

Proximity bounds for random integer programs

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Abstract. We study proximity bounds within a natural model of random integer programs of the type $\max \mathbf{c}^\top \mathbf{x} : \mathbf{A}\mathbf{x} = \mathbf{b}, \mathbf{x} \in \mathbb{Z}_{\geq 0}$, where $\mathbf{A} \in \mathbb{Z}^{m \times n}$ of rank m , $\mathbf{b} \in \mathbb{Z}^m$ and $\mathbf{c} \in \mathbb{Z}^n$. We prove that (up to a constant depending on n) the proximity is “generally” bounded by $\Delta_m(\mathbf{A})^{1/(n-m)}$, where $\Delta_m(\mathbf{A})$ is the maximal absolute value of an $m \times m$ subdeterminant of \mathbf{A} . This is significantly better than the best deterministic bounds which are linear in $\Delta_m(\mathbf{A})$.

1 Introduction

Given an linear program of the form

$$\begin{aligned} \max \quad & \mathbf{c}^\top \mathbf{x} : \mathbf{A}\mathbf{x} = \mathbf{b} \\ & \mathbf{x} \geq \mathbf{0}, \end{aligned} \tag{1}$$

where \mathbf{A} is a full-row-rank $m \times n$ integral matrix, $\mathbf{b} \in \mathbb{Z}^m$, and $\mathbf{c} \in \mathbb{Z}^n$, the proximity problem seeks to understand how far away an optimal feasible solution \mathbf{x}^* can be to a nearby feasible integer solution \mathbf{z}^* . Assuming the feasible region has at least one such integral point, bounds for proximity are typically given in terms of the largest possible absolute value $\Delta_m(\mathbf{A})$ of any $m \times m$ subdeterminant of \mathbf{A} . This is a well-studied problem which goes back to the classic Cook et al. result [4] bounding the proximity of the dual of (1). See, for instance, the recent works of Eisenbrand and Weismantel [5] and of Aliev, Henk, and Oertel [1] and the references therein.

In this manuscript, we would like to understand the worst-possible proximity, which we denote by $\text{dist}(\mathbf{A})$, over all choices of \mathbf{b} and \mathbf{c} , when the matrix \mathbf{A} is chosen *randomly*. The model of randomness we consider is the following: we choose the matrix \mathbf{A} up to left-multiplication by unimodular matrices, and we choose

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\mathbf{A} uniformly at random subject to the condition that $\Delta(\mathbf{A}) := \sqrt{\det \mathbf{A} \mathbf{A}^\top}$ is at most some large, fixed integer T . This is a natural model to study from a geometric point of view, as $\Delta(\mathbf{A})$ is the determinant of the lattice of integer points in the kernel of \mathbf{A} . This is also the model considered by Aliev and Henk in [2], in their investigation of diagonal Frobenius numbers.

Our main result concerns not $\text{dist}(\mathbf{A})$ but rather a related random variable we denote by $\text{dist}^*(\mathbf{A})$. This is an asymptotic version of $\text{dist}(\mathbf{A})$ that further imposes some mild restrictions on \mathbf{b} . Our main result is that it satisfies the following Markov-type inequality:

$$\mathbf{P} \left(\text{dist}^*(\mathbf{A}) > t \Delta(\mathbf{A})^{1/(n-m)} \right) \ll t^{-2/3}. \quad (2)$$

Here \ll means less than, up to constants which only depend on the dimension. In particular, this shows that proximity generally depends only on $\Delta^{1/(n-m)}$ in the random setting, for “almost all” choices of \mathbf{b} in a certain precise sense. This is significantly better than the linear dependency on Δ_m in the deterministic case, that is known to be tight [1 Theorem 1]. A similar result, with a slightly different random model, was obtained in [1] the so-called knapsack scenario, where $m = 1$. We also mention recent work of Oertel, Paat, and Weismantel in [8], which considers a random model that allows \mathbf{b} to vary but keeps \mathbf{A} fixed.

The proof of this result combines ideas of [2] and [1] using facts from the geometry of numbers, some results of Schmidt from [9] on random sublattices of \mathbb{Z}^n of fixed dimension, and computations of the measure of certain distinguished regions of the real Grassmannian $\text{Gr}(n, d)$ of d -dimensional subspaces of \mathbb{R}^n . The idea is two-fold. First, we use the results of Schmidt to relate the discrete measure in our model to the continuous $O(n)$ -invariant probability measure ν of $\text{Gr}(n, d)$. We show that there are essentially two distinct “bad” regions of $\text{Gr}(n, d)$, both parameterized by t , in which $\text{dist}^*(\mathbf{A})$ could be large, but whose measure with respect to ν gets smaller as t gets larger.

We remark that the exponent of $-2/3$ is mainly an artifact of the proof, and we expect that it can be further improved. The problem of finding an inequality analogous to [2] for $\text{dist}(\mathbf{A})$ is more challenging and remains open, as the polyhedral combinatorics of [1] may interfere with our analysis.

2 Main result and notation

2.1 Notation

Throughout this manuscript we assume fixed positive integers d, m, n such that $n = m + d$. For a subset $\sigma \subseteq [n]$ and $\mathbf{x} \in \mathbb{R}^n$, we let \mathbf{x}_σ denote the vector obtained by orthogonally projecting \mathbf{x} onto the coordinates indexed by σ . Similarly, if \mathbf{A} is a matrix, then we denote by \mathbf{A}_σ the submatrix of \mathbf{A} whose columns are those indexed by σ . In particular, if $k \in [n]$ then \mathbf{A}_k denotes the corresponding column of \mathbf{A} . If \mathbf{A}_σ is an invertible square matrix we say σ is a *basis* of \mathbf{A} . We denote the complement of σ by $\bar{\sigma} := [n] \setminus \sigma$. Given a d -dimensional subspace $L \subseteq \mathbb{R}^n$, the m -dimensional orthogonal complement of L is denoted by L^\perp . If $A \subset \mathbb{R}^n$, let $A_{\mathbb{R}}$ denote the linear subspace of \mathbb{R}^n spanned by A .

2.2 Definition of $\text{dist}(\mathbf{A})$

Given a full-rank matrix $\mathbf{A} \in \mathbb{Z}^{m \times n}$ and vector $\mathbf{b} \in \mathbb{Z}^m$, we define the polyhedron

$$\mathcal{P}(\mathbf{A}, \mathbf{b}) := \{\mathbf{x} \in \mathbb{R}^n : \mathbf{A}\mathbf{x} = \mathbf{b}, \mathbf{x} \geq \mathbf{0}\}.$$

Given a vertex \mathbf{x}^* of this polyhedron, we define

$$\text{dist}(\mathbf{A}, \mathbf{b}, \mathbf{x}^*) := \inf_{\mathbf{z}^* \in \mathbb{Z}^n \cap \mathcal{P}(\mathbf{A}, \mathbf{b})} \|\mathbf{x}^* - \mathbf{z}^*\|_2.$$

We then define the worst-case distance over all right-hand-side vectors $\mathbf{b} \in \mathbb{Z}^m$ for which $\mathcal{P}(\mathbf{A}, \mathbf{b})$ is nonempty, and over all vertices \mathbf{x}^* of $\mathcal{P}(\mathbf{A}, \mathbf{b})$:

$$\text{dist}(\mathbf{A}) := \sup_{\mathbf{b}} \sup_{\mathbf{x}^*} \text{dist}(\mathbf{A}, \mathbf{b}, \mathbf{x}^*). \quad (3)$$

This definition has the disadvantage that it is stated in terms of the matrix \mathbf{A} . Since we may replace $\mathbf{A}\mathbf{x} = \mathbf{b}$ with $\mathbf{U}\mathbf{A}\mathbf{x} = \mathbf{U}\mathbf{b}$ for any unimodular $m \times m$ matrix \mathbf{U} , it is not so clear from this formulation how to define our random model. This motivates an alternative, more geometric definition of $\text{dist}(\mathbf{A})$ which we now state.

2.3 Definition of $\text{dist}(\Lambda)$

Suppose instead we start with a *primitive* d -dimensional sublattice Λ of \mathbb{Z}^n , meaning that $\Lambda = \Lambda_{\mathbb{R}} \cap \mathbb{Z}^n$. Let $\mathbf{A} \in \mathbb{Z}^{m \times n}$ be any integral matrix for which the rows of \mathbf{A} form a basis of $\Lambda_{\mathbb{R}}^{\perp} \cap \mathbb{Z}^n$. Suppose σ is basis of Λ , and \mathbf{x}^* is a vector lying in the semigroup

$$\mathcal{S}_{\sigma} := \{\mathbf{x} \in \mathbb{Q}^n : \mathbf{x}_{\sigma} \in \mathbf{A}_{\sigma}^{-1} \mathbb{Z}^m, \mathbf{x}_{\bar{\sigma}} = \mathbf{0}, \mathbf{x}_{\sigma} \geq \mathbf{0}\}.$$

Then we may define

$$\text{dist}(\Lambda, \sigma, \mathbf{x}^*) := \text{dist}(\mathbf{A}, \mathbf{b}, \mathbf{x}^*), \quad (4)$$

where $\mathbf{b} := \mathbf{A}\mathbf{x}^*$, and

$$\text{dist}(\Lambda) := \sup_{\sigma} \sup_{\mathbf{x}^*} \text{dist}(\Lambda, \sigma, \mathbf{x}^*), \quad (5)$$

where the supremum is taken over all bases σ of Λ and elements $\mathbf{x}^* \in \mathcal{S}_{\sigma}$. Importantly, note that definitions (4) and (5) do not depend on the choice of \mathbf{A} , but only on the data $(\Lambda, \sigma, \mathbf{x}^*)$ and Λ , respectively.

One easily checks that the definitions of (3) and (5) agree. Nevertheless, the advantage of definition (5) is that there are only finitely many d -dimensional sublattices Λ of \mathbb{Z}^n whose determinant $\Delta(\Lambda) := \Delta(\mathbf{A})$ is at most some fixed positive integer T . Thus, we may consider the uniform distribution over these bounded-determinant lattices.

2.4 An asymptotic version of $\text{dist}(\Lambda)$

Again assume the rows of \mathbf{A} form a basis of $\Lambda_{\mathbb{R}}^{\perp} \cap \mathbb{Z}^n$. We next consider a related version of $\text{dist}(\mathbf{A})$, or equivalently $\text{dist}(\Lambda)$. Let $B_2^n \subset \mathbb{R}^n$ denote the n -dimensional Euclidean ball. Define the vector $\mathbf{w} \in \mathbb{R}^n$ as follows: for each $i \in [n]$, set

$$\mathbf{w}_i := \sqrt{1 - \mathbf{A}_i^{\top} (\mathbf{A}\mathbf{A}^{\top})^{-1} \mathbf{A}_i}. \quad (6)$$

This vector \mathbf{w} measures, for each $i \in [n]$, the largest possible value of \mathbf{x}_i for any $\mathbf{x} \in B_2^n \cap \Lambda_{\mathbb{R}}$. Denote by $\mu := \mu(\Lambda, B_2^n)$ the covering radius of B_2^n with respect to Λ . That is,

$$\mu := \inf \{t > 0 : \Lambda + tB_2^n \text{ contains } \Lambda_{\mathbb{R}}\}.$$

If σ is a basis of \mathbf{A} then define the following subsemigroup of \mathcal{S}_{σ} :

$$\mathcal{S}_{\sigma}^* := \{\mathbf{x} \in \mathcal{S}_{\sigma} : \mathbf{x}_{\sigma} \geq \mu \mathbf{w}_{\sigma} + \mathbf{A}_{\sigma}^{-1} \mathbf{A}_{\sigma} \mathbf{w}_{\sigma}\}.$$

The next proposition shows that if we further restrict \mathbf{x}^* so that it can only lie in \mathcal{S}_{σ}^* , then we can guarantee that $\mathcal{P}(\mathbf{A}, \mathbf{b})$ contains an integral point reasonably close to \mathbf{x}^* . We prove it in Section [5](#)

Proposition 1. *For a basis σ of \mathbf{A} and $\mathbf{x}^* \in \mathcal{S}_{\sigma}^*$, let $\mathbf{b} = \mathbf{A}\mathbf{x}^*$. Then $\mathcal{P}(\mathbf{A}, \mathbf{b})$ contains a translate of the scaled ball $\mu \cdot (B_2^n \cap \Lambda_{\mathbb{R}})$, which in turn contains an integral vector.*

Now set

$$\text{dist}^*(\Lambda) := \sup_{\sigma} \sup_{\mathbf{x}^*} \text{dist}(\Lambda, \sigma, \mathbf{x}^*), \quad (7)$$

where the supremum is taken over all bases σ of \mathbf{A} and elements \mathbf{x}^* of the semigroup \mathcal{S}_{σ}^* .

2.5 Main result

We are now ready to state the main theorem.

Theorem 1. *For $T \gg 1$, let Λ be a primitive sublattice of \mathbb{Z}^n of dimension d and determinant at most T , chosen uniformly at random. Then for all $t > 1$,*

$$\mathbf{P} \left(\text{dist}^*(\Lambda) > t (\Delta(\Lambda))^{1/d} \right) \ll t^{-2/3}.$$

3 A theorem of Schmidt

In this section we state a result that is fundamental to the proof, which follows from the results of Schmidt in [9](#). We continue with our assumption that $d = n - m$. Let $\text{Gr}(d, n)$ denote the set of d -dimensional subspaces of \mathbb{R}^n . Let ν denote the unique $O(n)$ -invariant probability measure on the real Grassmannian $\text{Gr}(d, n)$.

Definition 1 ([9 p. 40]). A set $\xi \subset \text{Gr}(d, n)$ is Jordan measurable if for all $\varepsilon > 0$ there exists continuous functions $f_1 \leq \mathbf{1}_\xi \leq f_2$ such that

$$\int (f_2 - f_1) d\nu < \varepsilon.$$

Here $\mathbf{1}_\xi$ denotes the indicator function of ξ .

Definition 2. Let $\mathbf{a} = (a_1, \dots, a_d) \in \mathbb{R}^d$, with each $a_i \geq 1$. Let T be a positive integer, and let $\xi \subset \text{Gr}(d, n)$. Then we define $G(\mathbf{a}, \xi, T)$ to be the set of sublattices Λ of \mathbb{Z}^n of dimension d with determinant at most T , such that

$$\frac{\lambda_{i+1}(\Lambda)}{\lambda_i(\Lambda)} \geq a_i \text{ for all } i = 1, 2, \dots, d,$$

and $\Lambda_{\mathbb{R}} \in \xi$.

The result of Schmidt that we intend to use is a combination of Theorems 3 and 5 in [9]:

Theorem 2. Assuming $\xi \subset \text{Gr}(d, n)$ is Jordan measurable, we have

$$|G(\mathbf{a}, \xi, T)| \asymp \left(\prod_{i=1}^{d-1} a_i^{-i(d-i)} \right) \nu(\xi) T^n,$$

where $f \asymp g$ means $f \ll g$ and $g \ll f$.

Let $G(d, n, T)$ denote the set of all sublattices of \mathbb{Z}^n of dimension d with determinant at most T . Let $\mathbf{P} = \mathbf{P}_{d, n, T}$ denote the uniform probability distribution over $G(d, n, T)$.

Corollary 1. For $t > 1$, we have

$$\mathbf{P} \left(\max_{i \in [d]} \left\{ \frac{\lambda_{i+1}(\Lambda)}{\lambda_i(\Lambda)} \right\} \geq t \right) \ll (d-1) t^{-(d-1)}.$$

Proof. Following Aliev and Henk in [2], let

$$\delta_i(t) := \left(1, \dots, 1, t, 1, \dots, 1 \right)^\top \in \mathbb{R}^d.$$

Applying the union bound to Theorem 2 this probability is at most

$$\sum_{i=1}^{d-1} \frac{|G(\delta_i(t), \text{Gr}(d, n), T)|}{|G(\delta_i(1), \text{Gr}(d, n), T)|} \ll \sum_{i=1}^{d-1} t^{-i(d-i)} \leq (d-1) t^{-(d-1)}.$$

4 Typical Cramer's rule ratios

This section is devoted to showing that the largest absolute value of any entry of the matrix $\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}}$ is typically not too large, when the subspace $L := \ker \mathbf{A}$ is chosen uniformly at random from $\text{Gr}(d, n)$. Note that the matrix $\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}}$ depends only on L and σ . We remark that the entries of the matrix $\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}}$ are explicitly computed using Cramer's rule: for $i \in \sigma$ and $j \notin \sigma$, we have

$$(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i = \frac{\det(\mathbf{A}_{\sigma-i+j})}{\det(\mathbf{A}_\sigma)}.$$

4.1 The real Grassmannian

For a general introduction to matrix groups and Grassmannians, we refer the reader to [3]. There is a right action of the orthogonal group $O(n)$ on $\text{Gr}(d, n)$ defined as follows: if $\ker(\mathbf{A}) \in \text{Gr}(d, n)$, where $\mathbf{A} \in \mathbb{R}^{m \times n}$, then

$$(\ker(\mathbf{A})) \cdot \mathbf{U} = \ker(\mathbf{A}\mathbf{U}). \quad (8)$$

This is well-defined, since if $\ker(\mathbf{A}) = \ker(\mathbf{A}')$ for some $\mathbf{A}' \in \mathbb{R}^{m \times n}$, then $\mathbf{A} = D\mathbf{A}'$ for some invertible $m \times m$ matrix D , and hence

$$\ker(\mathbf{A}\mathbf{U}) = \ker(D\mathbf{A}'\mathbf{U}) = \ker(\mathbf{A}'\mathbf{U}).$$

Let $\text{St}^{m \times n} := \{\mathbf{A} \in \mathbb{R}^{m \times n} : \text{rank}(\mathbf{A}) = m\}$. Call this the *Stiefel manifold*. Again, there is a right action of $O(n)$ on $\text{St}^{m \times n}$ which in this case is simply right multiplication:

$$\mathbf{A} \cdot \mathbf{U} = \mathbf{A}\mathbf{U}.$$

The only thing to check here is that $\mathbf{A}\mathbf{U}$ indeed lies in $\text{St}^{m \times n}$, but this is indeed the case since

$$\mathbf{A}\mathbf{U}(\mathbf{A}\mathbf{U})^\top = \mathbf{A}\mathbf{U}\mathbf{U}^\top\mathbf{A}^\top = \mathbf{A}\mathbf{A}^\top,$$

thus \mathbf{A} and $\mathbf{A}\mathbf{U}$ have the same Gram matrix $\mathbf{A}\mathbf{A}^\top$, and a $m \times n$ matrix has full-rank if and only if its Gram matrix does.

The kernel map gives rise to a surjective map

$$\begin{aligned} \ker : \text{St}^{m \times n} &\rightarrow \text{Gr}(d, n) \\ \mathbf{A} &\mapsto \ker(\mathbf{A}) \end{aligned}$$

Thus, we see from [8] that the following statement holds:

Proposition 2. *The map $\ker : \text{St}^{m \times n} \rightarrow \text{Gr}(d, n)$ is equivariant with respect to the right actions of $O(n)$ on $\text{St}^{m \times n}$ and $\text{Gr}(d, n)$; that is, $(\ker(\mathbf{A})) \cdot \mathbf{U} = \ker(\mathbf{A} \cdot \mathbf{U})$.*

4.2 Probability spaces

Consider the probability space $(\mathbb{R}^{m \times n}, \mathcal{B}(\mathbb{R}^{m \times n}), \gamma)$ where $\mathcal{B}(\mathbb{R}^{m \times n})$ is the Borel σ -algebra, and the measure γ is defined so that each $\mathbf{A} \in \mathbb{R}^{m \times n}$ has iid $N(0, 1)$ entries. In other words, γ is the standard Gaussian probability measure on the mn -dimensional real vector space $\mathbb{R}^{m \times n}$ with mean zero and identity covariance matrix. By restricting to $\text{St}^{m \times n}$, we get the probability space $(\text{St}^{m \times n}, \mathcal{B}(\text{St}^{m \times n}), \gamma)$. We can do this because $\mathbb{R}^{m \times n} \setminus \text{St}^{m \times n}$ is an algebraic hypersurface in $\mathbb{R}^{m \times n}$, and therefore has measure zero with respect to γ . Let $\mathcal{B} := \mathcal{B}(\text{St}^{m \times n})$.

The Grassmannian $\text{Gr}(d, n)$ is endowed with the topology where $E \subseteq \text{Gr}(d, n)$ is open iff $\ker^{-1}(E)$ is open in $\text{St}^{m \times n}$. Let \mathcal{G} denote the associated Borel σ -algebra. As before, we let $\nu : \mathcal{G} \rightarrow [0, 1]$ denote the $O(n)$ -invariant probability measure on $\text{Gr}(d, n)$. This measure is characterized as follows:

Proposition 3 ([7 Corollary 3.1.3]). *The measure ν is the unique measure on $\text{Gr}(d, n)$ satisfying*

$$\begin{aligned} \nu(E \cdot \mathbf{U}) &= \nu(E) \text{ for all } E \in \mathcal{G} \text{ and } \mathbf{U} \in O(n) \\ \nu(\text{Gr}(d, n)) &= 1. \end{aligned} \quad (9)$$

The map $\ker : \text{St}^{m \times n} \rightarrow \text{Gr}(d, n)$ thus defines a map of probability spaces:

$$\ker : (\text{St}^{m \times n}, \mathcal{B}, \gamma) \rightarrow (\text{Gr}(d, n), \mathcal{G}, \nu).$$

Proposition 4. *The measure ν is the pushforward measure of γ under this map. That is, $\nu(E) = \gamma(\ker^{-1}(E))$ for each $E \in \mathcal{G}$.*

Proof. We establish the conditions of [9]. By surjectivity, and the fact that γ is a probability measure, we have

$$\gamma(\ker^{-1}(\text{Gr}(d, n))) = \gamma(\text{St}^{m \times n}) = 1.$$

It therefore remains to show $\gamma(\ker^{-1}(E \cdot \mathbf{U})) = \gamma(\ker^{-1}(E))$ for each $E \in \mathcal{G}$ and $\mathbf{U} \in O(n)$. By Proposition [2], we have

$$\ker^{-1}(E \cdot \mathbf{U}) = \ker^{-1}(E) \cdot \mathbf{U}. \quad (10)$$

Now, $\mathbb{R}^{m \times n}$ has the inner product $\langle \mathbf{A}, \mathbf{B} \rangle = \text{trace}(\mathbf{A}\mathbf{B}^\top)$. With respect to this inner product we may consider the subgroup $O(m \times n)$ of $\text{GL}(\mathbb{R}^{m \times n})$ which is given by

$$O(m \times n) := \{\varphi \in \text{GL}(\mathbb{R}^{m \times n}) : \langle \varphi(\mathbf{A}), \varphi(\mathbf{B}) \rangle = \langle \mathbf{A}, \mathbf{B} \rangle\}.$$

Observe that, for a fixed $\mathbf{U} \in O(n)$, the linear map $\varphi_{\mathbf{U}} \in \text{GL}(\mathbb{R}^{m \times n})$ given by

$$\varphi_{\mathbf{U}}(\mathbf{A}) = \mathbf{A}\mathbf{U} \quad (11)$$

lies in $O(m \times n)$, since

$$\langle \varphi_{\mathbf{U}}(\mathbf{A}), \varphi_{\mathbf{U}}(\mathbf{B}) \rangle = \text{trace}(\mathbf{A}\mathbf{U}(\mathbf{B}\mathbf{U})^\top) = \text{trace}(\mathbf{A}\mathbf{B}^\top) = \langle \mathbf{A}, \mathbf{B} \rangle.$$

Now the probability measure γ on $\mathbb{R}^{m \times n}$ is defined so that the coordinates $\mathbf{A}_{i,j}$ of a randomly chosen $\mathbf{A} \in \mathbb{R}^{m \times n}$ are iid $N(0, 1)$ normally distributed. In particular this measure is invariant under isometry, in that for all $\mathcal{K} \in \mathcal{B}(\mathbb{R}^{m \times n})$ and $\varphi \in O(m \times n)$, we have

$$\gamma(\varphi(\mathcal{K})) = \gamma(\mathcal{K}). \quad (12)$$

The same is therefore true for the restricted probability measure γ on $\text{St}^{m \times n}$. It follows that if $\mathbf{U} \in O(n)$ and $E \in \mathcal{G}$, then, using [10], [11], and [12], we have

$$\gamma(\ker^{-1}(E \cdot \mathbf{U})) = \gamma(\ker^{-1}(E) \cdot \mathbf{U}) = \gamma(\varphi_{\mathbf{U}}(\ker^{-1}(E))) = \gamma(\ker^{-1}(E)).$$

4.3 Cramer's rule ratios

Let $\sigma \subset [n]$ of size m , and define

$$\begin{aligned} \text{St}_\sigma^{m \times n} &:= \{\mathbf{A} \in \text{St}^{m \times n} : \mathbf{A}_\sigma \text{ is nonsingular}\}. \\ \text{Gr}(d, n)_\sigma &:= \{\ker(\mathbf{A}) \in \text{Gr}(d, n) : \mathbf{A}_\sigma \text{ is nonsingular}\}. \end{aligned}$$

Note that $\gamma(\text{St}_\sigma^{m \times n}) = \nu(\text{Gr}(n, d)_\sigma) = 1$. Also define, for $s > 1$, $i \in \sigma$, and $j \notin \sigma$,

$$\xi_{\sigma, i, j}(s) := \{\ker(\mathbf{A}) \in \text{Gr}(d, n)_\sigma : |(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i| > s\}.$$

Proposition 5. *For $s > 1$ and σ, i, j as above, we have*

$$\nu(\xi_{\sigma, i, j}(s)) = \frac{2}{\pi s} + \mathcal{O}(s^{-3}).$$

Proof. Let \mathbf{A} be a random element of $\text{St}_\sigma^{m \times n}$, and let H denote the (random) hyperplane spanned by the columns of $\mathbf{A}_{\sigma-i}$, and let ℓ denote the line perpendicular to H . Let \mathbf{u}_ℓ denote the unit normal vector to H whose first nonzero coordinate is positive. Thus,

$$\ell = \mathbb{R}\mathbf{u}_\ell = \{\lambda\mathbf{u}_\ell : \lambda \in \mathbb{R}\}.$$

Let $\alpha \in \{-1, +1\}$ denote the sign of the first nonzero entry of $\mathbf{e}_i^\top \mathbf{A}_\sigma^{-1}$. Then we can write

$$\mathbf{u}_\ell^\top = \frac{\alpha \mathbf{e}_i^\top \mathbf{A}_\sigma^{-1}}{\|\mathbf{e}_i^\top \mathbf{A}_\sigma^{-1}\|_2},$$

since for all $k \in \sigma - i$ we have

$$\alpha \mathbf{e}_i^\top \mathbf{A}_\sigma^{-1} \mathbf{A}_k = \alpha \mathbf{e}_i^\top \mathbf{A}_\sigma^{-1} \mathbf{A}_\sigma \mathbf{e}_k = 0,$$

and $\alpha \mathbf{e}_i^\top \mathbf{A}_\sigma^{-1}$ has first nonzero component positive by definition of α .

Now let k be any element of $[n]$ outside of $\sigma - i$. Since \mathbf{u}_ℓ depends only on $\mathbf{A}_{\sigma-i}$, and the entries of \mathbf{A} are mutually independent, we have that \mathbf{u}_ℓ and \mathbf{A}_k are independent random vectors. Now, for any fixed unit vector $\mathbf{v} \in \mathbb{S}^{n-1}$, as \mathbf{A}_k has $N(0, 1)$ iid entries, then the dot product $\mathbf{v}^\top \mathbf{A}_k$ also has distribution $N(0, 1)$. Thus, for any fixed $t \in \mathbb{R}$, the random variable

$$\gamma(\mathbf{u}_\ell^\top \mathbf{A}_k \leq t \mid \ell)$$

(i.e. the conditional probability in terms of the σ -algebra generated by ℓ) is in fact constant. Evaluating at the line $\ell = \mathbb{R}\mathbf{e}_1$, for example, this constant is given by

$$\gamma(\mathbf{A}_{1, k} \leq t).$$

This shows that the random quantity $\mathbf{u}_\ell^\top \mathbf{A}_k$ has distribution $N(0, 1)$. We have

$$(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i = \frac{\mathbf{e}_i^\top \mathbf{A}_\sigma^{-1} \mathbf{A}_j}{\mathbf{e}_i^\top \mathbf{A}_\sigma^{-1} \mathbf{A}_i} = \frac{\mathbf{u}_\ell^\top \mathbf{A}_j}{\mathbf{u}_\ell^\top \mathbf{A}_i}.$$

The independence of $\mathbf{u}_\ell^\top \mathbf{A}_i$ and $\mathbf{u}_\ell^\top \mathbf{A}_j$ imply that $(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i$ has the Cauchy distribution, that is, the ratio of two iid $N(0, 1)$ random variables. In particular, the cdf of $(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i$ is given by

$$\gamma((\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i \leq t) = \frac{1}{\pi} \arctan(t) + \frac{1}{2}.$$

See [6, p. 50] for more on the Cauchy distribution. Using the series expansion

$$\arctan(t) = \frac{\pi}{2} - \frac{1}{t} + \frac{1}{3t^3} - \frac{1}{5t^5} + \dots,$$

we get

$$\gamma((\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i \leq t) = 1 - \left(\frac{1}{\pi t} - \frac{1}{3\pi t^3} + \frac{1}{5\pi t^5} - \dots \right).$$

Hence, using Proposition 4 and the fact $s > 1$, we conclude

$$\begin{aligned} \nu(\xi_{\sigma,i,j}(s)) &= \gamma(|(\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i| > s) \\ &= 2 \cdot \gamma((\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i > s) \\ &= 2(1 - \gamma((\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i \leq s)) \\ &= 2 \left(\frac{1}{\pi s} - \frac{1}{3\pi s^3} + \frac{1}{5\pi s^5} - \dots \right) \\ &= \frac{2}{\pi s} + \mathcal{O}(s^{-3}). \end{aligned}$$

5 Proof of main result

In this final section we prove the main result of this paper, Theorem 1.

Definition 3. Define the constant

$$\tilde{\omega}_d := \frac{\omega_d^{1/d}}{d},$$

where ω_d denotes the volume of the d -dimensional Euclidean ball. This constant $\tilde{\omega}_d$ is of the order $d^{-3/2}$.

Definition 4. Assume $\Lambda_{\mathbb{R}} = \ker(\mathbf{A})$. Given positive real numbers s and u , we say Λ is (σ, s, u) -controlled if σ is a basis of \mathbf{A} and:

1. The largest entry of $\mathbf{A}_\sigma^{-1} \mathbf{A}_\sigma$ is at most s , and
2. The successive minima ratios of Λ are not too large: we have

$$\frac{\lambda_{i+1}(\Lambda)}{\lambda_i(\Lambda)} < (\tilde{\omega}_d u)^{2/(d-1)}$$

for all $i = 1, 2, \dots, d-1$.

Lemma 1 ([2, Proof of Lemma 5.2]). *Suppose that*

$$\frac{\lambda_{i+1}(\Lambda)}{\lambda_i(\Lambda)} < (\tilde{\omega}_d u)^{2/(d-1)}$$

for all $i = 1, 2, \dots, d-1$. Then

$$\mu < u(\Delta(\Lambda))^{1/d}.$$

Lemma 2. *If σ is a basis of \mathbf{A} and Λ is (σ, s, u) -controlled, then for all $\mathbf{x}^* \in \mathcal{S}_\sigma$ we have*

$$\text{dist}(\Lambda, \sigma, \mathbf{x}^*) \leq 2n^{3/2} s u (\Delta(\Lambda))^{1/d}.$$

Proof. Let $\mathbf{b} = \mathbf{A}\mathbf{x}^*$, let $B = B_2^n \cap \Lambda_{\mathbb{R}}$, and let μ denote the covering radius of B with respect to Λ . Define the vector $\mathbf{v} \in \mathbb{R}^n$ so that:

$$\begin{aligned} \mathbf{v}_j &= \mu \mathbf{w}_j \text{ for all } j \in \bar{\sigma} \\ \mathbf{A}\mathbf{v} &= \mathbf{b}. \end{aligned}$$

We show that the scaled, translated ball $\mu B + \mathbf{v}$ is contained in $\mathcal{P}(\mathbf{A}, \mathbf{b})$. Since $B \subseteq \Lambda_{\mathbb{R}}$, we have that each $\mathbf{x} \in \mu B + \mathbf{v}$ satisfies $\mathbf{A}\mathbf{x} = \mathbf{b}$. For each $j \in [n]$, let $\mathbf{x}^{(j)}$ be the unique point in $\mu B + \mathbf{v}$ such that $\mathbf{x}_j^{(j)}$ is minimized. If $j \in \bar{\sigma}$, then

$$\mathbf{x}_j^{(j)} = \mu(-\mathbf{w}_j) + \mathbf{v}_j = \mu(-\mathbf{w}_j) + \mu \mathbf{w}_j = 0.$$

If $j \in \sigma$, then since $\mathbf{x}^* \in \mathcal{S}_\sigma$ we have

$$\begin{aligned} \mathbf{x}_j^{(j)} &= \mu(-\mathbf{w}_j) + \mathbf{v}_j \\ &= \mu(-\mathbf{w}_j) + (\mathbf{A}_\sigma^{-1} \mathbf{b} - \mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}} \mathbf{w}_{\bar{\sigma}})_j \\ &\geq \mu(-\mathbf{w}_j) + \mu \mathbf{w}_j \\ &= 0. \end{aligned}$$

This concludes the proof that $\mu B + \mathbf{v} \subseteq \mathcal{P}(\mathbf{A}, \mathbf{b})$.

Now, since μ is the covering radius of B with respect to Λ , there exists $\mathbf{z}^* \in \mathbb{Z}^n \cap (\mu B + \mathbf{v})$ such that

$$\|\mathbf{x}^* - \mathbf{z}^*\|_2 \leq \|\mathbf{x}^* - \mathbf{v}\|_2 + \|\mathbf{v} - \mathbf{z}^*\|_2 \leq \mu \|\tilde{\mathbf{w}}\|_2 + \mu. \quad (13)$$

where we define $\tilde{\mathbf{w}} := (\mathbf{v} - \mathbf{x}^*)/\mu$. That is, $\tilde{\mathbf{w}}$ satisfies

$$\begin{aligned} \mathbf{A}\tilde{\mathbf{w}} &= \mathbf{0} \\ \tilde{\mathbf{w}} &= \mathbf{w}_j \text{ for all } j \in \bar{\sigma}. \end{aligned}$$

Observe that

$$\tilde{\mathbf{w}}_\sigma = -\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}} \tilde{\mathbf{w}}_{\bar{\sigma}}.$$

Using the fact $\mathbf{w} \in [0, 1]^n$, we therefore have

$$\begin{aligned}\|\tilde{\mathbf{w}}\|_2^2 &= \|\tilde{\mathbf{w}}_\sigma\|_2^2 + \|\tilde{\mathbf{w}}_{\bar{\sigma}}\|_2^2 \\ &= \|\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}} \tilde{\mathbf{w}}_{\bar{\sigma}}\|_2^2 + \|\tilde{\mathbf{w}}_{\bar{\sigma}}\|_2^2 \\ &\leq m \|\mathbf{A}_\sigma^{-1} \mathbf{A}_{\bar{\sigma}}\|_\infty^2 \|\tilde{\mathbf{w}}_{\bar{\sigma}}\|_1^2 + \|\tilde{\mathbf{w}}_{\bar{\sigma}}\|_2^2 \\ &\leq (ms^2 + 1) d^2.\end{aligned}$$

Thus we conclude

$$\begin{aligned}\|\mathbf{x}^* - \mathbf{z}^*\|_2 &\leq \mu (\|\tilde{\mathbf{w}}\|_2 + 1) \\ &\leq u \Delta^{1/d} \left(\sqrt{(ms^2 + 1) d^2} + 1 \right) \\ &\leq 2n^{3/2} su \Delta^{1/d}.\end{aligned}$$

Proof (Proof of Theorem 1). Let Λ be a uniformly chosen lattice from $G(d, n, T)$. Let $t > 1$, and let $s := t^{2/3}/(2n^{3/2})$ and $u := t^{1/3}$, so that $t = 2n^{3/2}su$ as in Lemma 2. We have

$$\begin{aligned}\mathbf{P} \left(\text{dist}(\Lambda) > t (\Delta(\Lambda))^{1/d} \right) \\ &\leq \sum_{\sigma} \mathbf{P} \left(\sigma \text{ basis of } \mathbf{A}, \text{dist}(\Lambda, \sigma, \mathbf{x}^*) > t (\Delta(\Lambda))^{1/d} \text{ for some } \mathbf{x}^* \in \mathcal{S}_\sigma \right) \\ &\leq \sum_{\sigma} \mathbf{P}(\sigma \text{ basis of } \mathbf{A}, \Lambda \text{ is not } (\sigma, s, u)\text{-controlled})\end{aligned}$$

where the sums are over all subsets $\sigma \subseteq [n]$ of size m . It therefore suffices to show, for each such σ ,

$$\mathbf{P}(\sigma \text{ basis of } \mathbf{A}, \Lambda \text{ is not } (\sigma, s, u)\text{-controlled}) \ll t^{-2/3}.$$

By definition, this probability is at most

$$\mathbf{P} \left(\max_{i \in [d]} \left\{ \frac{\lambda_{i+1}(\Lambda)}{\lambda_i(\Lambda)} \right\} \geq (\tilde{\omega}_d u)^{2/(d-1)} \right) + \sum_{\substack{i \in \sigma \\ j \notin \sigma}} \mathbf{P}(\sigma \text{ basis of } \mathbf{A}, (\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i \geq s). \quad (14)$$

By Theorem 2, we have

$$\mathbf{P}(\sigma \text{ basis of } \mathbf{A}, (\mathbf{A}_\sigma^{-1} \mathbf{A}_j)_i \geq s) = \frac{|G(\mathbf{1}, \xi_{\sigma, i, j}(s), T)|}{|G(\mathbf{1}, \text{Gr}(d, n), T)|} \asymp \nu(\xi_{\sigma, i, j}(s)).$$

Hence, applying Corollary 1 and Proposition 5 for T sufficiently large, we may estimate up to constants the quantity (14) by

$$u^{-2} + s^{-1} \ll t^{-2/3}.$$

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