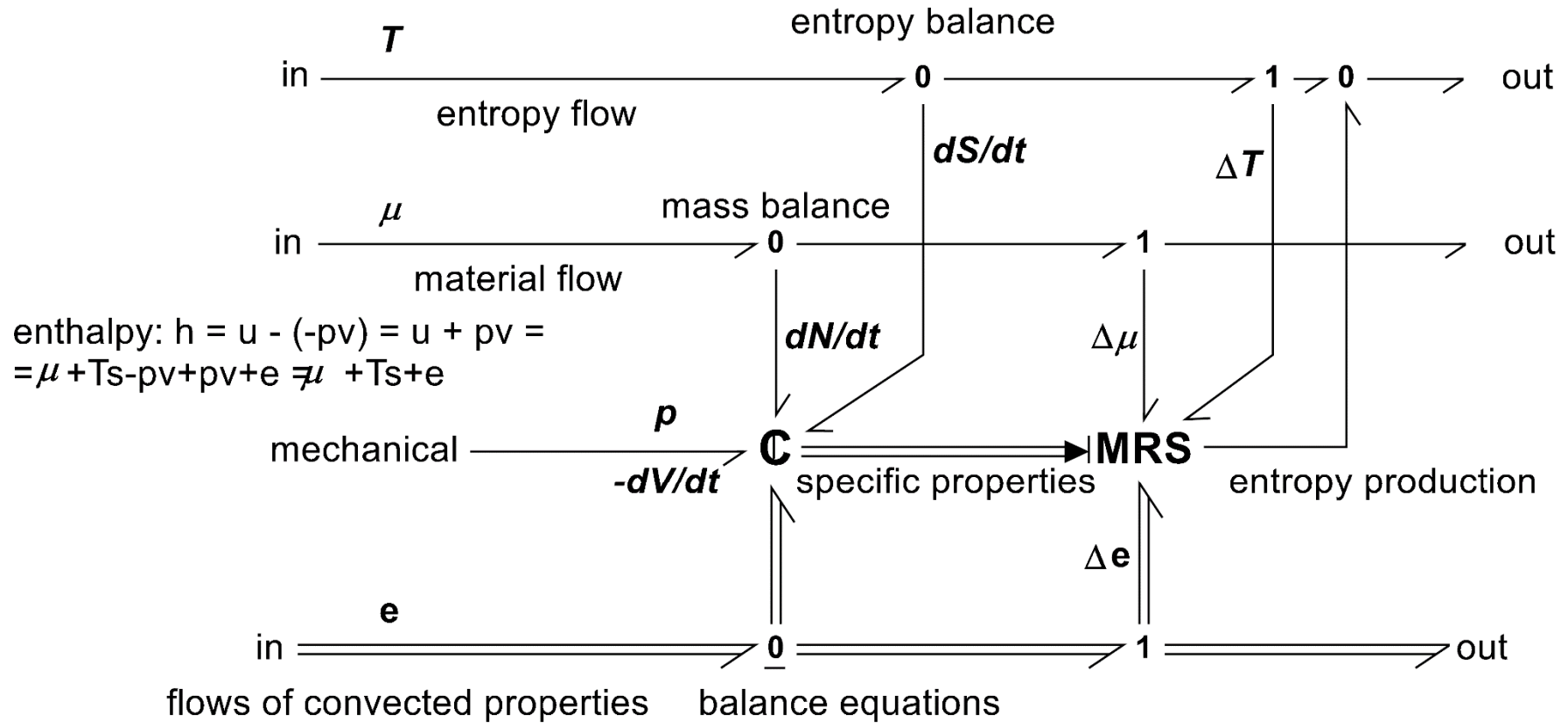
# GENERIC PICTURE: MASS/MATERIAL FLOW



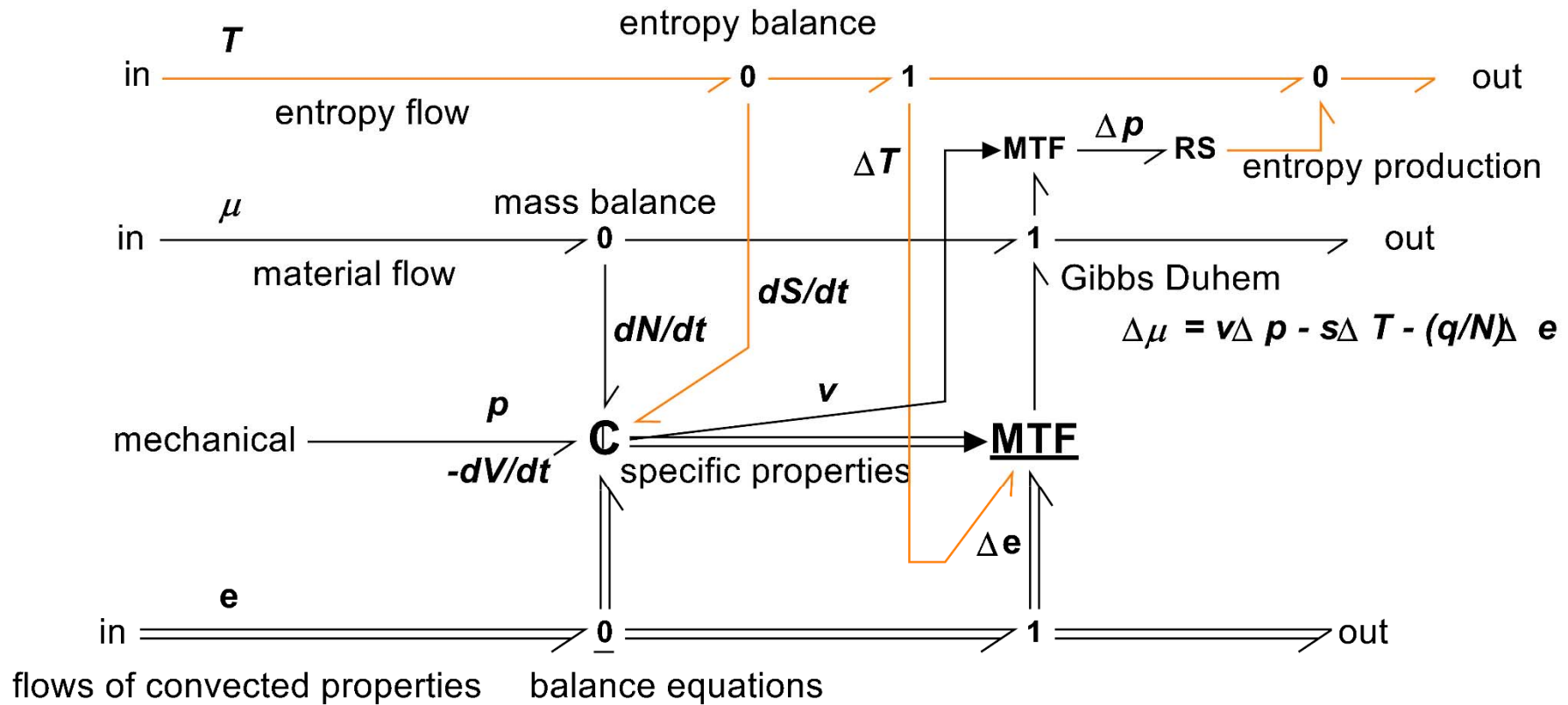
Total energy 'flow': 
$$(e + pv) \frac{dN}{dt} + p \left( -\frac{dV}{dt} \right) = \frac{dE}{dt}$$

but the specific enthalpy  $h$  **cannot** serve as an equilibrium-determining variable

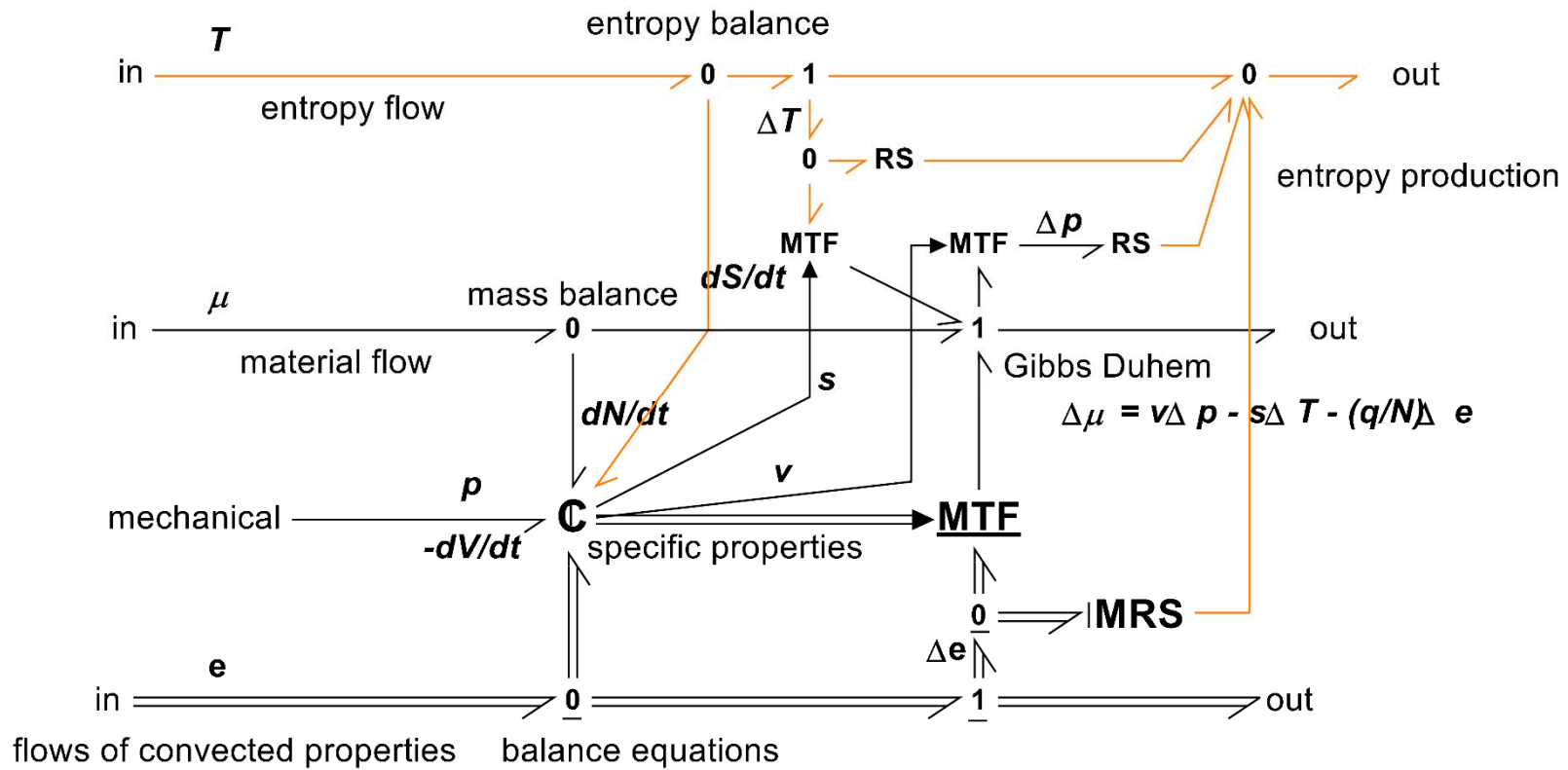
# GENERIC PICTURE: SPLIT OUT FLOWS



# GENERIC PICTURE: NO 'SLIP'

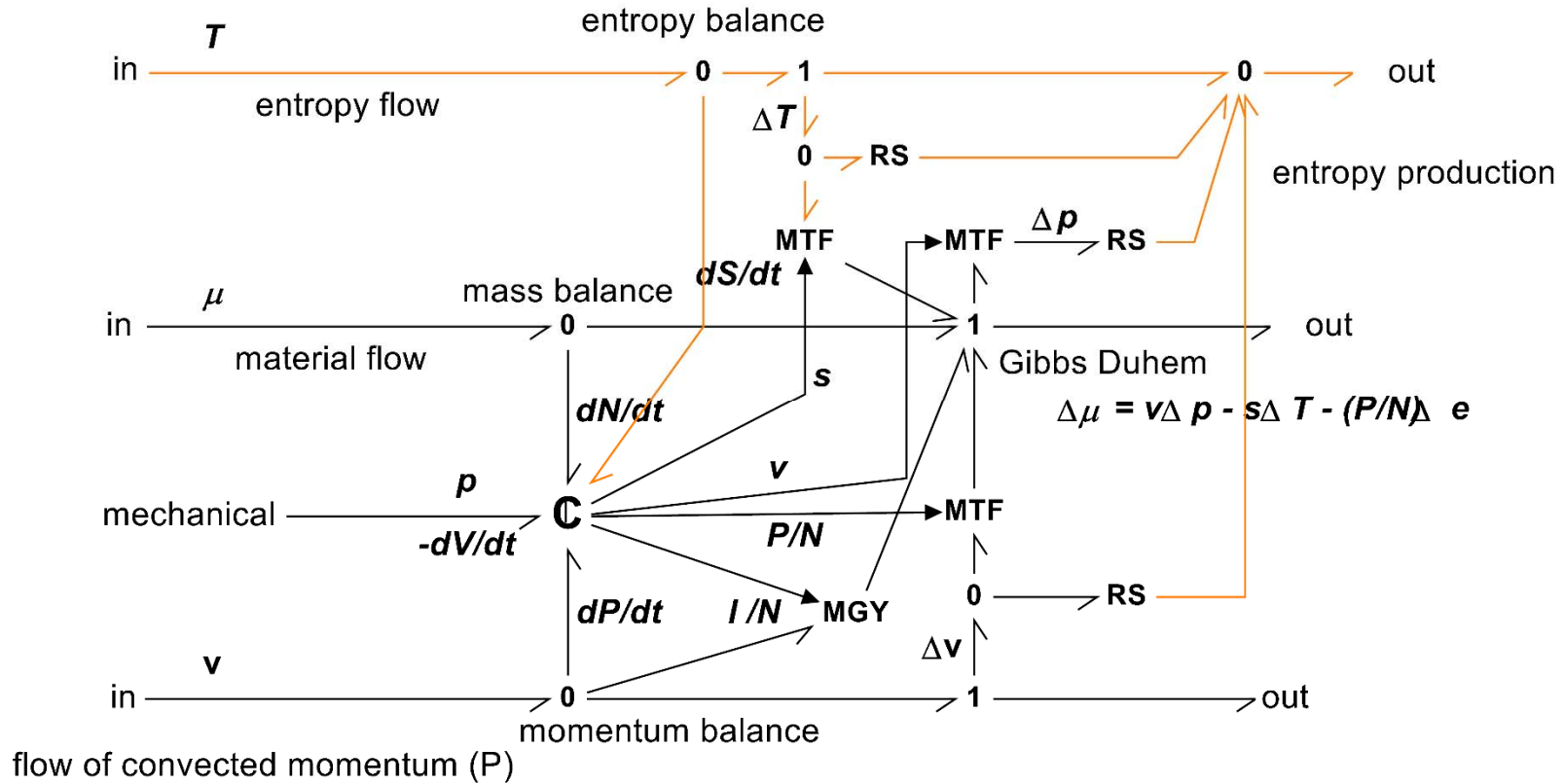


# GENERIC PICTURE: WITH 'SLIP' OF CONVECTED PROPERTIES

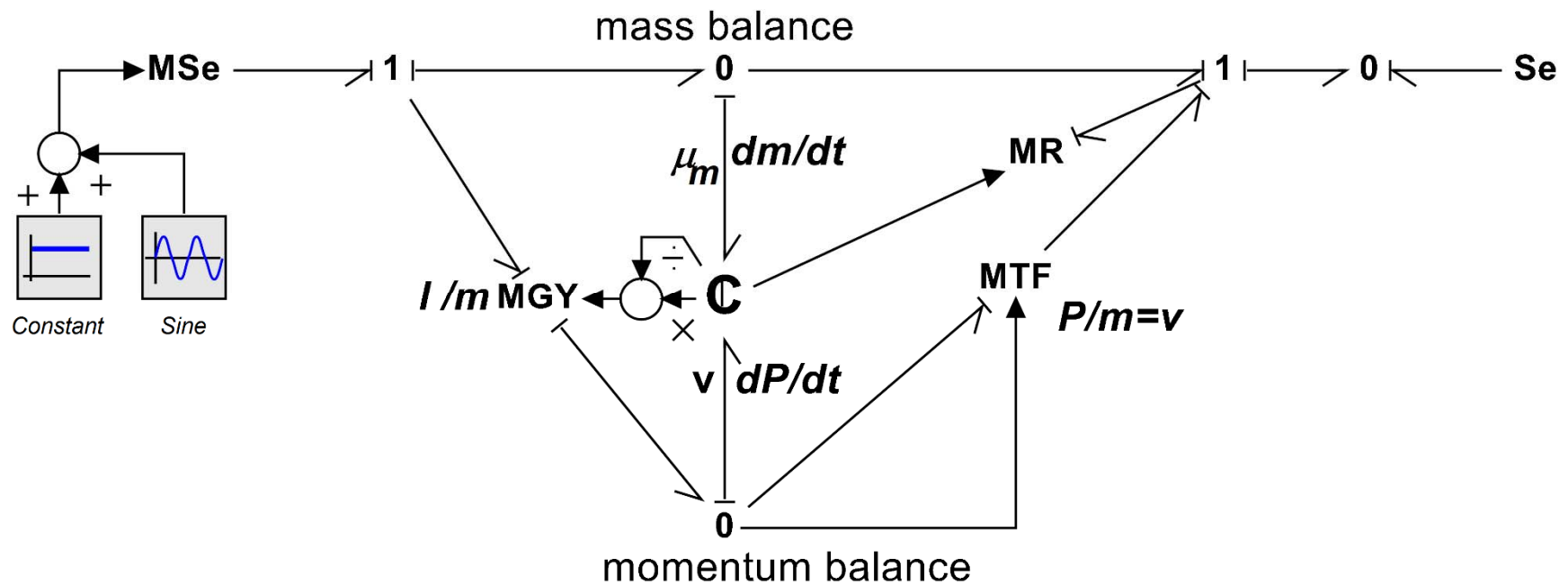




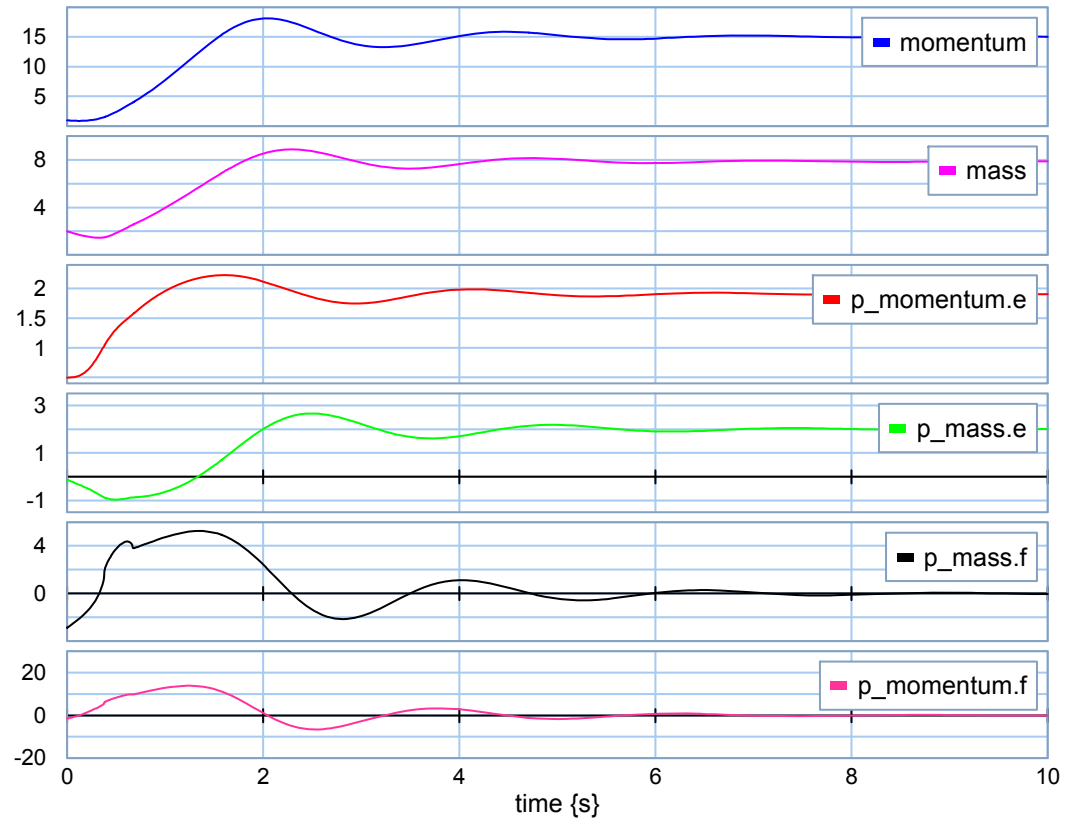
# GENERIC PICTURE: MOMENTUM CONVECTION



# SIMPLIFIED: MOMENTUM CONVECTION, RIGID TUBE WALL

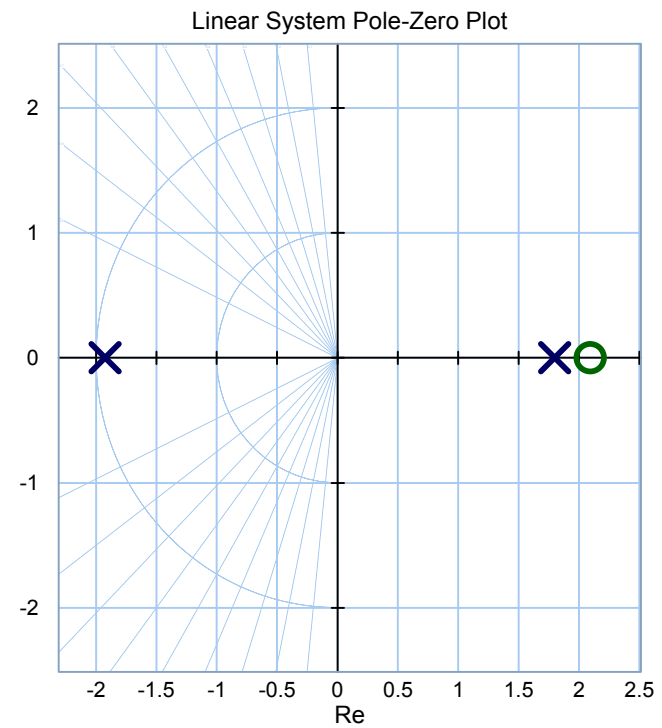
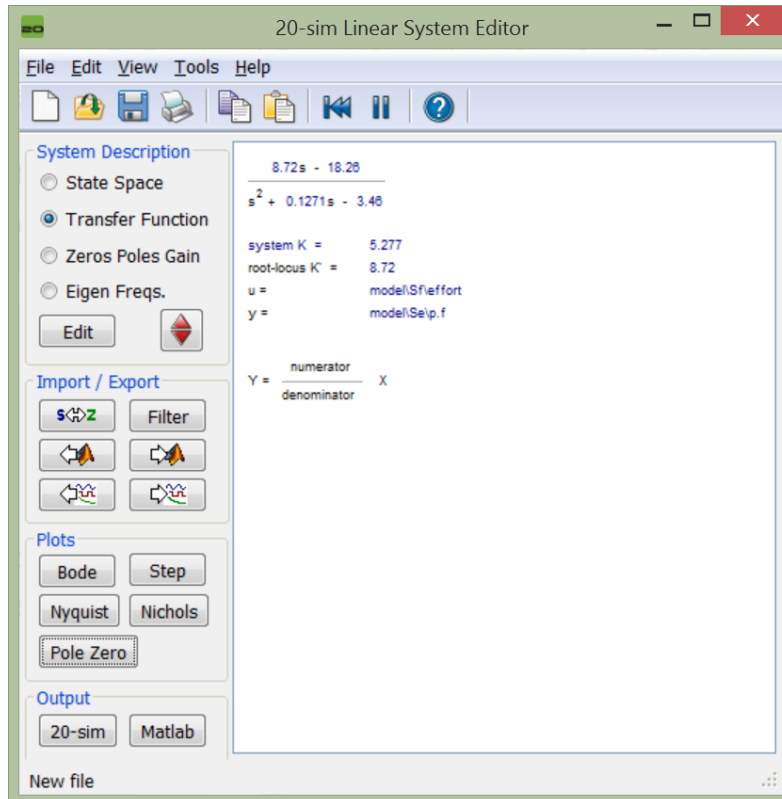


# NON-MINIMUM PHASE RESPONSE



Just qualitative,  
numbers have  
no meaning!

# NON-MINIMUM PHASE RESPONSE





## CONCLUSIONS

- separation between *configuration* and *energy* states: more insight
- system boundary definitions may be *mixed*: Eulerian vs Lagrangian
- concept of energy *density* (material of spatial) synonymous with first degree homogeneous energy function of all possible extensive states *in principle*
- energy-based modeling approach:
  - automatically satisfies fundamental principles of physics when all grammar rules are obeyed
  - systematic approach to the dynamic behavior of all properties that may be *convected* in principle (e.g. momentum, electric charge, etc.);
- generalized thermodynamic framework of variables more general than Hamiltonian (generalized mechanical) framework:
  - some domains have no dual storage